Dual-systems, orthogonal complement, Hamiltonian matrices, dissipativity-preserving model reduction (Lecture 13)

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- More analogies with indefinite linear algebra
- Lossless systems, orthogonal complement, dual/adjoint systems
- Hamiltonian matrices, trajectories of minimal dissipation
- Remaining behavioral-notation
- Dissipativity-preserving model-order reduction

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Consider subspace  $\mathbb{V} \subset \mathbb{R}^{w}$  and symmetric and nonsingular  $\Sigma \in \mathbb{R}^{w \times w}$ (Think initially  $\Sigma = \text{diag} (1, 1, 1, \dots, -1, -1, -1, \dots).)$ )

- $\mathbb{V} ext{ is } \Sigma ext{-non-negative} \Rightarrow \dim(\mathbb{V}) \leqslant \sigma_+(\Sigma)$
- $\mathbb{V}$  is  $\Sigma$ -neutral  $\Rightarrow \Sigma$  is indefinite (unless  $\mathbb{V} = 0$ )
- $\mathbb{V} \cap \mathbb{V}^{\perp} = 0$
- $\mathbb{V} \oplus \mathbb{V}^{\perp} = \mathbb{R}^{w}$  and  $\dim(\mathbb{V}) + \dim(\mathbb{V}^{\perp}) = w$
- $\mathbb{V}^{\perp_{\Sigma}} = (\Sigma \mathbb{V})^{\perp} = \Sigma^{-1} \mathbb{V}^{\perp}$
- $\mathbb{V}$  is strictly  $\Sigma$ -non-negative  $\Leftrightarrow \mathbb{V}$  is  $\Sigma$ -positive

 $\text{Suppose } \dim(\mathbb{V}) = \sigma_+(\Sigma) \, \left( \text{then } \dim(\mathbb{V}^{\perp_\Sigma}) = \sigma_-(\Sigma) \right)$ 

 $\mathbb{V} \text{ is } \Sigma\text{-positive} \Leftrightarrow \mathbb{V}^{\perp} \text{ is } \textbf{-}\Sigma^{-1}\text{-positive} \Leftrightarrow \mathbb{V}^{\perp_{\Sigma}} \text{ is } \textbf{-}\Sigma\text{-positive}$ 

 $\mathbb {V} ext{ is } \Sigma ext{-neutral} \equiv \mathfrak B ext{ is } \Sigma ext{-lossless} \ ext{all-pass}, \ \partial \Phi'(\xi) = 0$ 

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  - $\mathbb{V}$  is  $\Sigma$ -neutral  $\equiv \mathfrak{B}$  is  $\Sigma$ -lossless all-pass,  $\partial \Phi'(\xi) = 0$

# For behaviors $\mathfrak{B} \subset \mathfrak{C}^{\infty}(\mathbb{R}, \mathbb{R}^{w})$

The orthogonal complement of  $\mathfrak{B}$  (in  $\mathfrak{C}^{\infty}(\mathbb{R}, \mathbb{R}^{w})$ ):  $\mathfrak{B}^{\perp}$ Adjoint system, dual system, co-state dynamics (Dual Riccati: for the dual system) Suppose  $\Sigma \in \mathbb{R}^{w \times w}$  is symmetric and nonsingular.  $\mathfrak{B}^{\perp_{\Sigma}}$  just 'normalization' w.r.t.  $\Sigma$ .

• Number of inputs of  $\mathfrak{B}$  (i.e.  $\mathfrak{m}(\mathfrak{B})$ ): column rank of  $M(\xi)$  (Image representation  $w = M(\frac{d}{dt})\ell$ )

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$$\mathfrak{B}$$
 is  $\Sigma$ -dissipative  $\Rightarrow$  m $(\mathfrak{B}) \leqslant \sigma_+(\Sigma)$ 

- $\mathfrak{B} + \mathfrak{B}^{\perp} = \mathfrak{C}^{\infty}(\mathbb{R}, \mathbb{R}^{w})$ , though not direct sum
- $\mathfrak{B} \cap \mathfrak{B}^{\perp} \neq \{0\}$ , the intersection is 'thin'
- Intersection is autonomous, i.e. <u>finite</u> dimensional
- $\mathfrak{B} \cap \mathfrak{B}^{\perp} \cap \mathfrak{D} = \{0\}$
- Intersection has dynamics  $\frac{d}{dt}x = Hx$ , for a Hamiltonian matrix H.

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• (*H* is called Hamiltonian if  $H^T \sim -H$ )

Intersection: central role in model-order reduction (dissipativity preserving)

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 $\mathfrak{B}_1$  and  $\mathfrak{B}_2$  (both controllable) are  $\Sigma$ -orthogonal : $\Leftrightarrow$ 

$$\int_{\mathbb{R}} w_1^T \Sigma w_2 dt = 0 ext{ for all } w_1 \in \mathfrak{B}_1, w_2 \in \mathfrak{B}_2 \cap \mathfrak{D}.$$

 $\mathfrak{B}_1 \perp_{\Sigma} \mathfrak{B}_2 \Leftrightarrow \mathfrak{B}_1 imes \mathfrak{B}_2$  is lossless with respect to  $\begin{bmatrix} 0 & \Sigma \\ \Sigma & 0 \end{bmatrix}$ 

Note: the Cartesian product  $\mathfrak{B}_1 \times \mathfrak{B}_2 \subseteq \mathfrak{C}^{\infty}(\mathbb{R}, \mathbb{R}^{2w}),$  $(w_1, w_2) \in \mathfrak{B}_1 \times \mathfrak{B}_2 \Leftrightarrow w_1 \in \mathfrak{B}_1 \text{ and } w_2 \in \mathfrak{B}_2.$ 

In general,  $m(\mathfrak{B}_1) + m(\mathfrak{B}_2) \leqslant w$ 

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More generally,  $\mathfrak{B} \cap \mathfrak{B}^{\perp_{\Sigma}} =: \mathfrak{B}^*$ 

- $\mathfrak{B}^*$ : trajectories in  $\mathfrak{B}$  of 'minimal dissipation' (Minh, Trentelman & Rapisarda: MCSS 2009)
- Retain a lower dimension of  $\mathfrak{B}^*$  into the reduced order model
- Restriction on B (to B\*) can also be achieved by forcing *l* to satisfy equations (instead of free/generic):

$$w=M(rac{d}{dt})\ell \quad ext{ and } \quad \partial \Phi'(rac{d}{dt})\ell=0.$$

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- (In general, view additional laws as a controller: feedback? controller)
- Is intersection autonomous? Is det  $\partial \Phi'(\xi) \equiv 0$ ?

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### At maximality

Suppose  $\mathfrak{m}(\mathfrak{B}) = \sigma_+(\Sigma)$  (then  $\mathfrak{m}(\mathfrak{B}^{\perp_{\Sigma}}) = \sigma_-(\Sigma)$ )

- $\mathfrak{B}$  is  $\Sigma$ -dissipative  $\Leftrightarrow \mathfrak{B}^{\perp_{\Sigma}}$  is - $\Sigma$ -dissipative
- $\mathfrak{B}$  is strictly  $\Sigma$ -dissipative  $\Leftrightarrow \mathfrak{B}^{\perp_{\Sigma}}$  is strictly - $\Sigma$ -dissipative
- $\mathfrak{B}$  is strictly  $\Sigma$ -dissipative  $\Rightarrow$  ARE has a solution K
- $\mathfrak{B}^{\perp_{\Sigma}}$  is strictly - $\Sigma$ -dissipative  $\Rightarrow$  'Dual ARE' has a solution P (say)
- •With careful state-space basis choice, ARE solutions

 $-K^{-1} =$  Dual ARE solutions P

**References:** 

- Section 10 of QDF paper by Willems & Trentelman, 1998, SIAM Journal on Control & Optimization
- Proposition 12 of Willems & Trentelman (Part I), IEEE-TAC, 2002 (Synthesis of dissipative systems)

### Non-strict dissipativity

- $\Sigma$ -lossless  $\Leftrightarrow \mathfrak{B} \subseteq \mathfrak{B}^{\perp_{\Sigma}}$
- Consider system with proper SISO transfer function G(s) with no poles in CRHP.
- $\|G(s)\|_{\mathcal{H}_{\infty}} \ge \gamma \Leftrightarrow \text{dissipative with respect to } \gamma^2 u^2 y^2$

• 
$$(\cdots > \cdots \Leftrightarrow \text{strict} \cdots, \text{etc.})$$

- $||G(s)||_{\mathcal{H}_{\infty}} = \gamma \Leftrightarrow \text{dissipative with respect to } \gamma^2 u^2 y^2,$ but
- Either  $\gamma^2 I D^T D$  is singular (lack of strictness at infinity frequency) or there exists  $\omega_0 \in \mathbb{R}$  such that  $\mathcal{H}_{\infty}$  norm is attained at  $\omega$
- The former case: the Hamiltonian matrix *H* does not exist (singular descriptor system)
- The latter case: the Hamiltonian matrix H (exists and) has eigenvalue at  $\pm j\omega_0$ .

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Compared to just dissipativity, strict dissipativity helps Suppose  $\mathfrak{B} \in \mathfrak{L}^{\mathtt{w}}_{\text{cont}}$  and  $\mathfrak{B}$  is strictly  $\Sigma$ -dissipativity  $\Rightarrow \partial \Phi'(j\omega) > 0$  for each  $\omega \in \mathbb{R}$ .

- The P in  $u^T(P)u$  within the LMI is invertible. (Dissipativity at  $\infty$  frequency is strict.)
- The strict LMI has a solution: feasibility
- $\bullet$  The ARE and the Hamiltonian matrix H exist
- The strict ARI has a solution and  $K_{\max} > K_{\min}$  (Scherer)
- In fact, H has no eigenvalues on the imaginary axis
- det  $\partial \Phi'(\xi)$  has no roots on  $j\mathbb{R}$
- (Note that det  $\partial \Phi'(\xi) = \det(\xi I H)$ : spectral zeros)

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# Passivity preserving Model order reduction

- Many papers in the literature: Feldman, Freund (1995, 1999 IEEE-TAC), Ober (1998, SIAM Con & Opt), PRIMA
- Based on positive real balancing
- 'Simultaneous diagonalization': similarity transformation or congruence transformation?  $A \rightarrow S^{-1}AS$  or  $P \rightarrow S^T PS$
- Note that for storage  $x^T K x$ , state space coordinate transformation due to S means storage  $z^T (S^T K S) z$ .
- Find coordinate transformation such that max/min of ARE/Dual-ARE solutions are 'balanced' (Simultaneously diagonalized: Antoulas, SIAM 2004 book)
- In this course, passivity preserving model reduction by
  - 'interpolation at spectral zeros' (Antoulas/Sorensen: SCL 2005)
  - preserving trajectories of minimal dissipation (Minh, Trentelman, Rapisarda: MCSS 2009)

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Given  $\mathfrak{B} \in \mathfrak{L}_{\text{cont}}^{w}$  and symmetric nonsingular  $\Sigma \in \mathbb{R}^{w \times w}$ Suppose  $\mathfrak{B}$  is strictly  $\Sigma$ -dissipative and suppose n is the McMillan degree of  $\mathfrak{B}$ (McMillan degree: model order: minimum number of states)

Choose k < n. Find  $\mathfrak{B} \in \mathfrak{L}^{\scriptscriptstyle{W}}_{\operatorname{cont}}$  such that

- 9  $\hat{\mathfrak{B}}$  has McMillan degree at most k
- $@ m(\hat{\mathfrak{B}}) = m(\mathfrak{B})$
- **③**  $\hat{\mathfrak{B}}$  is also strictly  $\Sigma$ -dissipative
- $\textcircled{9} \ \hat{\mathfrak{B}} \text{ satisfies } \hat{\mathfrak{B}}^* \subset \mathfrak{B}^*$

(Fourth point: trajectories in  $\mathfrak{B}$  of minimal dissipation are retained into  $\hat{\mathfrak{B}}$ )

(Problem formulation correct except for stability aspect)

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