

Uniqueness & Existence of $\| \cdot \|$

Normed Space:

Def: A normed linear space is an ordered pair $(X, \| \cdot \|)$ where X is a linear vector space & $\| \cdot \|: X \rightarrow \mathbb{R}$ is a real valued function defined on X s.t. the following axioms hold:

- 1) $\|x\| \geq 0$, $\forall x \in X$; $\|x\| = 0$ iff $x = 0_x$
- 2) $\| \alpha x \| = |\alpha| \|x\|$ $\forall x \in X$, $\forall \alpha \in \mathbb{R}$ or \mathbb{C}
- 3) $\|x+y\| \leq \|x\| + \|y\|$, $\forall x, y \in X$

Examples: 1) $X = \mathbb{R}^n$, $\| \cdot \|_{\infty}: \mathbb{R}^n \rightarrow \mathbb{R}$ } X -finite
defined as $\|x\|_{\infty} = \max_{1 \leq i \leq n} |x_i|$ } dim

2) Let $C[a, b]$ be the set of all continuous functions mapping $[a, b]$ into \mathbb{R} .
Let $X = C[a, b]$ & $\|x\|_c = \max_{t \in [a, b]} |x(t)|$

Def: A sequence $\{x_i\}$ in a normed linear space $(X, \| \cdot \|)$ is said to be a Cauchy sequence if for every $\epsilon > 0$, $\exists N = N(\epsilon)$ s.t. $\|x_i - x_j\| < \epsilon$ for $i, j > N$.

The set of rational nos (with Euclidean norm) is not complete. e.g. $(1, 1.4, 1.41, 1.414, \dots)$ converges to $\sqrt{2}$, but does not converge in \mathbb{Q} .

Def: A normed linear space $(X, \|\cdot\|)$ is said to be a complete normed linear space or a Banach space if every Cauchy seq. in $(X, \|\cdot\|)$ converges to an element in X .

Ex: $C[a, b]$ with $\|x\|_{\infty} = \max_{t \in [a, b]} |x(t)|$ is a Banach space.

Def: Let $(X, \|\cdot\|_X)$ and $(Y, \|\cdot\|_Y)$ be two normed linear spaces & let $f: X \rightarrow Y$. Then f is said to be continuous at $x_0 \in X$ if for every $\epsilon > 0$ $\exists \delta = \delta(\epsilon, x_0)$ s.t. $\|f(x) - f(x_0)\|_Y < \epsilon$ whenever $\|x - x_0\|_X < \delta$.

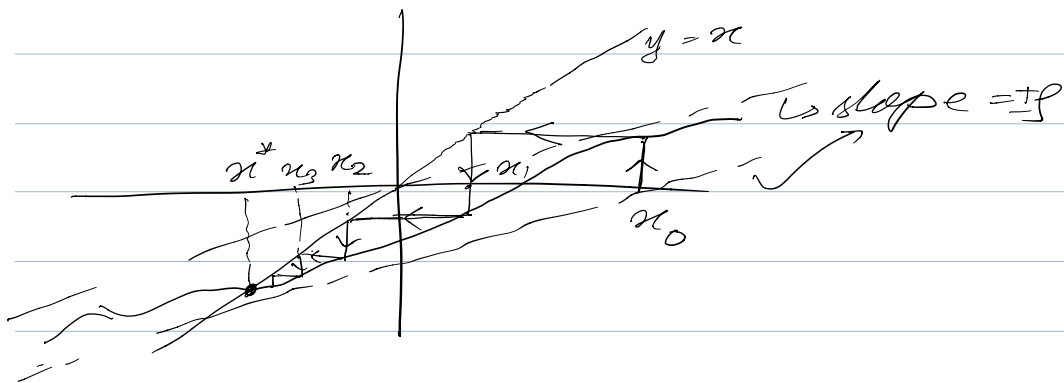
Contraction Mapping Theorem

Thm: Let $(X, \|\cdot\|)$ be a Banach space and let $T: X \rightarrow X$. Let $\exists \rho < 1$ s.t.
 $\|Tx - Ty\| \leq \rho \|x - y\| \quad \forall x, y \in X$

Then \exists exactly one $x^* \in X$ s.t. $Tx^* = x^*$

Moreover for each $x_0 \in X$, the seq. $\{x_n\}$ defined by $x_{n+1} = Tx_n$ converges to x^* .
($x^* \leftarrow$ fixed pt. of the map T .)

Exc: Let $f: \mathbb{R} \rightarrow \mathbb{R}$ be continuously diff.
& let $\sup_{x \in \mathbb{R}} |f'(x)| := \rho < 1$



Local Existence & Uniqueness

① $x' = f(t, x(t))$, $t \geq 0$, $x(0) = x_0$; $x(t) \in \mathbb{R}^n$

$f: \mathbb{R}_+ \times \mathbb{R}^n \rightarrow \mathbb{R}^n$. $t \in [0, T]$ if $x(t)$ is a solⁿ over $[0, T]$

Clearly, ② $x(t) = x_0 + \int_0^t f(\tau, x(\tau)) d\tau$, $t \in [0, T]$

(1) and (2) are \iff equivalent. i.e. every solution of (1) is also a solⁿ of (2) & vice versa.

Thm: Let the function f be continuous in t & x and satisfies: \exists finite constants T, r, h and k such that

$$\|f(t, x) - f(t, y)\| \leq k \|x - y\| \quad \forall x, y \in B$$
$$\forall t \in [0, T]$$

$\|f(t, x_0)\| \leq h \quad \forall t \in [0, T]$ where

$$B = \{x \in \mathbb{R}^n : \|x - x_0\| \leq r\}$$

Then (1) has exactly one solution over $[0, \delta]$ for δ sufficiently small.

Sketch of Proof: Notation:

$\|x(t)\|_c = \max_{t \in [a, b]} \|x(t)\| \rightarrow$ normal Euclidean norm in \mathbb{R}^n

$x(t) \in C^n[0, \delta]$

$x_0(t) := x_0 \quad \forall t \in [a, b]$

Let $S = \{x(\cdot) \in C^n[0, \delta] : \|x(\cdot) - x_0(\cdot)\|_c \leq r\}$

Let P be the map: $C^n[0, \delta] \rightarrow C^n[0, \delta]$

$$(Px)(t) = x_0 + \int_0^t f(\tau, x(\tau)) d\tau \quad \forall t \in [0, \delta]$$

$x(t)$ is a solⁿ of (1) iff $(Px)(\cdot) = x(\cdot)$
 i.e. $x(\cdot)$ is a fixed pt. of P .

$$\begin{aligned} \|(Px)(t) - (Py)(t)\| &= \left\| \int_0^t \{f(\tau, x(\tau)) - f(\tau, y(\tau))\} d\tau \right\| \\ &\leq \int_0^t \|f(\tau, x(\tau)) - f(\tau, y(\tau))\| d\tau \\ &\leq \int_0^t k \|x(\tau) - y(\tau)\| d\tau \end{aligned}$$

$$\leq kt \|x(\cdot) - y(\cdot)\|_c \leq \rho \|x(\cdot) - y(\cdot)\|_c$$

$$\Rightarrow \|(Px)(\cdot) - (Py)(\cdot)\|_c \leq \rho \|x(\cdot) - y(\cdot)\|_c$$

↳ why?

So contraction $\Rightarrow \exists$ unique fixed pt.

Many loose ends in the proof \rightarrow still not be done!

Corollary: For $x = f(t, x)$, ^(*) in some neighborhood of $(0, x_0)$ the function $f(t, x)$ is continuously differentiable. Then (*) has exactly one solution over $[0, \delta]$ provided δ is suff. small.

It might be possible to extend local solutions indefinitely

could repeat some arguments starting at δ .

Corollary: Consider $\dot{x} = f(t, x)$, $x(0) = x_0$ let $f(t, x)$ be continuously differentiable everywhere. Then \exists a unique no. $S_{max} = S_{max}(x_0)$, which could equal infinity, s.t. $(*)$ has a unique solution over $[0, S_{max})$ and over no larger interval. If S_{max} is finite, then $\|x(t)\| \rightarrow \infty$ as $t \rightarrow S_{max}$.

JMP: [half open interval]

Ex: $\dot{x}(t) = 1 + x^2$ $x(0) = 0$ $\rightarrow S_{max} = \frac{\pi}{2}$

$x(t) = \tan t$

As $t \rightarrow \frac{\pi}{2}$, $x(t) \rightarrow \infty$. [Finite escape time]

Global Existence & Uniqueness (without proofs)

Th: Suppose for each $T \in [0, \infty) \exists k_T, h_T < \infty$

s.t. $\|f(t, x) - f(t, y)\| \leq k_T \|x - y\| \quad \forall x, y \in \mathbb{R}^n$

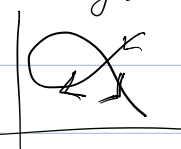
$\|f(t, x_0)\| \leq h_T \quad \forall t \in [0, T] \quad \forall x_0 \in \mathbb{R}^n$

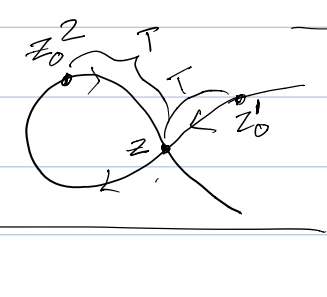
\triangleright Then $(*)$ has exactly one solution over $[0, \infty)$

2) For each $z \in \mathbb{R}^n$ & $T \in [0, \infty)$ \exists exactly one element $z_0 \in \mathbb{R}^n$ s.t. the unique solⁿ:
over $[0, T]$ of $\dot{x} = f(t, x(t))$, $x(0) = z_0$ satisfies $x(T) = z$.

3) Let $T \in [0, \infty)$. For each $\varepsilon > 0$, $\exists \delta(\varepsilon, T) > 0$, s.t. $\left. \begin{array}{l} \|x_0 - y_0\| < \delta(\varepsilon, T) \Rightarrow \|x(\cdot) - y(\cdot)\|_C \leq \varepsilon \\ [x(t) = f(t, x), x(0) = x_0; y(t) = f(t, y), y(0) = y_0] \end{array} \right\} \begin{array}{l} \text{cont.} \\ \text{dep. on} \\ \text{initial} \\ \text{condit.} \end{array}$

To clarify: For autonomous systems, a trajectory which passes through at least one pt. that is not an equilibrium pt. cannot cross itself unless it is a closed curve. In this case it is a periodic solution.

For non-autonomous system, trajectories can intersect \rightarrow  \leftarrow such curves are possible.

Q.  \leftarrow Why does this fig. not contradict (2) of Thom above?

Important Disclaimers

The conditions are sufficient & not necessary

e.g. $\dot{x}(t) = -x^2$ $x(0) = 1$

$$x(t) = \frac{1}{t+1} \leftarrow \text{unique sol}^n \text{ over } [0, \infty)$$

But $f(x) = -x^2$ is not globally Lipschitz cont.

Condition (3) does not guarantee continuous dependence on initial condition of the solⁿ over $[0, \infty)$ \Leftrightarrow Otherwise Lyapunov theory would be redundant. !!
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