

sop_6_6.xbe

Attributes

```
xbe name=sop_6_6 evaluate=yes allow_elex=yes
Jacobian: variable
input_vars: x1 x2 x3 x4 x5 x6
output_vars: y
aux_vars:
iparms:
+ k11=0 k12=0 k13=0 k14=0 k15=0 k16=0
+ k21=0 k22=0 k23=0 k24=0 k25=0 k26=0
+ k31=0 k32=0 k33=0 k34=0 k35=0 k36=0
+ k41=0 k42=0 k43=0 k44=0 k45=0 k46=0
+ k51=0 k52=0 k53=0 k54=0 k55=0 k56=0
+ k61=0 k62=0 k63=0 k64=0 k65=0 k66=0
sparms:
rparms:
+ k1=0 k2=0 k3=0 k4=0 k5=0 k6=0
+ k0=0
stparms:
igparms:
outparms: x1 x2 x3 x4 x5 x6 y
```

Description

sop_6_6.xbe is used to get a sum-of-products expression for output y in terms of inputs x1, x2, x3, x4, x5, x6. y is given by

$$y = k_0 + k_1 p_1 + k_2 p_2 + k_3 p_3 + k_4 p_4 + k_5 p_5 + k_6 p_6, \quad (1)$$

where p_j is $x_1, x_2, x_3, x_4, x_1 x_2, x_1 x_3, x_2 x_3$, etc., depending on the integer parameters $k_{j1}, k_{j2}, k_{j3}, k_{j4}, k_{j5}, k_{j6}$. For example, if $k_{11} = 0, k_{12} = 1, k_{13} = 1, k_{14} = 1, k_{15} = 0, k_{16} = 1$, then $p_1 = x_2 x_3 x_4 x_6$.

x1, x2, x3, x4, x5, x6, y are made available as output variables.