

Constrained Optimization

Note Title

27-06-2011

Implicit Function Theorem:

$$f: \underbrace{S}_{\mathbb{R}^{n+k}} \rightarrow \mathbb{R}^n \quad \begin{array}{l} \Delta f = (f_1, \dots, f_n) \\ \Rightarrow S \rightarrow \text{open} \\ \Rightarrow f \text{ has continuous partial} \\ \text{derivatives on } S \end{array}$$

$y = (y_1, \dots, y_k)$
 $x = (x_1, \dots, x_n)$

4) let $(x_0; y_0) \in S$ s.t. $f(x_0; y_0) = 0$

and $\det \begin{bmatrix} \frac{\partial f_1}{\partial x_1} & \dots & \frac{\partial f_1}{\partial x_n} \\ \vdots & & \vdots \\ \frac{\partial f_n}{\partial x_1} & \dots & \frac{\partial f_n}{\partial x_n} \end{bmatrix} \neq 0$

Then, \exists an open set $Y_0 \subset \mathbb{R}^k$ s.t. $y_0 \in Y_0$

and one and only one $g: Y_0 \rightarrow \mathbb{R}^n$ s.t.

1) g has continuous partial derivatives on Y_0

2) $g(y_0) = x_0$

3) $f(g(y), y) = 0 \quad \forall y \in Y_0$

NLS
↓

Problem: $f: X \rightarrow \mathbb{R}$; $g_1(x): X \rightarrow \mathbb{R}$

$$\min_{x \in X} f(x) \quad g_n(x): X \rightarrow \mathbb{R}$$

s.t

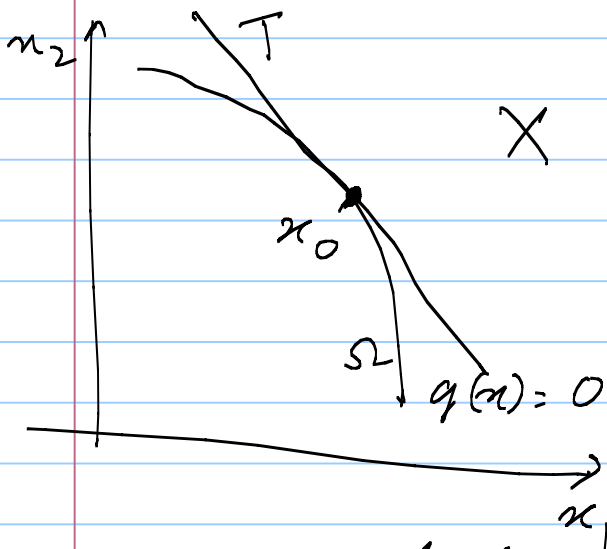
$$g_1(x) = 0$$

$$g_2(x) = 0$$

$$\vdots$$

$$g_n(x) = 0$$

Assumption
 f and g_j are
 Frechet diff
 on X .



$$\Omega = \{x: g_1(x) = \dots = g_n(x) = 0\}$$

If f has an extremum
 along Ω at x_0 it
 also has an extremum
 along T at x_0
 (FOR small displacements)

→ We need to express T as a function of derivatives of $g(x)$

Def: A pt. x_0 satisfying $g_1(x_0) = \dots = g_n(x_0) = 0$ is said to be a regular point of these constraints if the n linear functionals

$g_1'(x_0), g_2'(x_0) \dots g_n'(x_0)$ are linearly independent (Frechet derivatives)

[Recall $g_i'(x_0) = \delta g_i(x_0; h) \in B(X, \mathbb{R})$]

Thm: If x_0 is an extremum of the functional f s.t. the constraints $g_i(x) = 0$, $i=1, 2, \dots, n$ and if x_0 is a regular point of these constraints, then

$$\delta f(x_0; h) = 0$$

for all h satisfying $\delta g_i(x_0; h) = 0$
 $i=1, 2, \dots, n$

Proof: Choose some $h \in X$ satisfying $\delta g_i(x_0; h) = 0$ $i=1, 2, \dots, n$
 $(h \neq 0)$

Let $y_1, y_2, \dots, y_n \in X$ be n lin. ind vectors chosen s.t.

$$M = \begin{bmatrix} \delta g_1(x_0; y_1) & \delta g_1(x_0; y_2) & \dots & \delta g_1(x_0; y_n) \\ \vdots & \vdots & \ddots & \vdots \\ \delta g_n(x_0; y_1) & \delta g_n(x_0; y_2) & \dots & \delta g_n(x_0; y_n) \end{bmatrix}$$

is non-singular

Such (y_1, \dots, y_n) exists since x_0 is regular.

$$\begin{bmatrix} \alpha_1 \delta g_1(x_0; h) + \alpha_2 \delta g_2(x_0; h) + \dots + \alpha_n \delta g_n(x_0; h) = 0 \\ \text{for all } h \in X \end{bmatrix} \Leftrightarrow \alpha_i = 0 \forall i$$

At y_1 , $\alpha_1 \delta g_1(x_0; y_1) + \alpha_2 \delta g_2(x_0; y_1) + \dots + \alpha_n \delta g_n(x_0; y_1) = 0$

$$\vdots$$

$$\text{At } y_n, \alpha_1 \delta g_1(x_0; y_n) + \dots + \alpha_n \delta g_n(x_0; y_n) = 0$$

$$\begin{bmatrix} \delta g_1(x_0; y_1) & \dots & \delta g_n(x_0; y_1) \\ \vdots & & \vdots \\ \delta g_1(x_0; y_n) & \dots & \delta g_n(x_0; y_n) \end{bmatrix} \begin{bmatrix} \alpha_1 \\ \vdots \\ \alpha_n \end{bmatrix} = 0$$

$$\Leftrightarrow \alpha_i = 0$$

Now let $\varepsilon, \phi_1, \phi_2, \dots, \phi_n$ be real scalars and $h \neq 0 \in X$.

$$F_1(\varepsilon, \phi_i) = g_1(x_0 + \varepsilon h + \phi_1 y_1 + \dots + \phi_n y_n)$$

$$F_2 = g_2(x_0 + \varepsilon h + \phi_1 y_1 + \dots + \phi_n y_n)$$

$$F_n(\varepsilon, \phi_i) = g_n(x_0 + \varepsilon h + \phi_1 y_1 + \dots + \phi_n y_n)$$

$$F_i(0, 0) = 0$$

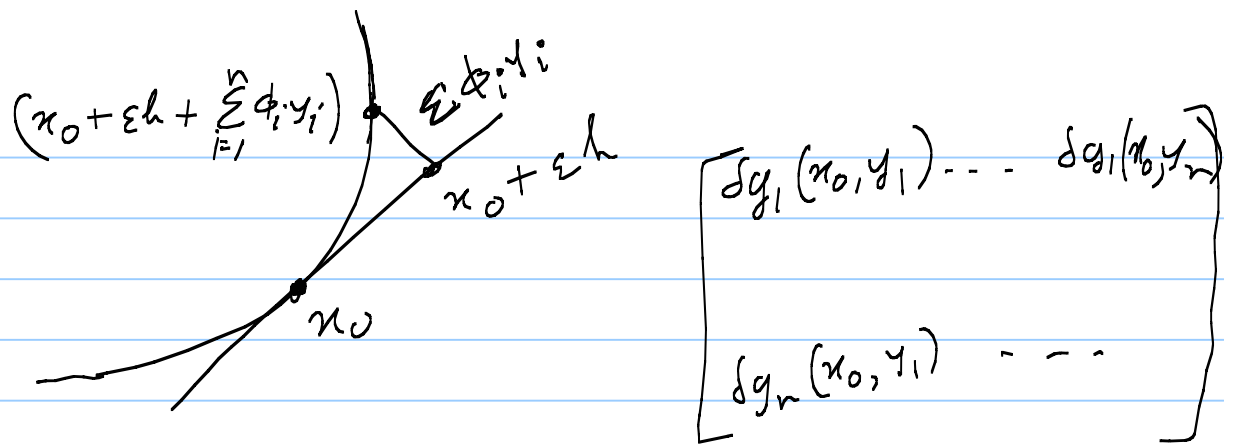
$\frac{\partial F_i}{\partial \phi_j}$ and $\frac{\partial F_i}{\partial \varepsilon}$ exists and are continuous fcn. of (ε, ϕ_i) in some nbd of $(0, 0)$

$\begin{bmatrix} \frac{\partial F_i}{\partial \phi_j} \end{bmatrix}$ has rank n . fcn (ε, ϕ) in some nbd $(0, 0)$

$$\begin{bmatrix} \frac{\partial F_i}{\partial \varepsilon} \end{bmatrix}_{\substack{\varepsilon=0 \\ \phi_i=0}} = 0$$

$$\lim_{\varepsilon \rightarrow 0} \frac{g_1(x_0 + \varepsilon h) - g_1(x_0)}{\varepsilon} = \delta g_1(x_0; h) = 0$$

by hypothesis



Consider the Jacobian //

$$\det \begin{bmatrix} \frac{\partial g_1}{\partial \phi_1} & \frac{\partial g_1}{\partial \phi_2} & \dots & \frac{\partial g_1}{\partial \phi_n} \\ \frac{\partial g_n}{\partial \phi_1} & \dots & \dots & \frac{\partial g_n}{\partial \phi_n} \end{bmatrix}_{\epsilon=0, \phi=0} = \det M \neq 0$$

Hence by implicit function thm:
 \exists n functions

$$\phi_i = \phi_i(\epsilon)$$

defined in some nbd of $\epsilon = 0$.

satisfying, for each i ,

$$1) 0 = g_i \left(x_0 + \epsilon h + \sum_{j=1}^n \phi_j(\epsilon) y_j \right) - \text{(*)}$$

2) Also $\phi_i(0) = 0$ and
 Each $\phi_i(\epsilon)$ is continuously diff.
 in a nbd of $\epsilon = 0$.

3) Moreover, since $\frac{\partial F_i}{\partial \epsilon}(0, 0) = 0 \quad \forall i=1, \dots, p$
 $\Rightarrow \phi_i'(0) = 0 \quad \forall i=1, \dots, p$

$$\left[\begin{array}{l} \text{Proof: } \phi_i(\varepsilon) = \varepsilon \phi_i'(\theta \varepsilon) \\ \lim_{\varepsilon \rightarrow 0} \frac{\phi_i(\varepsilon)}{\varepsilon} = \phi_i'(0) = 0 \end{array} \quad \begin{array}{l} 0 < \theta < 1 \\ \varepsilon \text{ small enough} \end{array} \right]$$

Now by (*),

$$\left(x_0 + \varepsilon h + \sum_{j=1}^n \phi_j(\varepsilon) y_j \right) \in \text{the constraint set}$$

$$\begin{aligned} & f\left(x_0 + \varepsilon h + \sum_{j=1}^n \phi_j(\varepsilon) y_j\right) - f(x_0) \\ &= \varepsilon \left[\sum_{j=1}^n \delta f(x_0; y_j) \phi_j'(0) + \delta f(x_0; h) + o(\varepsilon) \right] \end{aligned}$$

$$= \varepsilon \left[\delta f(x_0; h) + o(\varepsilon) \right]$$

$$\text{If } \delta f(x_0; h) = -a^2 \neq 0, \quad \varepsilon > 0 \quad \text{produce contra.}$$

$$\delta f(x_0; h) = +a^2 \neq 0, \quad \varepsilon < 0 \quad \text{"}$$

$$\text{Hence } \delta f(x_0; h) = 0.$$

Lemma: Let f_0, f_1, \dots, f_n be linearly ind. linear functionals on X (NLS) s.t.

For any x satisfying $f_i(x) = 0, (i=1, \dots, n)$
 $f_0(x) = 0.$

Then $\exists \lambda_1, \dots, \lambda_n$ in \mathbb{R} s.t.

$$f_0 + \lambda_1 f_1 + \dots + \lambda_n f_n = 0$$

Proof: Consider $S = \left\{ \begin{array}{l} (f_1(x), f_2(x), \dots, f_n(x)) \\ : x \in X \end{array} \right\}$
 S is a subspace of E^n

Thm: If x_0 is an extremum of the functional f s.t. the constraints

$$g_i(x) = 0 \quad i=1, 2, \dots, n$$

and x_0 is a regular pt. of these constraints, then $\exists \lambda_1, \dots, \lambda_n$ s.t.

$f(x) + \sum_{i=1}^n \lambda_i g_i(x)$
 is stationary at x_0 .

Proof: By last th $\delta f(x_0; h) = 0$ for every h satisfying $\delta g_i(x_0; h) = 0$
 $(i=1, \dots, n)$