Eigenvalue Decomposition based Acoustic Source Localization

Anish Patankar (06307914) B.V.R.Samir (06307917)

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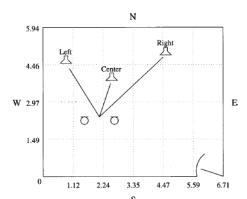
Problem Description and Setup

- Solution
 - Introduction
 - Adaptive Algorithm

3 References

Objective and Setup

- Objective: To determine the location of acoustic signal source, i.e. TDE(Time Delay Estimation) given the observations and positions of microphones.
- Setup: Number of microphones depends on the dimension of the intended localization.



Introduction

- Models
 - Ideal Model

$$x_i(n) = \alpha_i s(n - \tau_i) + b_i(n)$$

Real Model

$$x_i(n) = g_i * s(n) + b_i(n)$$

GCC(Generalized Cross-Correlation)

Adaptive Algorithm

- Define **u** as $[\mathbf{g}_2, -\mathbf{g}_1]^T$, and **R** as covariance matrix of microphone signals, x_1 and x_2
- Minimize u^TRu to obtain minimum eigenvalue with corresponding eigenvector as u using LMS algorithm,

$$\mathbf{u}(n+1) = \mathbf{u}(n) - \mu e(n) \nabla e(n)$$

where,

$$e(n) = \frac{\mathbf{u}^{T}(n)\mathbf{x}(n)}{\|\mathbf{u}(n)\|}$$

 Estimate Time Delay from eigen vector or impulse responses vector u

- J. Benesty, 'Adaptive Eigenvalue Decomposition Algorithm for Passive Acoustic Source Localization', Bell Labs Tech. Memo., 1998.
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