

Midsem Exam: EE 752 Model Order Reduction.
27th Feb 2015

Q-1 Consider the stable system $\dot{x} = Ax + Bu$, $y = Cx$ with A Hurwitz, (A, B) controllable and (C, A) observable.

(a) Write the equation of which the controllability & observability gramians P & Q are solutions.

(b) Show that the eigenvalues of the product of PQ is invariant w.r.t. coordinate transformations $x = Tz$

and also show that in general eigenvalues of P are not invariant (under $x = Tz$).

(c) Suggest a procedure that yields $\tilde{P}\tilde{Q} = \tilde{D}^2$, D diagonal. Show that this procedure indeed gives $\tilde{P} = D$ and $\tilde{P} = D = \tilde{Q}$

(d) Show that if P & Q are symmetric & nondefinite, then eigenvalues of PQ are positive; and comment on symmetry of PQ .

Q-2: For the state space system in Q-1 (with D =feedthrough term=0), obtain LMI conditions for H_∞ norm to be $\leq \gamma$, $\gamma > 0$. Suppose the H_∞ norm $< \gamma$, then obtain the corresponding Hamiltonian matrix and show that ~~exact~~ ARE solution X can be obtained from a suitable n -dimensional H -invariant subspace of \mathbb{R}^{2n} .

Q-3 Find minimum $\int_0^\infty (x^2 + u^2) dt$, $x(0) = 8$
 $u \in C^0(\mathbb{R}, \mathbb{R})$

using a suitable Riccati equation and its solution.

Note: ~~Q-1,2~~: 10 marks each.

Q-3 - 5 marks each.

Weightage 35%. Make suitable assumptions yourself in case of ambiguity & state assumption explicitly.