

M. B. Patil

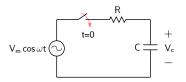
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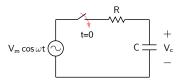
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Sinusoidal steady state



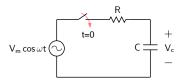




$$R(C V_c') + V_c = V_m \cos \omega t, \quad t > 0.$$
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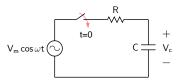


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 $R(C V'_c) + V_c = V_m \cos \omega t, \quad t > 0.$ (1) The solution $V_c(t)$ is made up of two components, $V_c(t) = V_c^{(h)}(t) + V_c^{(p)}(t)$.





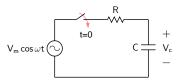
$$R(C V_c') + V_c = V_m \cos \omega t, \quad t > 0.$$
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$$R C V_c' + V_c = 0, (2)$$

from which, $V_c^{(h)}(t) = A \exp(-t/ au)$, with au = RC.

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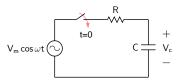
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from which, $V_c^{(h)}(t) = A \exp(-t/\tau)$, with $\tau = RC$. $V_c^{(p)}(t)$ is a particular solution of (1). Since the forcing function is $V_m \cos \omega t$, we try $V_c^{(p)}(t) = C_1 \cos \omega t + C_2 \sin \omega t$.

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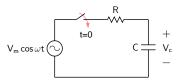
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 $\omega R C (-C_1 \sin \omega t + C_2 \cos \omega t) + C_1 \cos \omega t + C_2 \sin \omega t = V_m \cos \omega t.$

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$$R(C V_c') + V_c = V_m \cos \omega t, \quad t > 0.$$
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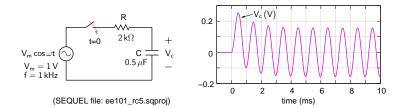
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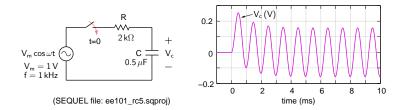
 $\omega R C (-C_1 \sin \omega t + C_2 \cos \omega t) + C_1 \cos \omega t + C_2 \sin \omega t = V_m \cos \omega t.$

 C_1 and C_2 can be found by equating the coefficients of sin ωt and $\cos \omega t$ on the left and right sides.



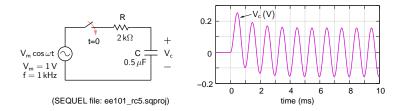
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* The complete solution is $V_c(t) = A \exp(-t/\tau) + C_1 \cos \omega t + C_2 \sin \omega t$.

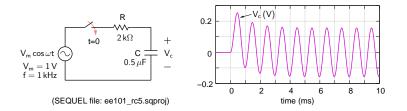




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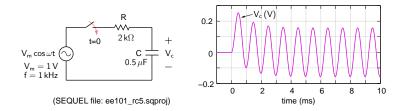
* As $t \to \infty$, the exponential term becomes zero, and we are left with $V_c(t) = C_1 \cos \omega t + C_2 \sin \omega t$.



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- * This is known as the "sinusoidal steady state" response since all quantities (currents and voltages) in the circuit are sinusoidal in nature.

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- * This is known as the "sinusoidal steady state" response since all quantities (currents and voltages) in the circuit are sinusoidal in nature.
- * Any circuit containing resistors, capacitors, inductors, sinusoidal voltage and current sources (of the same frequency), dependent (linear) sources behaves in a similar manner, viz., each current and voltage in the circuit becomes purely sinusoidal as $t \to \infty$.

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* In the sinusoidal steady state, "phasors" can be used to represent currents and voltages.



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 $\mathbf{X} = X_m \angle \theta = X_m \exp(j\theta),$



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with the following interpretation in the time domain.

 $x(t) = Re\left[\mathbf{X} e^{j\omega t}\right]$



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* Use of phasors substantially simplifies analysis of circuits in the sinusoidal steady state.

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with the following interpretation in the time domain.

$$\begin{aligned} \mathsf{x}(t) &= \mathsf{Re}\left[\mathsf{X}\,\mathsf{e}^{j\omega t}\right] \\ &= \mathsf{Re}\left[\mathsf{X}_m\,\mathsf{e}^{j\theta}\,\mathsf{e}^{j\omega t}\right] \\ &= \mathsf{Re}\left[\mathsf{X}_m\,\mathsf{e}^{j(\omega t+\theta)}\right] \\ &= \mathsf{X}_m\,\cos\left(\omega t+\theta\right) \end{aligned}$$

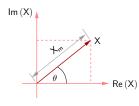
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* Note that a phasor can be written in the polar form or rectangular form, $\mathbf{X} = X_m \pounds^{\theta} = X_m \exp(j\theta) = X_m \cos \theta + j X_m \sin \theta$.

The term ωt is always *implicit*.



Time domain	Frequency domain
$v_1(t)=3.2\cos(\omega t+30^\circ) V$	

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$v_1(t)=3.2\cos(\omega t+30^\circ) V$	$V_1 = 3.2 \angle 30^\circ = 3.2 \exp{(j\pi/6)} V$
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$v_2(t) = -0.1\cos\left(\omega t\right) V$	

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$ i(t) = -1.5 \cos (\omega t + 60^{\circ}) A = 1.5 \cos (\omega t + \pi/3 - \pi) A = 1.5 \cos (\omega t - 2\pi/3) A $	$I = 1.5 \angle (-2\pi/3) A$
$ \begin{aligned} v_2(t) &= -0.1\cos\left(\omegat\right)V \\ &= 0.1\cos\left(\omegat + \pi\right)V \end{aligned} $	$V_2=0.1\angle\piV$
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$\begin{aligned} i_2(t) &= 0.18 \sin \left(\omega t \right) A \\ &= 0.18 \cos \left(\omega t - \pi/2 \right) A \end{aligned}$	$I_2 = 0.18 \angle (-\pi/2) A$
	$I_3=1+j1~A$

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	$ I_3 = 1 + j 1 A $

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$ \begin{aligned} \mathbf{v}_2(\mathbf{t}) &= -0.1\cos\left(\omega\mathbf{t}\right)\mathbf{V} \\ &= 0.1\cos\left(\omega\mathbf{t} + \pi\right)\mathbf{V} \end{aligned} $	$V_2 = 0.1\mathit{\angle}\piV$
$i_2(t) = 0.18 \sin (\omega t) A$ = 0.18 cos ($\omega t - \pi/2$) A	$I_2 = 0.18 \angle (-\pi/2) A$
$i_3(t) = \sqrt{2}\cos\left(\omega t + 45^\circ\right) A$	$ \begin{aligned} I_3 &= 1 + j 1 A \\ &= \sqrt{2} \angle 45^\circ A \end{aligned} $

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Consider addition of two sinusoidal quantities: $v(t) = v_1(t) + v_2(t)$ $= V_{m1} \cos(\omega t + \theta_1) + V_{m2} \cos(\omega t + \theta_2)$



$$= V_{m1} \cos (\omega t + \theta_1) + V_{m2} \cos (\omega t + \theta_2)$$

Now consider addition of the phasors corresponding to $v_1(t)$ and $v_2(t)$. $\mathbf{V} = \mathbf{V}_1 + \mathbf{V}_2$ $= V_{m1}e^{j\theta_1} + V_{m2}e^{j\theta_2}$



$$= V_{m1} \cos (\omega t + \theta_1) + V_{m2} \cos (\omega t + \theta_2)$$

Now consider addition of the phasors corresponding to $v_1(t)$ and $v_2(t)$.

$$\mathbf{V} = \mathbf{V}_1 + \mathbf{V}_2 \\ = V_{m1} e^{j\theta_1} + V_{m2} e^{j\theta_2}$$

In the time domain, **V** corresponds to $\tilde{v}(t)$, with $\tilde{v}(t) = Re\left[\mathbf{V}e^{j\omega t}\right]$

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In the time domain, **V** corresponds to $\tilde{v}(t)$, with $\tilde{v}(t) = Re \left[\mathbf{V} e^{j\omega t} \right]$ $= Re \left[\left(V_{m1} e^{j\theta_1} + V_{m2} e^{j\theta_2} \right) e^{j\omega t} \right]$

$$= V_{m1} \cos (\omega t + \theta_1) + V_{m2} \cos (\omega t + \theta_2)$$

Now consider addition of the phasors corresponding to $v_1(t)$ and $v_2(t)$.

$$\mathbf{V} = \mathbf{V}_1 + \mathbf{V}_2 \\ = V_{m1} e^{j\theta_1} + V_{m2} e^{j\theta_2}$$

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$$= V_{m1} \cos(\omega t + \theta_1) + V_{m2} \cos(\omega t + \theta_2)$$

Now consider addition of the phasors corresponding to $v_1(t)$ and $v_2(t)$.

$$\mathbf{V} = \mathbf{V}_1 + \mathbf{V}_2 \\ = V_{m1} e^{j\theta_1} + V_{m2} e^{j\theta_2}$$

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$$= V_{m1} \cos(\omega t + \theta_1) + V_{m2} \cos(\omega t + \theta_2)$$

Now consider addition of the phasors corresponding to $v_1(t)$ and $v_2(t)$.

$$V = V_1 + V_2$$

= $V_{m1}e^{j\theta_1} + V_{m2}e^{j\theta_2}$

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In the time domain, **V** corresponds to $\tilde{v}(t)$, with $\tilde{v}(t) = Re \left[\mathbf{V}e^{j\omega t} \right]$ $= Re \left[\left(V_{m1}e^{j\theta_1} + V_{m2}e^{j\theta_2} \right) e^{j\omega t} \right]$ $= Re \left[V_{m1}e^{j(\omega t+\theta_1)} + V_{m2}e^{(\omega t+j\theta_2)} \right]$ $= V_{m1} \cos (\omega t + \theta_1) + V_{m2} \cos (\omega t + \theta_2)$

which is the same as v(t).

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- * The KCL and KVL equations, $\sum_{ik} i_k(t) = 0 \text{ at a node, and}$ $\sum_{ik} v_k(t) = 0 \text{ in a loop,}$ amount to addition of sinusoidal quantities and can therefore be replaced by the corresponding phasor equations, $\sum_{ik} I_k = 0 \text{ at a node, and}$ $\sum_{ik} V_k = 0 \text{ in a loop.}$

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Let $i(t) = I_m \cos(\omega t + \theta)$.





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The phasors corresponding to $i(t)$ and $v(t)$ are, respectively,
 $\mathbf{I} = I_m \underline{\ell}\theta$, $\mathbf{V} = R \times I_m \underline{\ell}\theta$.

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We have therefore the following relationship between **V** and **I**: $\mathbf{V} = R \times \mathbf{I}$.



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We have therefore the following relationship between V and I: $V = R \times I$. Thus, the *impedance* of a resistor, defined as, Z = V/I, is

$$\mathbf{Z}=R+j\,\mathbf{0}$$

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Let $v(t) = V_m \cos(\omega t + \theta)$.





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Using the identity, $\cos(\phi + \pi/2) = -\sin \phi$, we get
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$$\mathbf{I} = \omega C V_m \, e^{j(\theta + \pi/2)} = \omega C V_m \, e^{j\theta} \, e^{j\pi/2} = j\omega C \, \left(V_m \, e^{j\theta} \right) = j\omega C \, \mathbf{V}_m$$



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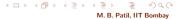
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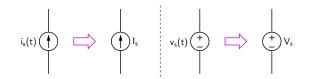


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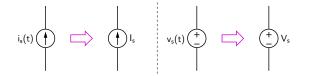
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Sources



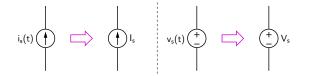




* An independent sinusoidal current source, $i_s(t) = I_m \cos(\omega t + \theta)$, can be represented by the phasor $I_m \pounds \theta$ (i.e., a *constant* complex number).

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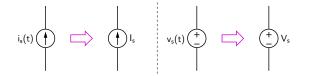
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- Dependent (linear) sources can be treated in the sinusoidal steady state in the same manner as a resistor, i.e., by the corresponding phasor relationship. For example, for a CCVS, we have,
 v(t) = r i_c(t) in the time domain.
 V = r I_c in the frequency domain.

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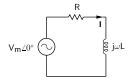
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- * Series/parallel formulas for resistors, nodal analysis, mesh analysis, Thevenin's and Norton's theorems can be directly applied to circuits in the sinusoidal steady state.

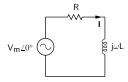
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RL circuit



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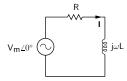
RL circuit



$$I = \frac{V_m \angle 0}{R + j\omega L} \equiv I_m \angle (-\theta),$$

where $I_m = \frac{V_m}{\sqrt{R^2 + \omega^2 L^2}}$, and $\theta = \tan^{-1}(\omega L/R).$

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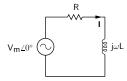


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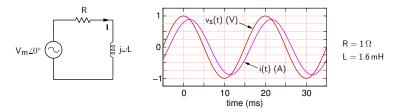


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For $R = 1 \Omega$, L = 1.6 mH, f = 50 Hz, $\theta = 26.6^{\circ}$, $t_{\text{lag}} = 1.48 \text{ ms}$. (SEQUEL file: ee101_rl_ac_1.sqproj)



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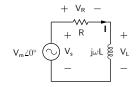
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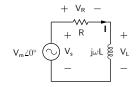
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RL circuit



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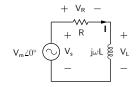


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 $\mathbf{V_R} = \mathbf{I} \times R = R I_m \angle (-\theta)$.

 $\mathbf{V}_{\mathbf{L}} = \mathbf{I} \times j\omega L = \omega I_m L \angle (-\theta + \pi/2),$

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$$I = \frac{V_m \angle 0}{R + j\omega L} \equiv I_m \angle (-\theta),$$

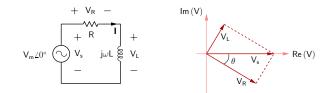
where $I_m = \frac{V_m}{\sqrt{R^2 + \omega^2 L^2}}$, and $\theta = \tan^{-1}(\omega L/R).$

$$\mathbf{V}_{\mathbf{R}} = \mathbf{I} \times R = R I_m \angle (-\theta) ,$$

$$\mathbf{V}_{\mathbf{L}} = \mathbf{I} \times j\omega L = \omega I_m L \angle (-\theta + \pi/2) ,$$

The KVL equation, $V_{\text{s}}=V_{\text{R}}+V_{\text{L}},$ can be represented in the complex plane by a "phasor diagram."

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$$I = \frac{V_m \angle 0}{R + j\omega L} \equiv I_m \angle (-\theta),$$

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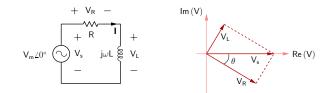
$$\mathbf{V}_{\mathbf{R}} = \mathbf{I} \times R = R I_m \angle (-\theta),$$

$$\mathbf{V}_{\mathbf{L}} = \mathbf{I} \times j\omega L = \omega I_m L \angle (-\theta + \pi/2),$$

The KVL equation, $V_{s}=V_{R}+V_{L},$ can be represented in the complex plane by a "phasor diagram."

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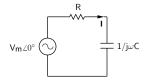
where $I_m = \frac{V_m}{\sqrt{R^2 + \omega^2 L^2}}$, and $\theta = \tan^{-1}(\omega L/R).$

$$\mathbf{V}_{\mathbf{R}} = \mathbf{I} \times R = R I_m \angle (-\theta),$$

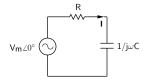
$$\mathbf{V}_{\mathbf{L}} = \mathbf{I} \times j\omega L = \omega I_m L \angle (-\theta + \pi/2),$$

The KVL equation, $V_{\text{s}}=V_{\text{R}}+V_{\text{L}},$ can be represented in the complex plane by a "phasor diagram."

If $R \gg |j\omega L|$, $\theta \to 0$, $|\mathbf{V}_{\mathbf{R}}| \simeq |\mathbf{V}_{\mathbf{s}}| = V_m$. If $R \ll |j\omega L|$, $\theta \to \pi/2$, $|\mathbf{V}_{\mathbf{L}}| \simeq |\mathbf{V}_{\mathbf{s}}| = V_m$.



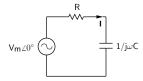




$$I = \frac{V_m \angle 0}{R + 1/j\omega C} \equiv I_m \angle \theta,$$

where $I_m = \frac{\omega C V_m}{\sqrt{1 + (\omega R C)^2}}$, and $\theta = \pi/2 - \tan^{-1}(\omega R C)$.

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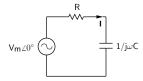


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In the time domain, $i(t) = I_m \cos(\omega t + \theta)$, which *leads* the source voltage since the peak (or zero) of i(t) occurs $t = \theta/\omega$ seconds before that of the source voltage.

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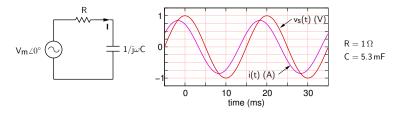


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$$\label{eq:Formula} \begin{split} &\mathsf{For}\; R=1\,\Omega,\; C=5.3\,\mathsf{mF},\; f=50\,\mathsf{Hz},\; \theta=31^\circ,\; t_{\mathsf{lead}}=1.72\;\mathsf{ms}.\\ &(\mathsf{SEQUEL\;file:\;ee101_rc_ac_1.sqproj}) \end{split}$$



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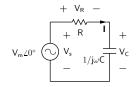
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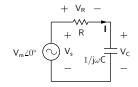
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RC circuit



$$\begin{split} \mathbf{I} &= \frac{V_m \angle 0}{R + 1/j\omega C} \equiv I_m \angle \theta, \\ \text{where } I_m &= \frac{\omega C V_m}{\sqrt{1 + (\omega R C)^2}}, \text{ and } \theta = \pi/2 - \tan^{-1}(\omega R C). \end{split}$$

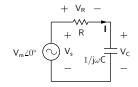


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 $\mathbf{V}_{\mathbf{R}} = \mathbf{I} \times R = R I_m \angle \theta ,$ $\mathbf{V}_{\mathbf{C}} = \mathbf{I} \times (1/j\omega C) = (I_m/\omega C) \angle (\theta - \pi/2) ,$

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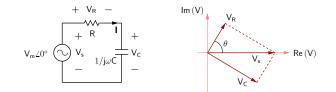


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 $\begin{aligned} \mathbf{V}_{\mathbf{R}} &= \mathbf{I} \times R = R \ I_m \angle \theta \,, \\ \mathbf{V}_{\mathbf{C}} &= \mathbf{I} \times (1/j\omega C) = (I_m/\omega C) \angle (\theta - \pi/2) \,, \end{aligned}$

The KVL equation, $V_s = V_R + V_C$, can be represented in the complex plane by a "phasor diagram."



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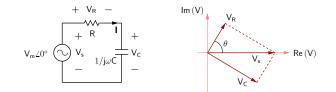
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$$\begin{split} \mathbf{V}_{\mathbf{R}} &= \mathbf{I} \times R = R \, I_m \, \angle \theta \,, \\ \mathbf{V}_{\mathbf{C}} &= \mathbf{I} \times (1/j\omega \, \mathcal{C}) = (I_m/\omega \, \mathcal{C}) \, \angle (\theta - \pi/2) \,, \end{split}$$

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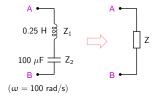
where $I_m = \frac{\omega C V_m}{\sqrt{1 + (\omega R C)^2}}$, and $\theta = \pi/2 - \tan^{-1}(\omega R C)$.

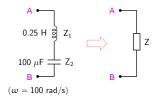
 $\begin{aligned} \mathbf{V}_{\mathbf{R}} &= \mathbf{I} \times R = R \ I_m \angle \theta \,, \\ \mathbf{V}_{\mathbf{C}} &= \mathbf{I} \times (1/j\omega C) = (I_m/\omega C) \angle (\theta - \pi/2) \,, \end{aligned}$

The KVL equation, $V_{\rm s}=V_{\rm R}+V_{\rm C},$ can be represented in the complex plane by a "phasor diagram."

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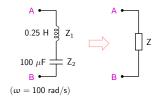
If $R \gg |1/j\omega C|$, $\theta \to 0$, $|\mathbf{V}_{\mathbf{R}}| \simeq |\mathbf{V}_{\mathbf{s}}| = V_m$. If $R \ll |1/j\omega C|$, $\theta \to \pi/2$, $|\mathbf{V}_{\mathbf{C}}| \simeq |\mathbf{V}_{\mathbf{s}}| = V_m$.





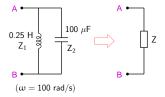
$$\begin{split} & Z_1 = j \times 100 \times 0.25 = j \, 25 \, \Omega \\ & Z_2 = -j/(100 \times 100 \times 10^{-6}) = -j \, 100 \, \Omega \\ & Z = Z_1 + Z_2 = -j \, 75 \, \Omega \end{split}$$

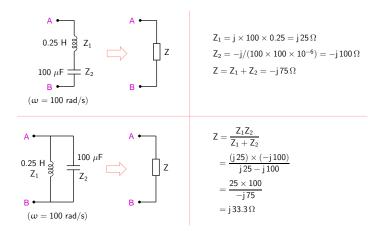
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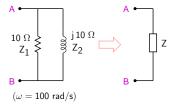




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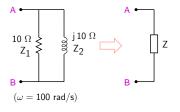
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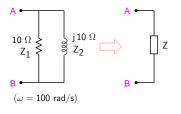
Method 1:

$$Z = \frac{10 \times j10}{10 + j10} = \frac{j10}{1 + j}$$
$$= \frac{j10}{1 + j} \times \frac{1 - j}{1 - j}$$
$$= \frac{10 + j10}{2} = 5 + j5 \Omega$$

Convert to polar form \rightarrow Z = 7.07 \angle 45° Ω

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Method 1:

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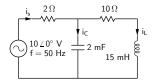
Method 2:

$$Z = \frac{10 \times j10}{10 + j10} = \frac{100 \angle \pi/2}{10\sqrt{2} \angle \pi/4}$$
$$= 5\sqrt{2} \angle (\pi/2 - \pi/4) = 7.07 \angle 45^{\circ} \Omega$$

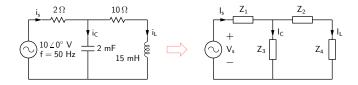
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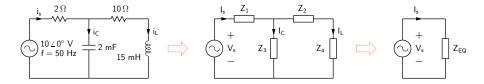
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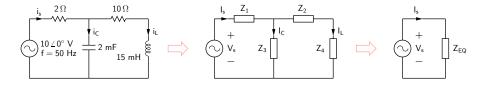




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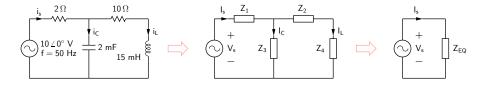






$$\mathbf{Z}_3 = \frac{1}{j \times 2\pi \times 50 \times 2 \times 10^{-3}} = -j \, 1.6 \, \Omega$$

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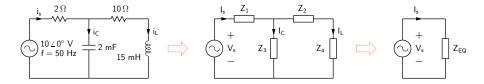


$$\begin{aligned} \mathbf{Z}_3 &= \frac{1}{j \times 2\pi \times 50 \times 2 \times 10^{-3}} = -j \, 1.6 \, \Omega \\ \mathbf{Z}_4 &= 2\pi \times 50 \times 15 \times 10^{-3} = j \, 4.7 \, \Omega \end{aligned}$$



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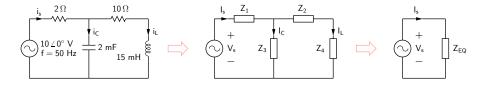


$$\begin{aligned} \mathbf{Z}_{3} &= \frac{1}{j \times 2\pi \times 50 \times 2 \times 10^{-3}} = -j \, 1.6 \, \Omega \\ \mathbf{Z}_{4} &= 2\pi \times 50 \times 15 \times 10^{-3} = j \, 4.7 \, \Omega \\ \mathbf{Z}_{EQ} &= \mathbf{Z}_{1} + \mathbf{Z}_{3} \parallel (\mathbf{Z}_{2} + \mathbf{Z}_{4}) \end{aligned}$$



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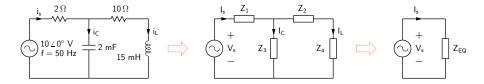
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$$\begin{aligned} \mathbf{Z}_3 &= \frac{1}{j \times 2\pi \times 50 \times 2 \times 10^{-3}} = -j \, 1.6 \, \Omega \\ \mathbf{Z}_4 &= 2\pi \times 50 \times 15 \times 10^{-3} = j \, 4.7 \, \Omega \\ \mathbf{Z}_{EQ} &= \mathbf{Z}_1 + \mathbf{Z}_3 \parallel (\mathbf{Z}_2 + \mathbf{Z}_4) \\ &= 2 + (-j \, 1.6) \parallel (10 + j \, 4.7) = 2 + \frac{(-j \, 1.6) \times (10 + j \, 4.7)}{-j \, 1.6 + 10 + j \, 4.7} \end{aligned}$$

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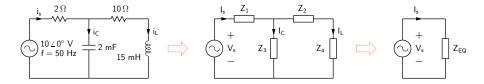
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$$\begin{aligned} \mathbf{Z}_{3} &= \frac{1}{j \times 2\pi \times 50 \times 2 \times 10^{-3}} = -j \, 1.6 \, \Omega \\ \mathbf{Z}_{4} &= 2\pi \times 50 \times 15 \times 10^{-3} = j \, 4.7 \, \Omega \\ \mathbf{Z}_{EQ} &= \mathbf{Z}_{1} + \mathbf{Z}_{3} \parallel (\mathbf{Z}_{2} + \mathbf{Z}_{4}) \\ &= 2 + (-j \, 1.6) \parallel (10 + j \, 4.7) = 2 + \frac{(-j \, 1.6) \times (10 + j \, 4.7)}{-j \, 1.6 + 10 + j \, 4.7} \\ &= 2 + \frac{1.6 \angle (-90^{\circ}) \times 11.05 \angle (25.2^{\circ})}{10.47 \angle (17.2^{\circ})} = 2 + \frac{17.7 \angle (-64.8^{\circ})}{10.47 \angle (17.2^{\circ})} \end{aligned}$$

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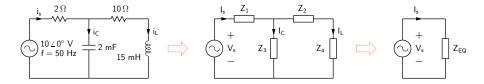
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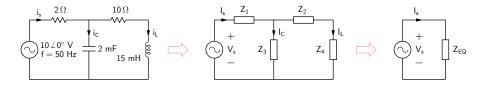
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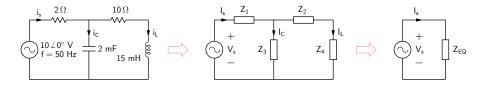


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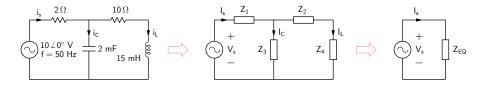






$$I_{s} = \frac{V_{s}}{Z_{EQ}} = \frac{10 \angle (0^{\circ})}{2.79 \angle (-36.8^{\circ})} = 3.58 \angle (36.8^{\circ}) A$$

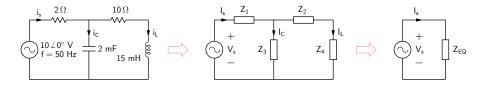




$$I_{s} = \frac{V_{s}}{Z_{EQ}} = \frac{10 \angle (0^{\circ})}{2.79 \angle (-36.8^{\circ})} = 3.58 \angle (36.8^{\circ}) A$$
$$I_{C} = \frac{(Z_{2} + Z_{4})}{Z_{3} + (Z_{2} + Z_{4})} \times I_{s} = 3.79 \angle (44.6^{\circ}) A$$

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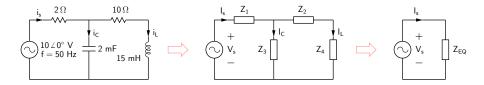
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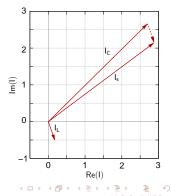
$$I_{s} = \frac{V_{s}}{Z_{EQ}} = \frac{10 \angle (0^{\circ})}{2.79 \angle (-36.8^{\circ})} = 3.58 \angle (36.8^{\circ}) A$$
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$$I_{L} = \frac{Z_{3}}{Z_{3} + (Z_{2} + Z_{4})} \times I_{s} = 0.546 \angle (-70.6^{\circ}) A$$

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$$I_{s} = \frac{V_{s}}{Z_{EQ}} = \frac{10 \angle (0^{\circ})}{2.79 \angle (-36.8^{\circ})} = 3.58 \angle (36.8^{\circ}) A$$
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$$I_{L} = \frac{Z_{3}}{Z_{3} + (Z_{2} + Z_{4})} \times I_{s} = 0.546 \angle (-70.6^{\circ}) A$$



Sinusoidal steady state: power computation







Let
$$v(t) = V_m \cos(\omega t + \theta)$$
, i.e., $\mathbf{V} = V_m \angle \theta$,
 $i(t) = I_m \cos(\omega t + \phi)$, i.e., $\mathbf{I} = I_m \angle \phi$.





Let
$$v(t) = V_m \cos(\omega t + \theta)$$
, i.e., $\mathbf{V} = V_m \angle \theta$,
 $i(t) = I_m \cos(\omega t + \phi)$, i.e., $\mathbf{I} = I_m \angle \phi$.

The instantaneous power absorbed by ${\bf Z}$ is,

$$P(t) = v(t) i(t)$$

$$= V_m I_m \cos(\omega t + \theta) \cos(\omega t + \phi)$$

$$= \frac{1}{2} V_m I_m [\cos(2\omega t + \theta + \phi) + \cos(\theta - \phi)]$$
(1)



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Let
$$v(t) = V_m \cos(\omega t + \theta)$$
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$$= \frac{1}{2} V_m I_m [\cos(2\omega t + \theta + \phi) + \cos(\theta - \phi)]$$
(1)

The average power absorbed by Z is

$$P = rac{1}{T} \int_0^T P(t) \, dt$$
, where $T = 2\pi/\omega$.

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Let
$$v(t) = V_m \cos(\omega t + \theta)$$
, i.e., $\mathbf{V} = V_m \angle \theta$,
 $i(t) = I_m \cos(\omega t + \phi)$, i.e., $\mathbf{I} = I_m \angle \phi$.

The instantaneous power absorbed by Z is,

$$P(t) = v(t) i(t)$$

$$= V_m I_m \cos(\omega t + \theta) \cos(\omega t + \phi)$$

$$= \frac{1}{2} V_m I_m [\cos(2\omega t + \theta + \phi) + \cos(\theta - \phi)]$$
(1)

The average power absorbed by Z is

$$P = rac{1}{T} \int_0^T P(t) \, dt$$
, where $T = 2\pi/\omega$.

The first term in Eq. (1) has an average value of zero and does not contribute to P. Therefore,

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$$P = rac{1}{2} V_m I_m \cos{(heta - \phi)}$$
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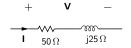
$$V = V_{m} \angle \theta, I = I_{m} \angle \phi$$
$$P = \frac{1}{2} V_{m} I_{m} \cos(\theta - \phi)$$

+ V -	General formula: $V = V_m \angle \theta, I = I_m \angle \phi$ $P = \frac{1}{2} V_m I_m \cos (\theta - \phi)$
+ V − → ₩ I R	$\begin{split} V &= RI \\ ForI &= I_m\mathit{\angle}\alpha, \; V = RI_m\mathit{\angle}\alpha, \\ P &= \frac{1}{2}(RI_m)I_mcos(\alpha - \alpha) = \frac{1}{2}I_m^2R = \frac{1}{2}V_m^2/R \end{split}$

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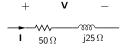
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+ V $-+$ $ -I _{C}$	$\begin{split} \mathbf{I} &= \mathbf{j}\omegaCV \\ \text{For } V &= V_m\mathit{\perp}\alpha, \ \mathbf{I} = \omegaCV_m\mathit{\perp}(\alpha + \pi/2), \\ P &= \frac{1}{2}V_mI_m\cos\left[\alpha - (\alpha + \pi/2)\right] = 0 \\ & < \square \diamond < \square < \square \diamond < \square > \square < \square < \square < \square < \square < \square > \square < \square > \square < \square < \square < \square < \square < \square < \square > \square < \square > \square < \square < \square > \square < \square < \square > \square < \square > \square < \square < \square > \square < \square > \square < \square < \square < \square > \square > \square > \square > \square < \square > \square > \square < \square > \square < \square > \square > \square < \square > \square < \square > \square > \square < \square > \square < \square > \square < \square < \square > \square < \square > \square > \square > \square < \square > \square > \square > \square > \square < \square > \square > \square > \square > \square < \square > \square > \square > \square > \square > \square > \square < \square > \square $



Find the average power absorbed.



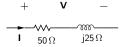


Find the average power absorbed.

Method 1:

$$V = (50 + j25) \times 2 \angle 45^{\circ} = 55.9 \angle 26.6^{\circ} \times 2 \angle 45^{\circ} = 111.8 \angle (45^{\circ} + 26.6^{\circ})$$





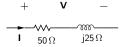
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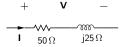
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No average power is absorbed by the inductor. $\Rightarrow P = P_R$ (average power absorbed by R)

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Find the average power absorbed.

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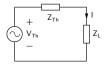
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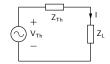
Method 2:

No average power is absorbed by the inductor. $\Rightarrow P = P_R \text{ (average power absorbed by } R\text{)}$ $= \frac{1}{2} I_m^2 R = \frac{1}{2} \times 2^2 \times 50$ = 100 W.





Let $\mathbf{Z}_L = R_L + jX_L$, $\mathbf{Z}_{Th} = R_{Th} + jX_{Th}$, and $\mathbf{I} = I_m \angle \phi$.



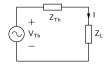


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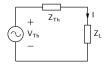
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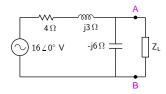
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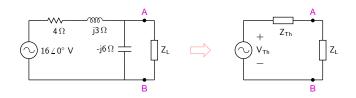
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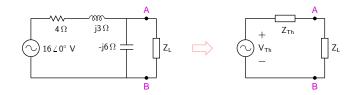
Therefore, for maximum power transfer to the load Z_L , we need,

$$R_L = R_{Th}, X_L = -X_{Th}, \text{ i.e., } \mathbf{Z}_L = \mathbf{Z}_{Th}^*.$$



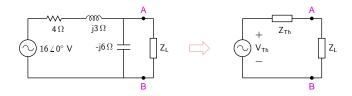






 $\mathbf{Z}_{Th} = (-j\,6) \parallel (4+j\,3) = 5.76 - j\,1.68\,\Omega$.



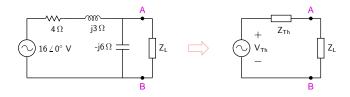


$$\begin{split} \mathbf{Z}_{\mathit{Th}} &= (-j\,6) \parallel (4+j\,3) = 5.76 - j\,1.68\,\Omega \,. \\ \text{For maximum power transfer, } \mathbf{Z}_L &= \mathbf{Z}^*_{\mathit{Th}} = 5.76 + j\,1.68\,\Omega \equiv \mathit{R}_L + j\,\mathit{X}_L \,. \end{split}$$

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Maximum power transfer: example

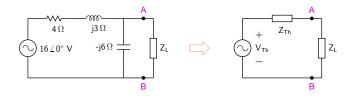


$$\begin{split} & \mathbf{Z}_{Th} = (-j\,6) \parallel (4+j\,3) = 5.76 - j\,1.68\,\Omega \,. \\ & \text{For maximum power transfer, } \mathbf{Z}_L = \mathbf{Z}^*_{Th} = 5.76 + j\,1.68\,\Omega \equiv R_L + j\,X_L \,. \\ & \mathbf{V}_{Th} = 16\,\angle\,0^\circ \,\times\, \frac{-j\,6}{(4+j\,3) + (-j\,6)} = 19.2\,\angle(-53.13^\circ) \,. \end{split}$$

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Maximum power transfer: example



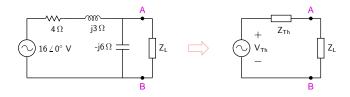
$$Z_{Th} = (-j6) \parallel (4+j3) = 5.76 - j \, 1.68 \, \Omega.$$

For maximum power transfer, $Z_L = Z_{Th}^* = 5.76 + j \, 1.68 \, \Omega \equiv R_L + j \, X_L$.
 $V_{Th} = 16 \, \angle \, 0^\circ \times \frac{-j6}{(4+j3) + (-j6)} = 19.2 \, \angle (-53.13^\circ).$
 $I = \frac{V_{Th}}{Z_{TL} + Z_L} = \frac{V_{Th}}{2R_L}.$

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Maximum power transfer: example



$$\begin{aligned} \mathbf{Z}_{Th} &= (-j6) \parallel (4+j3) = 5.76 - j \, 1.68 \, \Omega \, . \\ \text{For maximum power transfer, } \mathbf{Z}_L &= \mathbf{Z}_{Th}^* = 5.76 + j \, 1.68 \, \Omega \equiv R_L + j \, X_L \, . \\ \mathbf{V}_{Th} &= 16 \, \angle \, 0^\circ \, \times \, \frac{-j6}{(4+j3) + (-j6)} = 19.2 \, \angle (-53.13^\circ) \, . \\ \mathbf{I} &= \frac{\mathbf{V}_{Th}}{\mathbf{Z}_{Th} + \mathbf{Z}_L} = \frac{\mathbf{V}_{Th}}{2 \, R_L} \, . \\ P &= \frac{1}{2} \, l_m^2 R_L = \frac{1}{2} \, \left(\frac{19.2}{2 \, R_L} \right)^2 \, \times \, R_L = \frac{1}{2} \, \frac{(19.2)^2}{4 \, R_L} = 8 \, W. \end{aligned}$$

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$$P_1 = rac{1}{T} \, \int_{t_0}^{t_0+T} [i(t)]^2 \, R \, dt \, ,$$

where t_0 is some reference time (we will take t_0 to be 0).

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 I_{eff} , the effective value of i(t), is defined such that $P_1 = P_2$, i.e.,

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$$I_{eff}^2 R = \frac{1}{T} \int_0^T \left[i(t) \right]^2 R \, dt \, ,$$

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If i(t) is sinusoidal, i.e., $i(t) = I_m \cos(\omega t + \phi)$,

$$\begin{split} I_{eff} &= \sqrt{\frac{1}{T} \int_0^T I_m^2 \cos^2(\omega t + \phi) \, dt} = I_m \sqrt{\frac{1}{T} \int_0^T \frac{1}{2} \left[1 + \cos\left(2\omega t + 2\phi\right)\right] \, dt} \\ &= I_m \sqrt{\frac{1}{T} \frac{1}{2}T} = I_m / \sqrt{2} \,. \end{split}$$

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Similarly, $V_{eff} = V_m/\sqrt{2}$.

$$P = \frac{1}{2} V_m I_m \cos(\theta - \phi) = \frac{V_m}{\sqrt{2}} \frac{I_m}{\sqrt{2}} \cos(\theta - \phi)$$
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Apparent power is defined as $P_{app} = V_{eff} I_{eff}$ (Volt-Amp).

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 $(\theta - \phi) > 0$: i(t) lags v(t), the P.F. is called a *lagging* P.F. (inductive impedance)

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$$P = \frac{1}{2} V_m I_m \cos(\theta - \phi) = \frac{V_m}{\sqrt{2}} \frac{I_m}{\sqrt{2}} \cos(\theta - \phi)$$
$$= V_{eff} I_{eff} \cos(\theta - \phi) \text{ (Watts)}$$

Apparent power is defined as $P_{app} = V_{eff} I_{eff}$ (Volt-Amp).

Power factor is defined as $P. F. = \frac{\text{Average power}}{\text{Apparent power}} = \cos(\theta - \phi).$

 $(\theta - \phi) > 0$: i(t) lags v(t), the P.F. is called a *lagging* P.F. (inductive impedance)

 $(\theta - \phi) < 0$: i(t) leads v(t), the P.F. is called a *leading* P.F. (capacitive impedance)

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 $P_{app} = 120 \times 2 = 240$ V-A.



$$\begin{split} P_{app} &= 120 \times 2 = 240 \ V\text{-}A. \\ \text{P.F.} &= \cos\left(0^{\circ} - (-36.9^{\circ})\right) = 0.8 \text{ lagging (since I lags V)}. \end{split}$$



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$$P_{app} = 120 \times 2 = 240 \text{ V-A.}$$

P.F. = cos (0° - (-36.9°)) = 0.8 lagging (since I lags V).
 $P = P_{app} \times P.F. = 192 \text{ W.}$

2. Given: P = 50 kW, P.F. = 0.95 (lagging), $\mathbf{V} = 480 \angle 0^{\circ} \text{ V (rms)}$. Find I.

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 $V_{eff} \times I_{eff} \times P.F = 50 \times 10^3$

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 $I_{eff} = \frac{50 \times 10^{3}}{480 \times 0.95} = 109.6 \ A.$

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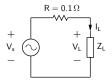
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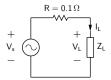
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Consider a simplified model of a power system consisting of a generator (V_s) , transmission line (R), and load (Z_L) .

The load is specified as P = 50 kW, P.F.= 0.6 (lagging), $\mathbf{V}_L = 480 \angle 0^\circ V$ (rms). Note: lagging power factors are typical of industrial loads (motors).

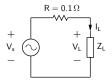
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 $P = 50 \times 10^3 \ W = |\mathbf{V}_L| \times |\mathbf{I}_L| \times \text{P.F.} \Rightarrow |\mathbf{I}_L| = \frac{50 \times 10^3}{480 \times 0.6} = 173.6 \ A \ (\text{rms}).$



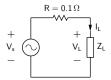
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Power loss in the transmission line $P_{\text{loss}} = |\mathbf{I}_L|^2 R = (173.6)^2 \times 0.1 = \underline{3 \text{ kW}}$.

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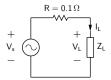
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If the load power factor was 0.95 (lagging), we would have 50×10^3

$$|I_L| = \frac{50 \times 10^5}{480 \times 0.95} = 109.6 \ A \ (rms), \text{ and } P_{loss} = (109.6)^2 \times 0.1 = \underline{1.2 \ kW}.$$



Consider a simplified model of a power system consisting of a generator (V_s) , transmission line (R), and load (Z_L) .

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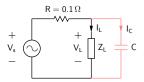
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If the load power factor was 0.95 (lagging), we would have 10^3

$$|I_L| = \frac{50 \times 10^4}{480 \times 0.95} = 109.6 \ A \ (rms), \text{ and } P_{loss} = (109.6)^2 \times 0.1 = \underline{1.2 \ kW}.$$

Thus, a higher power factor can substantially reduce transmission losses.



Consider a simplified model of a power system consisting of a generator (V_s) , transmission line (R), and load (Z_L) .

The load is specified as P = 50 kW, P.F.= 0.6 (lagging), $V_L = 480 \angle 0^{\circ} V$ (rms). Note: lagging power factors are typical of industrial loads (motors).

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Power loss in the transmission line $P_{\text{loss}} = |\mathbf{I}_L|^2 R = (173.6)^2 \times 0.1 = \underline{3 \text{ kW}}.$

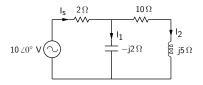
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Thus, a higher power factor can substantially reduce transmission losses. The effective power factor of an inductive load can be improved by connecting a suitable capacitance in parallel.

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Power computation: home work



- * Find I_1 , I_2 , I_s .
- * Compute the average power absorbed by each element.

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* Verify power balance.

(SEQUEL file: ee101_phasors_2.sqproj)