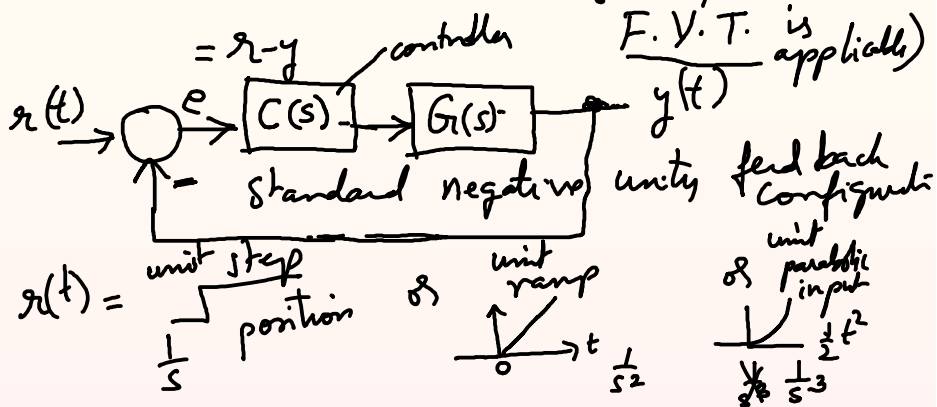


Steady state error analysis

(assuming steady state "exists", i.e. stability of

F.V.T. is applicable)



$$\frac{Y(s)}{R(s)} = \frac{C(s)G(s)}{1 + C(s)G(s)}$$

$$\lambda \rightarrow e$$

$$\frac{E(s)}{R(s)} = \frac{1}{1 + G(s)G(s)}$$

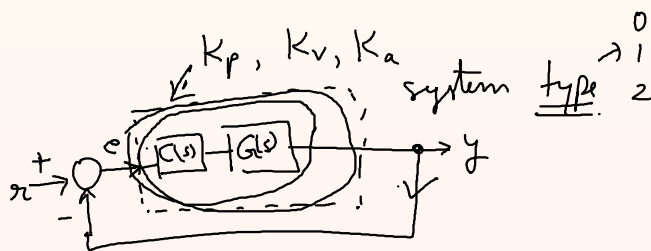
$e(\infty)$ for $r(t) = \text{unit step} \rightarrow R(s) = \frac{1}{s}$
 (assuming limit exists)

$$e(\infty) = \frac{1}{1 + C(0)G(0)}$$

$$K_p = \lim_{s \rightarrow 0} C(s) G(s) \quad \text{position constant}$$

$$K_v = \lim_{s \rightarrow 0} s C(s) G(s) \quad \text{velocity constant}$$

$$K_a = \lim_{s \rightarrow 0} s^2 C(s) G(s) \quad \text{acceleration constant}$$



$$\leftarrow C(s)=1$$

$$C(s)G(s) = \frac{n(s)}{d(s)} = \frac{\tilde{n}(s)}{s^n \tilde{d}(s)}$$

$n=0 \rightarrow$ system is type 0 $\tilde{n}(0) \neq 0$
 $\tilde{d}(0) \neq 0$

$n=1 \rightarrow$ system is type 1

$n=2 \rightarrow$ system is type 2.

$r(t) \rightarrow$ unit step
 ramp
 parabolic

for $r(t)$	Type 0	Type 1	Type 2
step input	K_p is (non-zero) constant $\frac{1}{1+K_p}$	$K_p = \infty$ $e(\infty) = 0$	$e(\infty) = \infty$ $e(\infty) = \infty$
Ramp input	$K_v = 0$ ∞	K_v is constant $\frac{1}{K_v}$	∞ $e(\infty) = 0$
parabolic input $\cdot K_a \Rightarrow$	∞	$K_a = 0$ ∞	∞ $K_a = \text{const}$ $\frac{1}{K_a}$
error as $t \rightarrow \infty$ using F.V.T. applicable.			



$$G(s) = \frac{1}{s(s+3)} \rightarrow K_p = \frac{1}{3} \text{ type } \underline{1}$$

$$r = \frac{1}{s} \text{ unit step}$$

$$\underline{E(s)} = \frac{1}{1+G(s)}$$

$\lim_{s \rightarrow 0} \frac{1}{1+K_p} \rightarrow$
 \rightarrow zeros are in OLHP
 closed loop poles are in OLHP

$e(\infty)$ (for ramp).

$$E(s) = \lim_{s \rightarrow 0} \frac{1}{1+G(s)} \times \frac{1}{s^2} \leftarrow \text{ramp}$$

$$\frac{1}{s(1 + \frac{1}{s(s+3)})} = \frac{1}{s + \frac{1}{s+3}} = \frac{s+3}{s^2+3s+1}$$

$e(\infty)$ for unit step
 $\lim_{s \rightarrow 0}$

$$\frac{s}{1+G(s)} \times \frac{1}{s} \leftarrow \text{unit step}$$
$$= \lim_{s \rightarrow 0} \frac{g(s+3)}{s^2+3s+1} = 0$$

closed loop stable. n

ramp. $3 \left(\frac{1}{K_v} \right)$