

EE101: Digital circuits (Part 4)



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Sequential circuits

- * The digital circuits we have seen so far (gates, multiplexer, demultiplexer, encoders, decoders) are *combinatorial* in nature, i.e., the output(s) depends only on the *present* values of the inputs and *not* on their past values.

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- * In *sequential* circuits, the “state” of the circuit is crucial in determining the output values. For a given input combination, a sequential circuit may produce different output values, depending on its previous state.

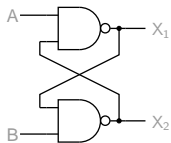
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- * In *sequential* circuits, the “state” of the circuit is crucial in determining the output values. For a given input combination, a sequential circuit may produce different output values, depending on its previous state.
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- * In other words, a sequential circuit has a *memory* (of its past state) whereas a combinatorial circuit has no memory.
- * Sequential circuits (together with combinatorial circuits) make it possible to build several useful applications, such as counters, registers, arithmetic/logic unit (ALU), all the way to microprocessors.

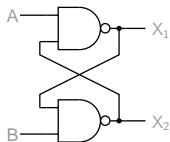
NAND latch (RS latch)



A	B	X_1	X_2

* A, B : inputs, X_1, X_2 : outputs

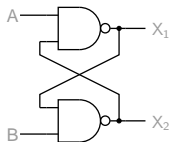
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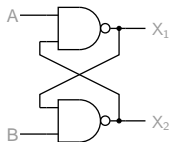
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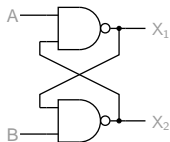
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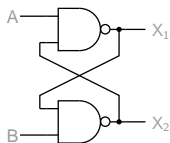
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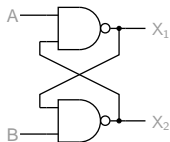
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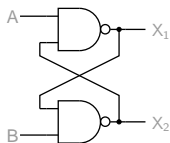
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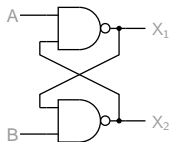
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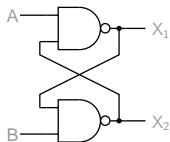
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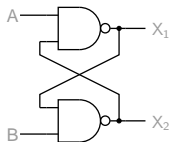
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If $X_1 = 1, X_2 = 0$ previously, the circuit continues to “hold” that state.

Similarly, if $X_1 = 0, X_2 = 1$ previously, the circuit continues to “hold” that state.

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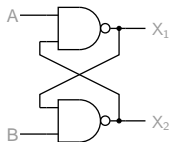
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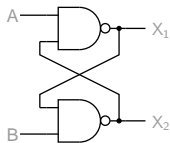
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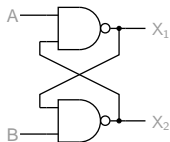
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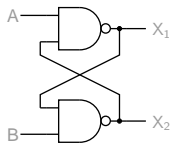
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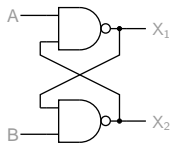
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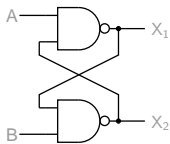
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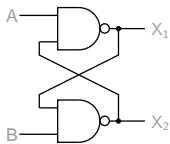
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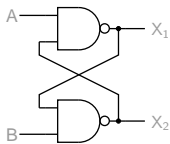
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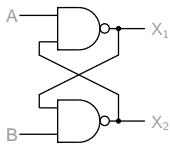
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- * The A input is therefore called the RESET (R) input, and B is called the SET (S) input of the latch.

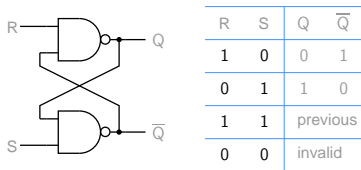
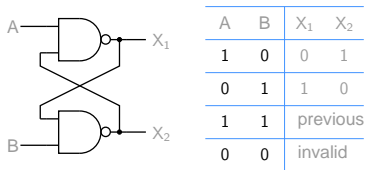
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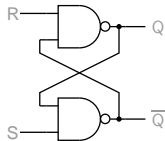
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- * X_1 is denoted by Q , and X_2 (which is $\overline{X_1}$ in all cases except for $A = B = 0$) is denoted by \overline{Q} .

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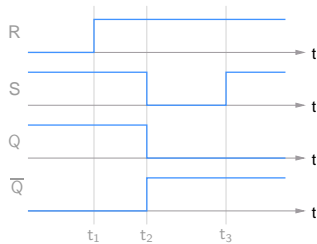


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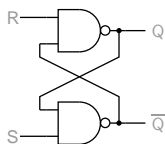
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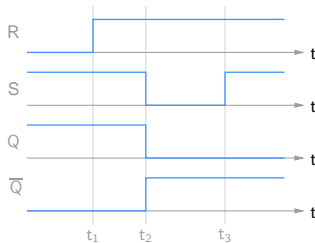
R	S	Q	\overline{Q}
1	0	0	1
0	1	1	0
1	1	previous	
0	0	invalid	



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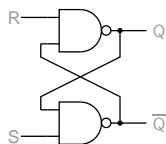


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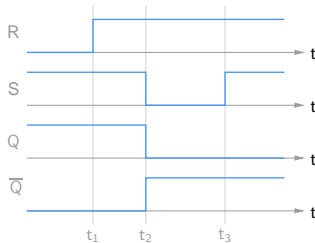


* Up to $t = t_1$, $R = 0$, $S = 1 \rightarrow Q = 1$.

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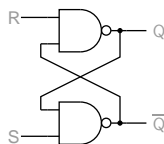


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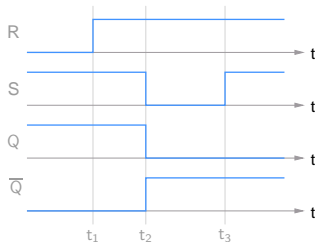


- * Up to $t = t_1$, $R = 0$, $S = 1 \rightarrow Q = 1$.
- * At $t = t_1$, R goes high $\rightarrow R = S = 1$, and the latch holds its previous state \rightarrow no change at the output.

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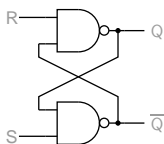


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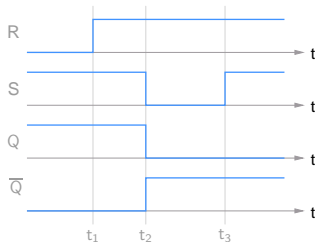


- * Up to $t = t_1$, $R = 0$, $S = 1 \rightarrow Q = 1$.
- * At $t = t_1$, R goes high $\rightarrow R = S = 1$, and the latch holds its previous state \rightarrow no change at the output.
- * At $t = t_2$, S goes low $\rightarrow R = 1$, $S = 0 \rightarrow Q = 0$.

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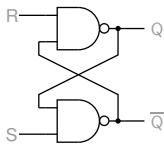


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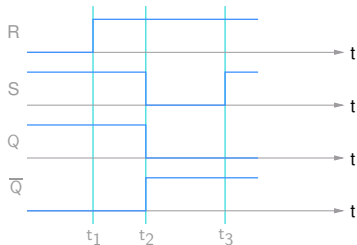


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- * At $t = t_2$, S goes low $\rightarrow R = 1$, $S = 0 \rightarrow Q = 0$.
- * At $t = t_3$, S goes high $\rightarrow R = S = 1$, and the latch holds its previous state \rightarrow no change at the output.

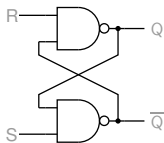
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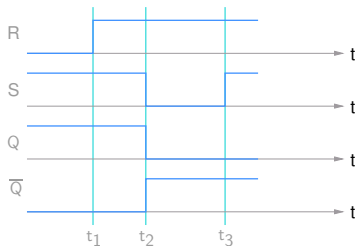
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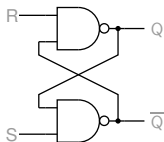


R	S	Q	\bar{Q}
1	0	0	1
0	1	1	0
1	1	previous	
0	0	1	1

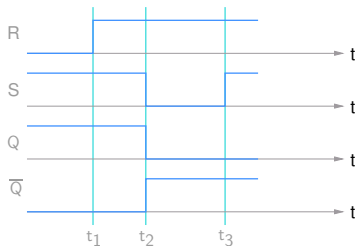


* Why not allow $R = S = 0$?

NAND latch (RS latch)



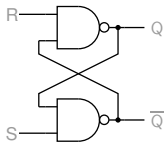
R	S	Q	\overline{Q}
1	0	0	1
0	1	1	0
1	1	previous	
0	0	1	1



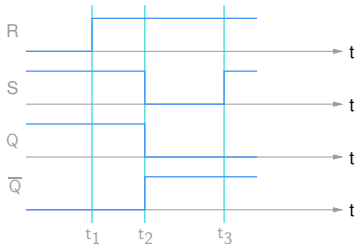
* Why not allow $R = S = 0$?

- It makes $Q = \overline{Q} = 1$, i.e., Q and \overline{Q} are not inverse of each other any more.

NAND latch (RS latch)



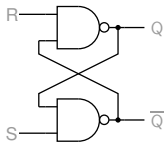
R	S	Q	\overline{Q}
1	0	0	1
0	1	1	0
1	1	previous	
0	0	1	1



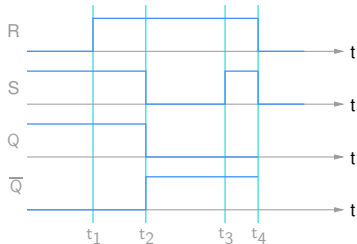
* Why not allow $R = S = 0$?

- It makes $Q = \overline{Q} = 1$, i.e., Q and \overline{Q} are not inverse of each other any more.
- More importantly, when R and S both become 1 simultaneously (starting from $R = S = 0$), the final outputs Q and \overline{Q} cannot be uniquely determined. We could have $Q = 0$, $\overline{Q} = 1$ or $Q = 1$, $\overline{Q} = 0$, depending on the delays associated with the two NAND gates.

NAND latch (RS latch)



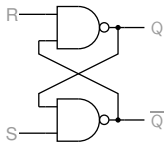
R	S	Q	\overline{Q}
1	0	0	1
0	1	1	0
1	1	previous	
0	0	1	1



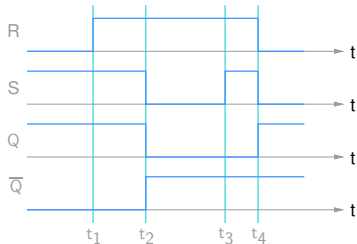
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NAND latch (RS latch)



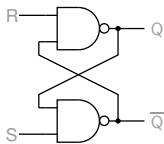
R	S	Q	\overline{Q}
1	0	0	1
0	1	1	0
1	1	previous	
0	0	1	1



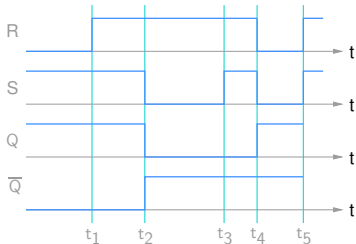
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NAND latch (RS latch)



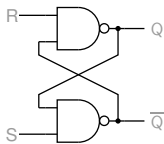
R	S	Q	\overline{Q}
1	0	0	1
0	1	1	0
1	1	previous	
0	0	1	1



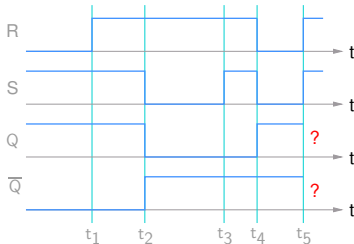
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NAND latch (RS latch)



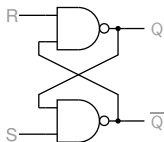
R	S	Q	\overline{Q}
1	0	0	1
0	1	1	0
1	1	previous	
0	0	1	1



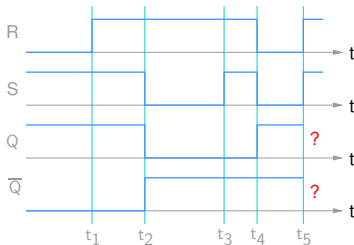
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NAND latch (RS latch)



R	S	Q	\overline{Q}
1	0	0	1
0	1	1	0
1	1	previous	
0	0	1	1

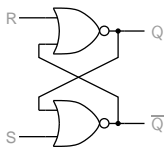


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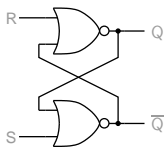
* We surely don't want any question marks in digital electronics!

NOR latch (RS latch)



R	S	Q	\bar{Q}
1	0	0	1
0	1	1	0
0	0	previous	
1	1	invalid	

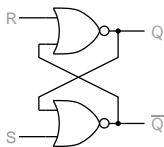
NOR latch (RS latch)



R	S	Q	\bar{Q}
1	0	0	1
0	1	1	0
0	0	previous	
1	1	invalid	

- * The NOR latch is similar to the NAND latch:
When $R = 1$, $S = 0$, the latch gets *reset* to $Q = 0$.
When $R = 0$, $S = 1$, the latch gets *set* to $Q = 1$.

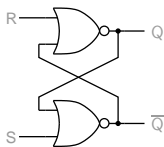
NOR latch (RS latch)



R	S	Q	\overline{Q}
1	0	0	1
0	1	1	0
0	0	previous	
1	1	invalid	

- * The NOR latch is similar to the NAND latch:
When $R = 1, S = 0$, the latch gets *reset* to $Q = 0$.
When $R = 0, S = 1$, the latch gets *set* to $Q = 1$.
- * For $R = S = 0$, the latch retains its previous state (i.e., the previous values of Q and \overline{Q}).

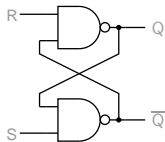
NOR latch (RS latch)



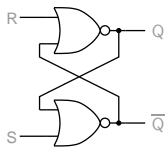
R	S	Q	\overline{Q}
1	0	0	1
0	1	1	0
0	0	previous	
1	1	invalid	

- * The NOR latch is similar to the NAND latch:
When $R = 1, S = 0$, the latch gets *reset* to $Q = 0$.
When $R = 0, S = 1$, the latch gets *set* to $Q = 1$.
- * For $R = S = 0$, the latch retains its previous state (i.e., the previous values of Q and \overline{Q}).
- * $R = S = 1$ is not allowed for reasons similar to those discussed in the context of the NAND latch.

Comparison of NAND and NOR latches

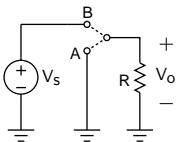


R	S	Q	\overline{Q}
1	0	0	1
0	1	1	0
1	1	previous	
0	0	invalid	

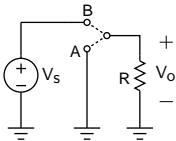


R	S	Q	\overline{Q}
1	0	0	1
0	1	1	0
0	0	previous	
1	1	invalid	

Chatter (bouncing) due to a mechanical switch

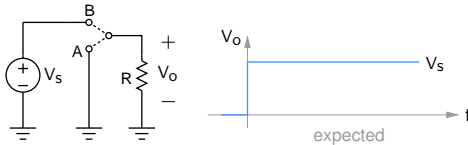


Chatter (bouncing) due to a mechanical switch



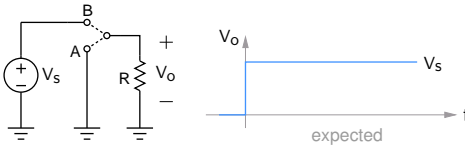
- * When the switch is thrown from A to B, V_o is expected to go from 0 V to V_s (say, 5 V).

Chatter (bouncing) due to a mechanical switch



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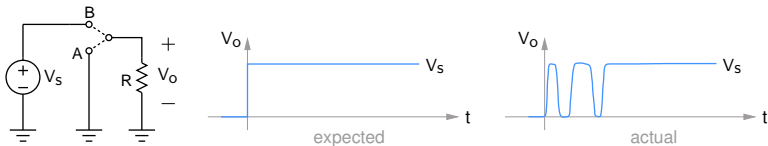
- * When the switch is thrown from A to B, V_o is expected to go from 0 V to V_s (say, 5 V).
- * However, mechanical switches suffer from “chatter” or “bouncing,” i.e., the transition from A to B is not a single, clean one. As a result, V_o oscillates between 0 V and 5 V before settling to its final value (5 V).

Chatter (bouncing) due to a mechanical switch



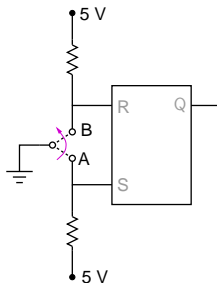
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Chatter (bouncing) due to a mechanical switch

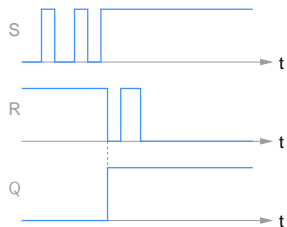


- * When the switch is thrown from A to B, V_o is expected to go from 0 V to V_s (say, 5 V).
- * However, mechanical switches suffer from “chatter” or “bouncing,” i.e., the transition from A to B is not a single, clean one. As a result, V_o oscillates between 0 V and 5 V before settling to its final value (5 V).
- * In some applications, this chatter can cause malfunction → need a way to remove the chatter.

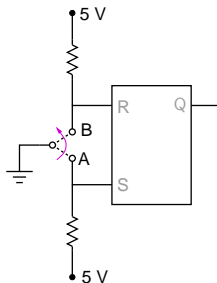
Chatter (bouncing) due to a mechanical switch



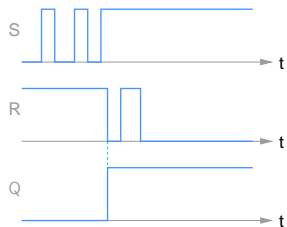
R	S	Q	\bar{Q}
1	0	0	1
0	1	1	0
1	1	previous	
0	0	invalid	



Chatter (bouncing) due to a mechanical switch

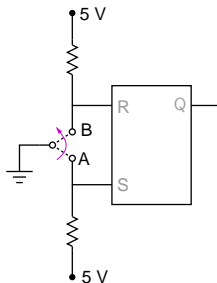


R	S	Q	\bar{Q}
1	0	0	1
0	1	1	0
1	1	previous	
0	0	invalid	

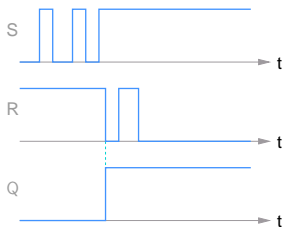


- * Because of the chatter, the S and R inputs may have multiple transitions when the switch is thrown from A to B.

Chatter (bouncing) due to a mechanical switch



R	S	Q	\bar{Q}
1	0	0	1
0	1	1	0
1	1	previous	
0	0	invalid	



- * Because of the chatter, the S and R inputs may have multiple transitions when the switch is thrown from A to B.
- * However, for $S = R = 1$, the previous value of Q is retained, causing a *single* transition in Q , as desired.

The “clock”

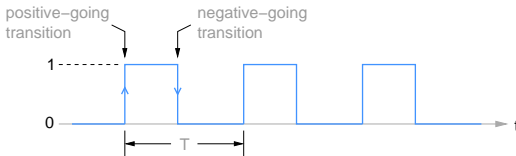
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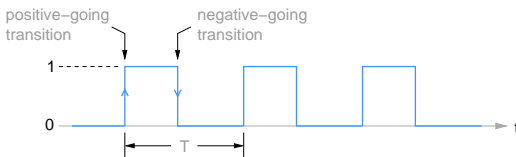
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- * A clock is a periodic signal, with a positive-going transition and a negative-going transition.



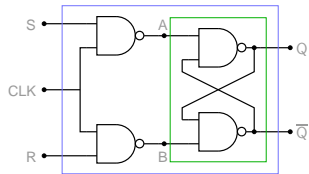
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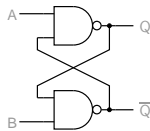
- * The clock frequency determines the overall speed of the circuit. For example, a processor that operates with a 1 GHz clock is 10 times faster than one that operates with a 100 MHz clock.

Clocked RS latch



Clocked RS latch

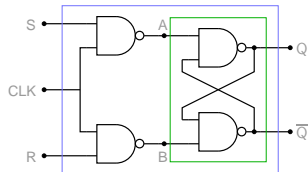
CLK	R	S	Q	\bar{Q}
0	X	X	previous	
1	1	0	0	1
1	0	1	1	0
1	0	0	previous	
1	1	1	invalid	



NAND RS latch

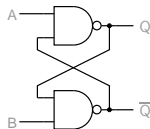
A	B	Q	\bar{Q}
1	0	0	1
0	1	1	0
1	1	previous	
0	0	invalid	

Clocked RS latch



Clocked RS latch

CLK	R	S	Q	\bar{Q}
0	X	X	previous	
1	1	0	0	1
1	0	1	1	0
1	0	0	previous	
1	1	1	invalid	

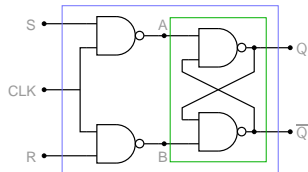


NAND RS latch

A	B	Q	\bar{Q}
1	0	0	1
0	1	1	0
1	1	previous	
0	0	invalid	

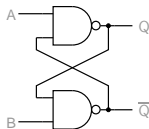
- * When clock is inactive (0), $A = B = 1$, and the latch holds the previous state.

Clocked RS latch



Clocked RS latch

CLK	R	S	Q	\bar{Q}
0	X	X	previous	
1	1	0	0	1
1	0	1	1	0
1	0	0	previous	
1	1	1	invalid	

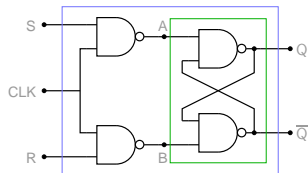


NAND RS latch

A	B	Q	\bar{Q}
1	0	0	1
0	1	1	0
1	1	previous	
0	0	invalid	

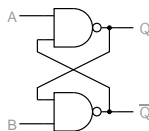
- * When clock is inactive (0), $A = B = 1$, and the latch holds the previous state.
- * When clock is active (1), $A = \bar{S}$, $B = \bar{R}$. Using the truth table for the NAND RS latch (right), we can construct the truth table for the clocked RS latch.

Clocked RS latch



Clocked RS latch

CLK	R	S	Q	\bar{Q}
0	X	X	previous	
1	1	0	0	1
1	0	1	1	0
1	0	0	previous	
1	1	1	invalid	

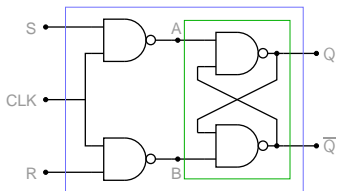


NAND RS latch

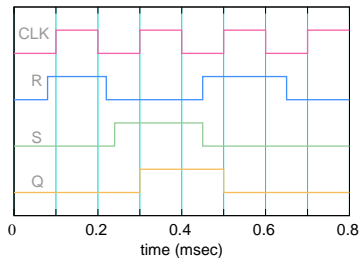
A	B	Q	\bar{Q}
1	0	0	1
0	1	1	0
1	1	previous	
0	0	invalid	

- * When clock is inactive (0), $A = B = 1$, and the latch holds the previous state.
- * When clock is active (1), $A = \bar{S}$, $B = \bar{R}$. Using the truth table for the NAND RS latch (right), we can construct the truth table for the clocked RS latch.
- * Note that the above table is sensitive to the *level* of the clock (i.e., whether CLK is 0 or 1).

Clocked RS latch



CLK	R	S	Q	\bar{Q}
0	X	X	previous	
1	1	0	0	1
1	0	1	1	0
1	0	0	previous	
1	1	1	invalid	



(SEQUEL file: ee101_rs_1.sqproj)

Edge-triggered flip-flops

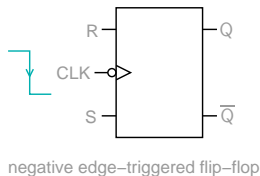
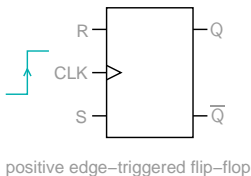
- * The clocked RS latch seen previously is *level-sensitive*, i.e., if the clock is active ($\text{CLK} = 1$), the flip-flop output is allowed to change, depending on the R and S inputs.

Edge-triggered flip-flops

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- * In an *edge-sensitive* flip-flop, the output can change only at the active clock *edge* (i.e., CLK transition from 0 to 1 or from 1 to 0).

Edge-triggered flip-flops

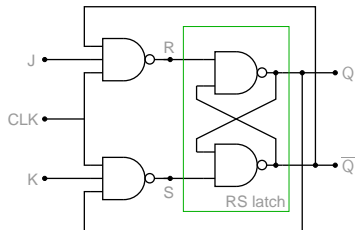
- * The clocked RS latch seen previously is *level-sensitive*, i.e., if the clock is active ($\text{CLK} = 1$), the flip-flop output is allowed to change, depending on the R and S inputs.
- * In an *edge-sensitive* flip-flop, the output can change only at the active clock *edge* (i.e., CLK transition from 0 to 1 or from 1 to 0).
- * Edge-sensitive flip-flops are denoted by the following symbols:



JK flip-flop

R	S	Q	\bar{Q}
1	0	0	1
0	1	1	0
1	1	previous	
0	0	invalid	

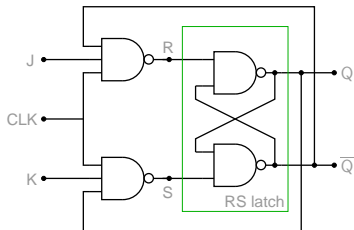
Truth table for RS latch



JK flip-flop

R	S	Q	\bar{Q}
1	0	0	1
0	1	1	0
1	1	previous	
0	0	invalid	

Truth table for RS latch

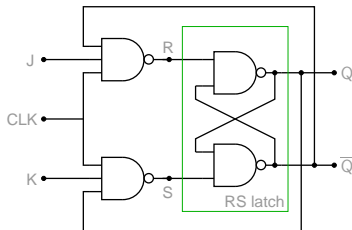


- * When $CLK = 0$, we have $R = S = 1$, and the RS latch holds the previous Q . In other words, nothing happens as long as $CLK = 0$.

JK flip-flop

R	S	Q	\bar{Q}
1	0	0	1
0	1	1	0
1	1	previous	
0	0	invalid	

Truth table for RS latch



CLK	J	K	$Q(Q_{n+1})$
0	X	X	previous (Q_n)

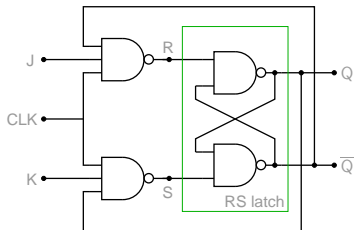
Truth table for JK flip-flop

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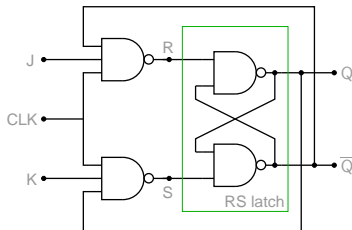
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- * When $CLK = 1$:

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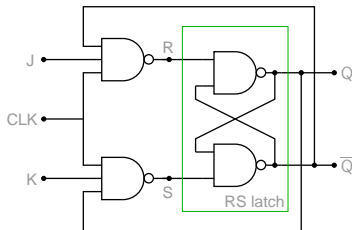
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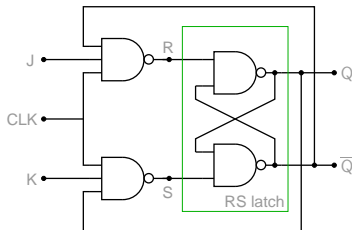
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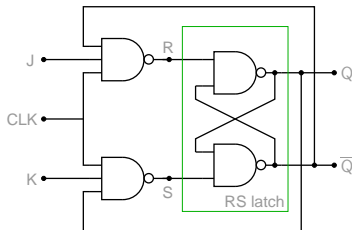
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 - $J = 0, K = 1 \rightarrow R = 1, S = \overline{Q_n}$.

JK flip-flop

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Truth table for RS latch



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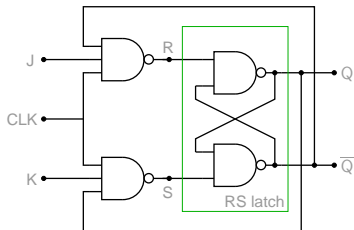
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Case (i): $Q_n = 0 \rightarrow S = 1$ (i.e., $R = S = 1$) $\rightarrow Q_{n+1} = Q_n = 0$.

JK flip-flop

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Truth table for RS latch



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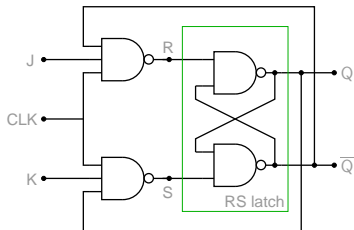
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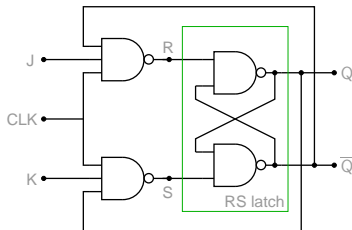
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 - Case (ii): $Q_n = 1 \rightarrow S = 0$ (i.e., $R = 1, S = 0$) $\rightarrow Q_{n+1} = 0$.
- In either case, $Q_{n+1} = 0 \rightarrow$ For $J = 0, K = 1, Q_{n+1} = 0$.

JK flip-flop

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Truth table for RS latch



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1	0	0	previous (Q_n)
1	0	1	0

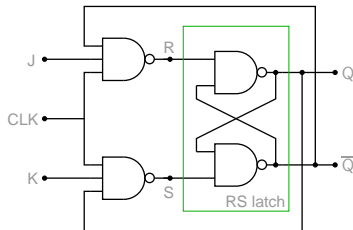
Truth table for JK flip-flop

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 - $J = 0, K = 1 \rightarrow R = 1, S = \bar{Q}_n$.
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JK flip-flop

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Truth table for RS latch



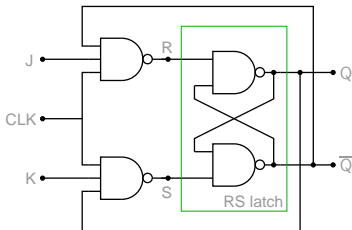
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Truth table for JK flip-flop

JK flip-flop

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Truth table for JK flip-flop

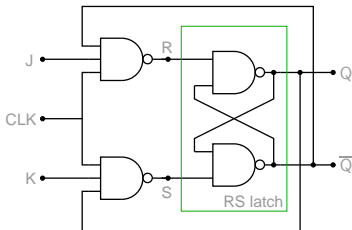
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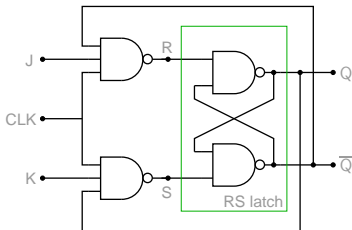
- Consider $J = 1, K = 0 \rightarrow S = 1, R = \overline{\overline{Q_n}} = Q_n$.

Case (i): $Q_n = 0 \rightarrow R = 0$ (i.e., $R = 0, S = 1$) $\rightarrow Q_{n+1} = 1$.

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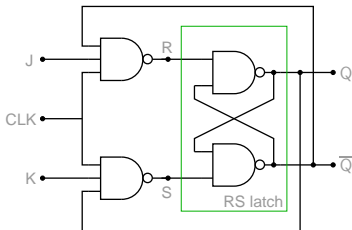
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JK flip-flop

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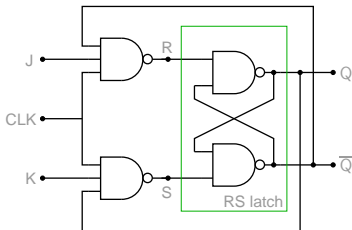
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Truth table for JK flip-flop

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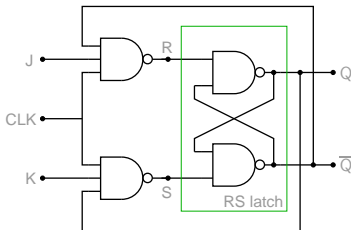
Case (ii): $Q_n = 1 \rightarrow R = 1$ (i.e., $R = 1, S = 1$) $\rightarrow Q_{n+1} = Q_n = 1$.

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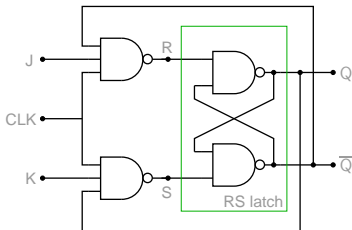
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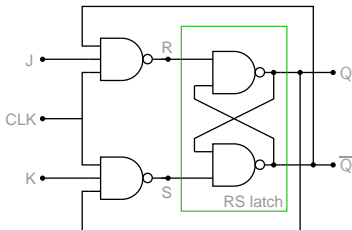
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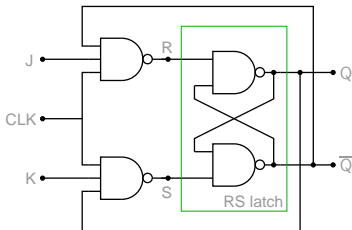
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Truth table for RS latch



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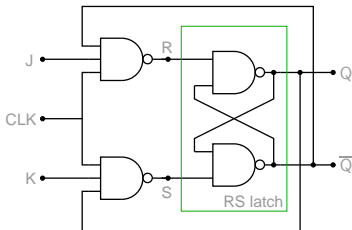
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JK flip-flop

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0	1	1	0
1	1	previous	
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Truth table for RS latch



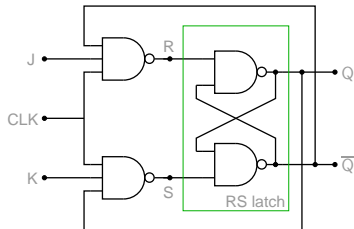
CLK	J	K	Q (Q_{n+1})
0	X	X	previous (Q_n)
1	0	0	previous (Q_n)
1	0	1	0
1	1	0	1
1	1	1	toggles (\bar{Q}_n)

Truth table for JK flip-flop

* When CLK = 1:

- Consider $J = 1, K = 0 \rightarrow S = 1, R = \bar{\bar{Q}}_n = Q_n$.
Case (i): $Q_n = 0 \rightarrow R = 0$ (i.e., $R = 0, S = 1$) $\rightarrow Q_{n+1} = 1$.
Case (ii): $Q_n = 1 \rightarrow R = 1$ (i.e., $R = 1, S = 1$) $\rightarrow Q_{n+1} = Q_n = 1$.
 \rightarrow For $J = 1, K = 0, Q_{n+1} = 1$.
- Consider $J = 1, K = 1 \rightarrow R = Q_n, S = \bar{Q}_n$.
Case (i): $Q_n = 0 \rightarrow R = 0, S = 1 \rightarrow Q_{n+1} = 1$.
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JK flip-flop

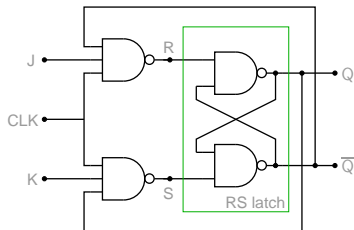


CLK	J	K	Q (Q_{n+1})
0	X	X	previous (Q_n)
1	0	0	previous (Q_n)
1	0	1	0
1	1	0	1
1	1	1	toggles ($\overline{Q_n}$)

Truth table for JK flip-flop

Consider $J = K = 1$ and $\text{CLK} = 1$.

JK flip-flop



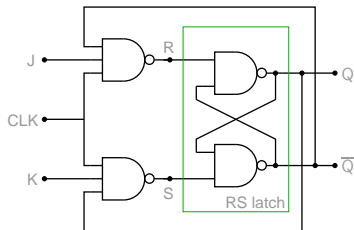
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1	1	0	1
1	1	1	toggles ($\overline{Q_n}$)

Truth table for JK flip-flop

Consider $J = K = 1$ and $\text{CLK} = 1$.

As long as $\text{CLK} = 1$, Q will keep toggling! (The frequency will depend on the delay values of the various gates).

JK flip-flop



CLK	J	K	Q (Q_{n+1})
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1	0	0	previous (Q_n)
1	0	1	0
1	1	0	1
1	1	1	toggles (\bar{Q}_n)

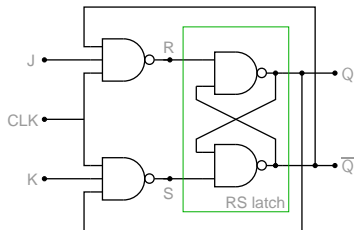
Truth table for JK flip-flop

Consider $J = K = 1$ and $\text{CLK} = 1$.

As long as $\text{CLK} = 1$, Q will keep toggling! (The frequency will depend on the delay values of the various gates).

When CLK changes from 1 to 0, the toggling will stop. However, the final value of Q is not known; it could be 0 or 1.

JK flip-flop



CLK	J	K	Q (Q_{n+1})
0	X	X	previous (Q_n)
1	0	0	previous (Q_n)
1	0	1	0
1	1	0	1
1	1	1	toggles ($\overline{Q_n}$)

Truth table for JK flip-flop

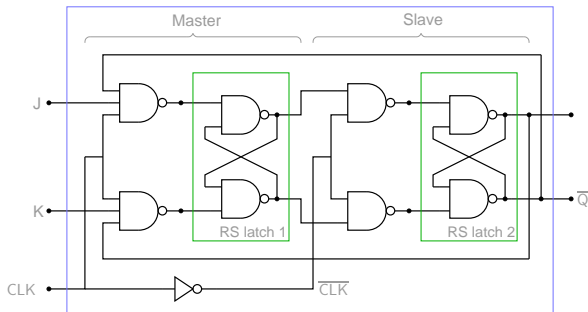
Consider $J = K = 1$ and $\text{CLK} = 1$.

As long as $\text{CLK} = 1$, Q will keep toggling! (The frequency will depend on the delay values of the various gates).

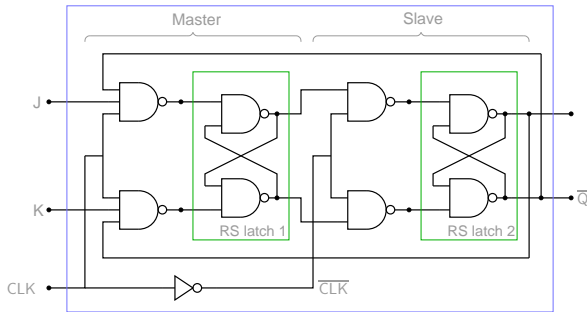
When CLK changes from 1 to 0, the toggling will stop. However, the final value of Q is not known; it could be 0 or 1.

→ Use the “Master-slave” configuration.

JK flip-flop (Master-Slave)

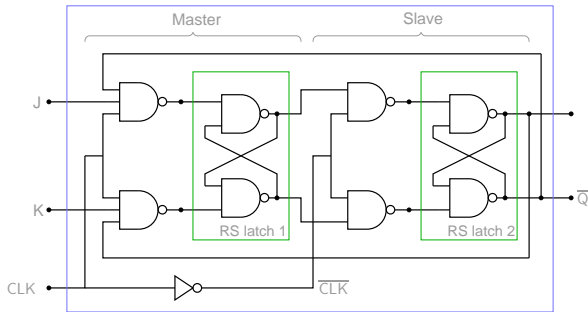


JK flip-flop (Master-Slave)



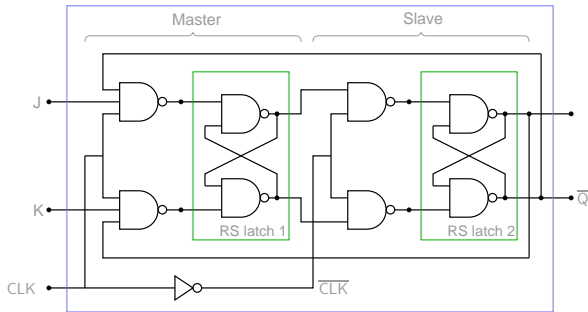
- * When CLK goes high, only the first latch is affected; the second latch retains its previous value (because $\overline{\text{CLK}} = 0 \rightarrow R_2 = S_2 = 1$).

JK flip-flop (Master-Slave)



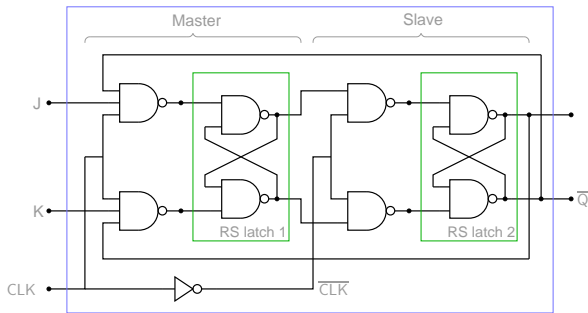
- * When CLK goes high, only the first latch is affected; the second latch retains its previous value (because $\overline{\text{CLK}} = 0 \rightarrow R_2 = S_2 = 1$).
- * When CLK goes low, the output of the first latch (Q_1) is retained (since $R_1 = S_1 = 1$), and Q_1 can now affect Q .

JK flip-flop (Master-Slave)



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- * When CLK goes low, the output of the first latch (Q_1) is retained (since $R_1 = S_1 = 1$), and Q_1 can now affect Q .
- * In other words, the effect of any changes in J and K appears at the output Q only when CLK makes a transition from 1 to 0.
This is therefore a negative edge-triggered flip-flop.

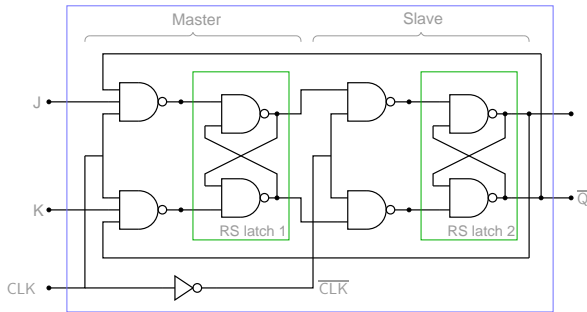
JK flip-flop (Master-Slave)



CLK	J	K	Q_{n+1}
↓	0	0	Q_n
↓	0	1	0
↓	1	0	1
↓	1	1	$\overline{Q_n}$

- * When CLK goes high, only the first latch is affected; the second latch retains its previous value (because $\overline{\text{CLK}} = 0 \rightarrow R_2 = S_2 = 1$).
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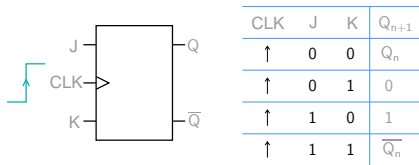
JK flip-flop (Master-Slave)



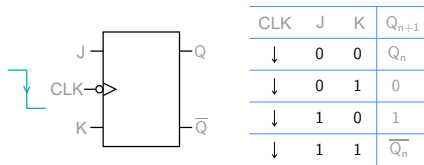
CLK	J	K	Q_{n+1}
↓	0	0	Q_n
↓	0	1	0
↓	1	0	1
↓	1	1	$\overline{Q_n}$

- * When CLK goes high, only the first latch is affected; the second latch retains its previous value (because $\overline{\text{CLK}} = 0 \rightarrow R_2 = S_2 = 1$).
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- * In other words, the effect of any changes in J and K appears at the output Q only when CLK makes a transition from 1 to 0. This is therefore a negative edge-triggered flip-flop.
- * Note that, unlike the RS NAND latch which does not allow one of the combinations of R and S (viz., $R = S = 0$), the JK flip-flop allows all four combinations.

JK flip-flop

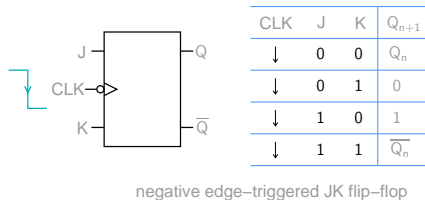
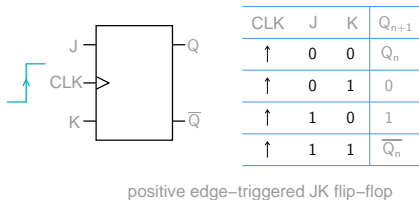


positive edge-triggered JK flip-flop



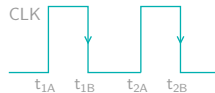
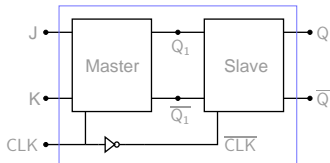
negative edge-triggered JK flip-flop

JK flip-flop



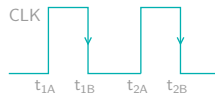
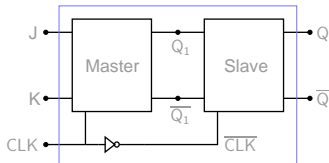
- * Both negative (e.g., 74101) and positive (e.g., 7470) edge-triggered JK flip-flops are available as ICs.

JK flip-flop



Consider a negative edge-triggered JK flip-flop.

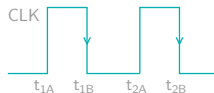
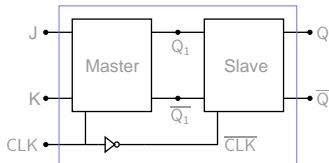
JK flip-flop



Consider a negative edge-triggered JK flip-flop.

- * As seen earlier, when CLK is high (i.e., $t_{1A} < t < t_{1B}$, etc.), the input J and K determine the Master latch output Q_1 . During this time, *no change* is visible at the flip-flop output Q .

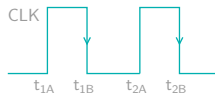
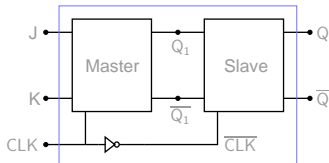
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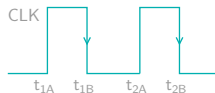
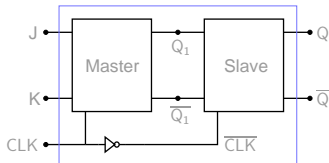
JK flip-flop



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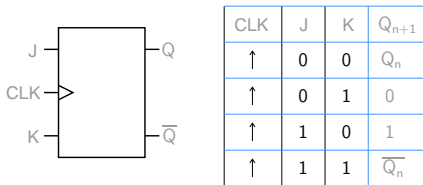
JK flip-flop



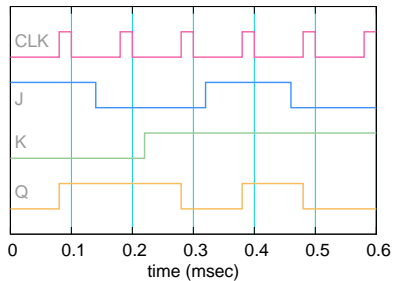
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- * In short, although the flip-flop output Q can only change *after* the active edge, (t_{1B} , t_{2B} , etc.), the new Q value is determined by J and K values just *before* the active edge.
This is a very important point!

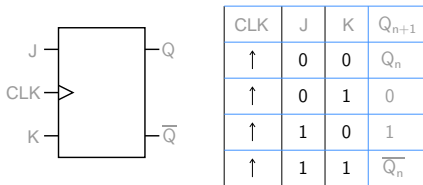
JK flip-flop



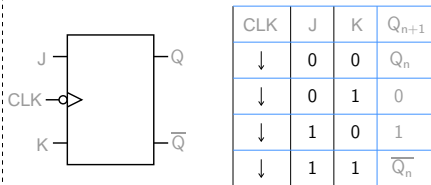
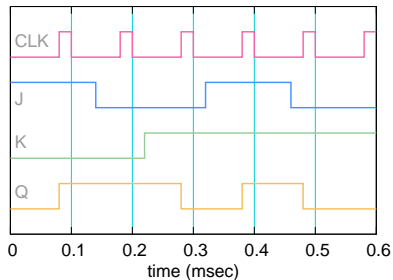
positive edge-triggered JK flip-flop



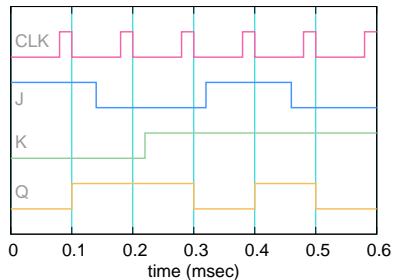
JK flip-flop



positive edge-triggered JK flip-flop

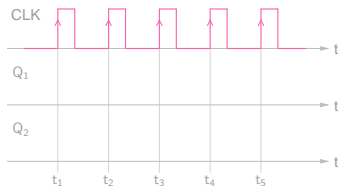
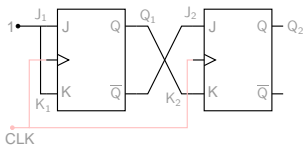


negative edge-triggered JK flip-flop



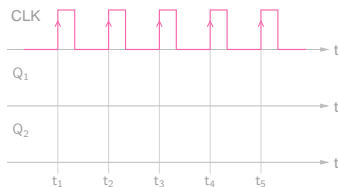
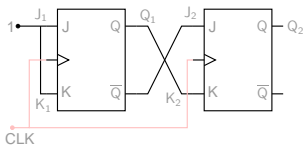
JK flip-flop

$J_1 = K_1 = 1$. Assume $Q_1 = Q_2 = 0$ initially.



JK flip-flop

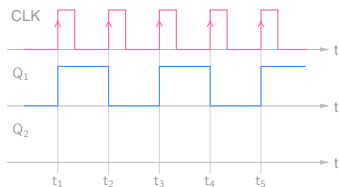
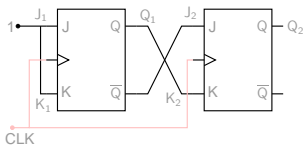
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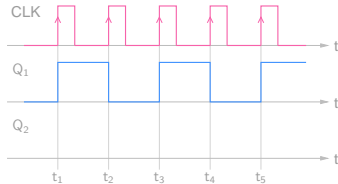
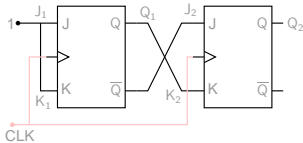
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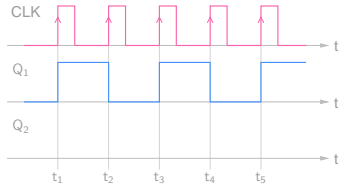
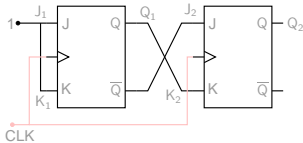
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- * $J_2 = \overline{Q_1}$, $K_2 = Q_1$. We need to look at J_2 and K_2 values *just before* the active edge, to determine the next value of Q_2 .

JK flip-flop

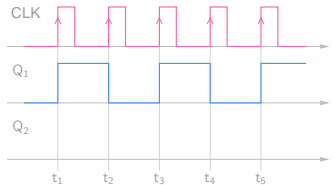
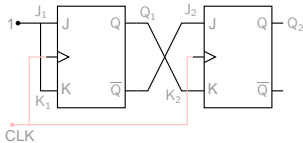
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- * It is convenient to construct a table listing J_2 and K_2 to figure out the next Q_2 value.

JK flip-flop

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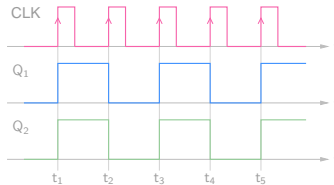
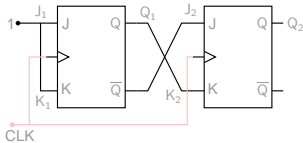


t	$J_2(t = t_k^-)$	$K_2(t = t_k^-)$	$Q_2(t = t_k^+)$
t_1	1	0	1
t_2	0	1	0
t_3	1	0	1
t_4	0	1	0
t_5	1	0	1

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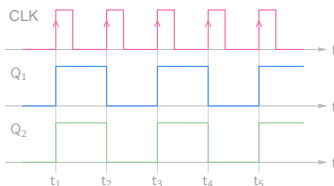
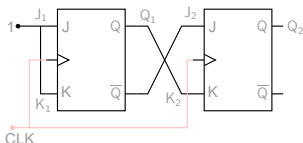


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- * It is convenient to construct a table listing J_2 and K_2 to figure out the next Q_2 value.
- * Note that the circuit is not doing much, apart from taxing our minds!
But hold on, some useful circuits will appear soon.