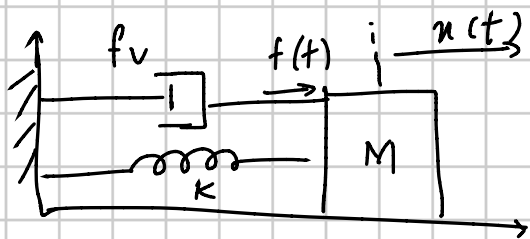


01)



input = Force

output = Displacement

$$f(t) = f_v \dot{x}(t) + kx(t) + M\ddot{x}(t) \rightarrow (1)$$

$$F(s) = f_v s X(s) + k X(s) + Ms^2 X(s)$$

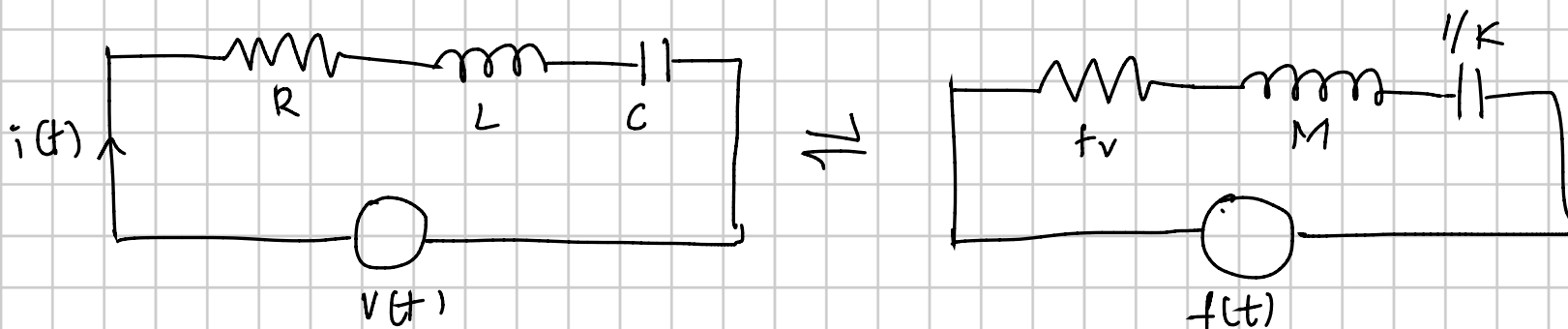
$$\frac{X(s)}{F(s)} = \frac{1}{Ms^2 + f_v s + k}$$

Force - voltage ; current - velocity:
 $f(t) - v(t) \quad i(t) - \dot{x}(t)$

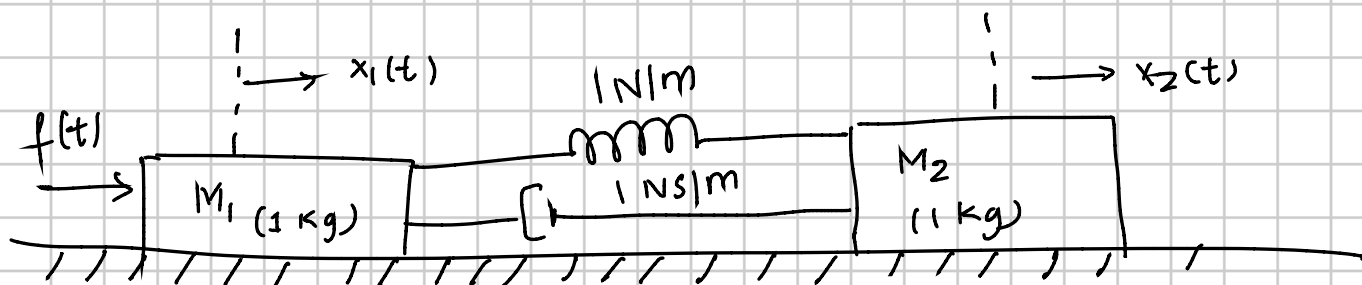
(1) beweis:

$$v(t) = f_v i(t) + k \int i(t) dt + M \frac{di(t)}{dt}$$

$$v(t) = R i(t) + \frac{1}{C} \int i dt + L \frac{di}{dt}$$



02)



i/p = $f(t)$
 o/p = $x_2(t)$

$B = 1$
 $k = 1$

For M_1 :

$$f(t) = M_1 \ddot{x}_1(t) + [\dot{x}_1(t) - \dot{x}_2(t)] + [x_1(t) - x_2(t)]$$

For M_2 :

$$0 = M_2 \ddot{x}_2(t) + (\dot{x}_2(t) - \dot{x}_1(t)) + [x_2(t) - x_1(t)]$$

$$F(s) = M_1 s^2 x_1(s) + s x_1(s) - s x_2(s) + x_1(s) - x_2(s)$$

$$F(s) = [M_1 s^2 + s + 1] x_1(s) - (s + 1) x_2(s)$$

$$0 = M_2 s^2 x_2(s) + s x_2(s) - s x_1(s) + x_2(s) - x_1(s)$$

$$0 = [M_2 s^2 + s + 1] x_2(s) - (s + 1) x_1(s)$$

$$x_1(s) = \frac{(M_2 s^2 + s + 1)}{s + 1} x_2(s)$$

$$F(s) = \left((M_1 s^2 + s + 1) \frac{(M_2 s^2 + s + 1)}{(s + 1)} \right) x_2(s) - (s + 1) x_2(s)$$

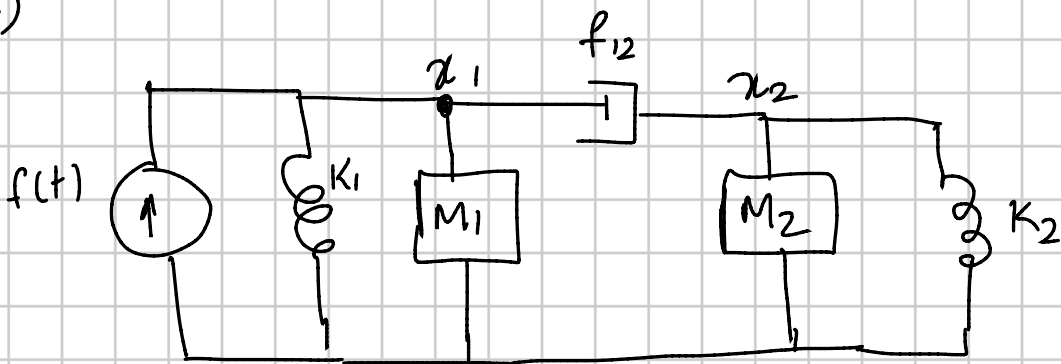
$$= \frac{x_2(s)}{(s + 1)} \left(M_1 M_2 s^4 + M_1 s^3 + M_1 s^2 + M_2 s^3 + s^2 + s + M_2 s^2 + s + 1 - (s + 1)^2 \right)$$

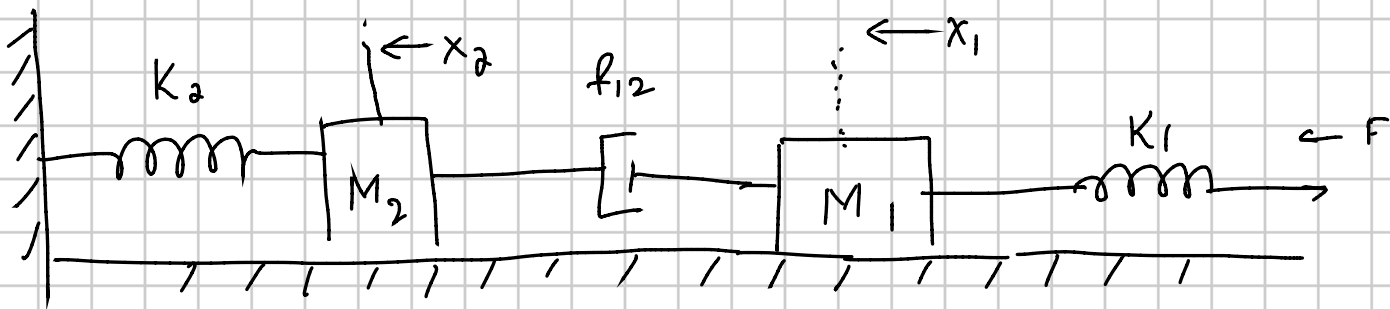
$$= \frac{x_2(s)}{(s + 1)} \left[M_1 M_2 s^4 + s^2 (M_1 s + M_1 + M_2 s + M_2) + s^2 + 2s + 1 - (s + 1)^2 \right]$$

$$\boxed{\begin{matrix} M_1 = 1 \\ M_2 = 1 \end{matrix}} = \frac{x_2(s)}{(s + 1)} \left[M_1 M_2 s^4 + s^2 (M_1 + M_2)(s + 1) + (s + 1)^2 - (s + 1)^2 \right]$$

$$\boxed{\frac{x_2(s)}{F(s)} = \frac{s + 1}{s^4 + 2s^3 + 2s^2}}$$

03)





→ For M_1 :

$$F(t) = M_1 \ddot{x}_1(t) + f_{12}(\dot{x}_1(t) - \dot{x}_2(t)) + K_1 x_1$$

For M_2 :

$$0 = M_2 \ddot{x}_2(t) + f_{12}(\dot{x}_2(t) - \dot{x}_1(t)) + K_2 x_2$$

(a) Voltage as a source

Voltage = Force.

Both equations become

$$V = V_R + V_L + V_C$$

$$V = IR + L \frac{dI}{dt} + \frac{1}{C} \int I dt$$

$$I = \frac{dq}{dt}$$

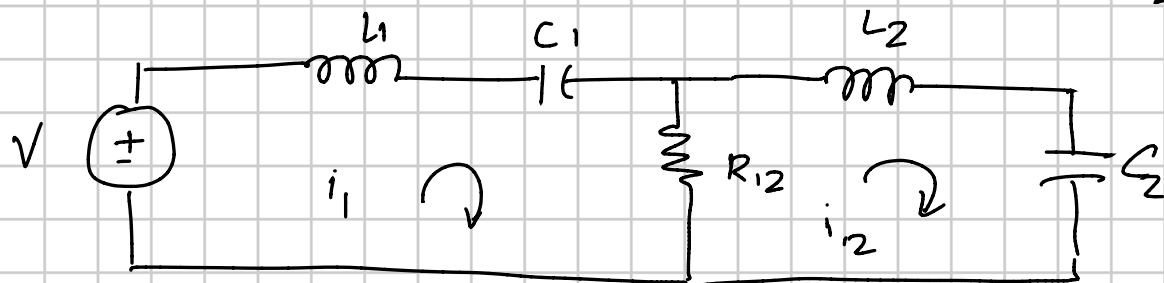
$$V = R \frac{dq}{dt} + L \frac{d^2 q}{dt^2} + \frac{q}{C}$$

$$V(s) = sRQ + s^2 LQ + \frac{Q}{C}$$

$$M \rightarrow L ; R \rightarrow R ; K \rightarrow 1/C$$

$$V(t) = L_1 \dot{i}_1(t) + R_{12} [i_1(t) - i_2(t)] + \frac{1}{C_1} \int i_1 dt$$

$$0 = L_2 \dot{i}_2(t) + R_{12} [i_2(t) - i_1(t)] + \frac{1}{C_2} \int i_2 dt$$



(b) current as source

$$\bar{I} = I_R + I_L + I_C$$

$$I = \frac{V}{R} + \frac{1}{L} \int V dt + C \frac{dV}{dt}$$

$$V = \frac{d\phi}{dt}$$

$$\bar{I} = \frac{1}{R} \frac{d\phi}{dt} + \frac{1}{L} \phi + C \frac{d^2\phi}{dt^2}$$

$$\bar{I}(s) = \frac{s}{R} \phi(s) + \frac{\phi}{L} + s^2 C \phi$$

$$I = C s^2 \phi + \frac{1}{R} s \phi + \frac{1}{L} \phi$$

$$M \rightarrow C; \quad B \rightarrow \frac{1}{R}; \quad K \rightarrow \frac{1}{L}$$

$$I = C_1 \frac{dV_1}{dt} + \frac{V_1 - V_2}{R_{12}} + \frac{1}{L_1} \int V_1 dt$$

$$0 = C_2 \frac{dV_2}{dt} + \frac{V_1 - V_2}{R_{12}} + \frac{1}{L_2} \int V_2 dt$$

