

Assignment 4: Hints

Qn 1 Either use Laplace inverse of $(sI - A)^{-1}$ to determine e^{At} and replace $t = 1$, or use the Cayley-Hamilton based method discussed during class interaction to infer that options (a) & (b) are the correct answers.

Qn 2 Obtain $C(sI - A)^{-1}B$ to see that the transfer $f(s)$ has one pole. (indicating pole-zero cancellation) This rules out options (a) & (b). It is straightforward to see that (c) & (d) are true.

Qn 3 It is a 2×2 system. Recall that $\det(A) = \text{product of eigenvalues} = \lambda_1 \lambda_2$. Similarly, $\text{trace}(A) = \text{sum of eigenvalues} = \lambda_1 + \lambda_2$ [Even if you do not recall this you should be still able to derive this: Take $A = \begin{bmatrix} a & b \\ c & d \end{bmatrix}$; $|(\lambda I - A)| = \begin{vmatrix} \lambda - a & -b \\ -c & \lambda - d \end{vmatrix} = (\lambda - a)(\lambda - d) - bc$
 $= \lambda^2 - (a+d)\lambda + ad - bc$
 $= \lambda^2 - \text{tr}(A) \cdot \lambda + \det(A)$]

However, this result is true, in general, for any $n \times n$ matrix, i.e. $\text{tr}(A) = \sum \text{eigenvalues}$ & $\det(A) = \prod \text{eigenvalues}$

Clearly, $\lambda_1 \lambda_2 < 0$, implies λ_1, λ_2 are real since for complex eigenvalues, they appear in conj. pairs so

$$\lambda_1 = p + jq \text{ \& } \lambda_2 = p - jq \Rightarrow \lambda_1 \lambda_2 = p^2 + q^2 > 0.$$

Also $\text{sgn}(\lambda_1) = -\text{sgn}(\lambda_2)$. Hence, (a) is true.

(b) is ruled out similarly.

→ Recall from (a) that $\lambda = \frac{\gamma \pm \sqrt{\gamma^2 - 4\delta}}{2}$

$$\delta > 0 \Rightarrow \gamma^2 - 4\delta < \gamma^2$$

$$\Rightarrow |\gamma| > \sqrt{\gamma^2 - 4\delta}$$

$$\text{Moreover, } \gamma < 0 \Rightarrow \lambda = \frac{\gamma \pm \sqrt{\gamma^2 - 4\delta}}{2} < 0 \Rightarrow \text{stable.}$$

Further, for $\gamma > 0$, $\lambda = \frac{\gamma \pm \sqrt{\gamma^2 - 4\delta}}{2} > 0$.

~~So~~

$\Rightarrow$ instability

So (c) is true.

If $\delta > 0$ then $\gamma = 0$, $\lambda = \pm j\sqrt{\delta}$

$\Rightarrow$ imaginary eigenvalues

$\Rightarrow$ marginally stable system

$\Rightarrow$ oscillatory ~~response~~ response to non-zero initial conditions

[Recall: $x(t) = e^{At}x_0$ & e^{At} will contain pure undamped sines/cosines].

Hence, (d) is also true.

Qn 4 > Write down the op of every integrator as a state. readily follows that the parallel realization corresponds to the diagonal ~~state~~ A matrix.

Others can be seen similarly too.

It follows that (i) & (v) are the correct matches.

Qn 5 > Asymptotic stability can be readily checked by obtaining eigenvalues and ascertaining if they are all in the open left half plane (excludes imaginary axis) or not.

Turns out the (iii) is true.

For ~~system~~ $(A) \& (B)$

$$|(\lambda I - A)| = \begin{vmatrix} \lambda & -1 \\ -1 & \lambda \end{vmatrix} = \lambda^2 - 1$$

$\Rightarrow$ eigenvalues = 1, -1.

distinct ~~real~~ real eigenvalues! Hence diagonalizable.

For (C) it follows that eigenvalues are imaginary. So cannot be diagonalised over the real field.

For (D), again eigenvalues are a complex conjugate pair. So, not diagonalizable over the reals.

Thus, (iv) is true. & (v) is not

(vi) is not true since A^T is not the same for (C) & (D) as D is asymptotically stable while (C) is not

Check $\mathcal{L}(AB) = \begin{bmatrix} B & AB \end{bmatrix}$ for (A)

$$= \begin{bmatrix} 1 & 1 \\ 1 & 1 \end{bmatrix}$$

This is not invertible, so both poles cannot be placed. None of the original poles is at -2 or -3 . So cannot be placed (vii) is not true.

By the same token, $\mathcal{L}(A^T B)$ is invertible for (B), (C) & (D). So poles can be arbitrarily placed. Thus, (viii), (ix) & (x) are true.

(A) & (B) have the same eigenvalues and are both diagonalizable (since (iv) is true above). Thus we have

for (A) $T_1^{-1} A_1 T_1 = D \rightarrow \text{diag matrix.}$

& for (B) $T_2^{-1} A_2 T_2 = D \rightarrow \text{same diag. matrix.}$

$$= T_1^{-1} A_1 T_1$$

$$\Rightarrow A_2 = T_2 T_2^{-1} A_1 T_1 T_2^{-1}$$

$$\text{Let } T = T_1 T_2^{-1}$$

$$\therefore A_2 = T^{-1} A_1 T.$$

But for a similarity transform, we must also have.

the same transfer fn. Check to see that $C(sI-A)^{-1}B$ does not match in the two systems
Hence (xi) is not true

(xii) is also not true since the eigenvalues of the system matrices do not match.

Qn 6

$[B \ AB]$ is not invertible, ^(check!) so both poles cannot be placed arbitrarily. Original poles are not at $-2, -3$. So (a) is not true.

Due to same reason, (b) is true
check to see that

$$A+BF = \begin{bmatrix} 2 & 1 \\ 0 & 3 \end{bmatrix} + \begin{bmatrix} 5 \\ 0 \end{bmatrix} \begin{bmatrix} f_1 & f_2 \end{bmatrix}$$

$$= \begin{bmatrix} 2+5f_1 & 3f_2+1 \\ 0 & 3 \end{bmatrix}$$

Since $A+BF$ is a matrix, closed loop poles are at $2+5f_1$ & 3 .

Choosing $f_1 = -4/5$ and $f_2 = \text{any real no.}$
we can place poles at $(-2, 3)$.

Hence, (c) is non-unique. Option (c) is true.
By same reasoning, there exists a non-unique feedback, $F = \begin{bmatrix} -1 & f_2 \end{bmatrix}$ (f_2 is any real no.) to place poles at $(-3, 3)$. Hence (d) is not true.

Qn 7 Clearly (a) is false. & (b) is true.

Take $C(sI-A)^{-1}B$ with $C = \begin{bmatrix} c_1 & c_2 \end{bmatrix}$

$$(sI-A)^{-1}B = \begin{pmatrix} s-2 & -1 \\ 0 & s-3 \end{pmatrix}^{-1} \begin{bmatrix} 5 \\ 0 \end{bmatrix} = \frac{1}{(s-2)(s-3)} \begin{bmatrix} s-3 & 1 \\ 0 & s-2 \end{bmatrix} \begin{bmatrix} 5 \\ 0 \end{bmatrix}$$

$$= \begin{bmatrix} \frac{5}{s-2} \\ 0 \end{bmatrix}$$

For arbitrary c_1, c_2 , $G(s) = \frac{5c_1}{s^2}$
 thus the pole at ~~0~~ 3 has been cancelled.
 so (c) is true.

Q. 8

Since both poles of the t.o. p_0 are at 0, both eigenvalues of the SSR will be at 0.

Thus, A matrix can either be of rank 1 or rank 0 (zero matrix).

Suppose it is the zero matrix.

Then $(sI - A)^{-1} = \begin{pmatrix} s & 0 \\ 0 & s \end{pmatrix}^{-1} = \frac{1}{s^2} \begin{pmatrix} s & 0 \\ 0 & s \end{pmatrix}$
 $= \begin{pmatrix} \frac{1}{s} & 0 \\ 0 & \frac{1}{s} \end{pmatrix}$

There is no way that this can lead to a t.f of $\frac{1}{s^2}$ for any $B = \begin{bmatrix} b_1 \\ b_2 \end{bmatrix}$ and $C = [c_1 \ c_2]$

A must have rank 1, but not rank 2 (since its eigenvalues are at 0, so it is singular).

Hence, option (b) is true.

If A is diagonalizable, we will again land up with the zero matrix & the transfer fns for the diagonal system cannot be $\frac{1}{s^2}$. But for diagonalizable systems (diagonalized

through similarity transforms), eigenvalue transfer fns are invariant. Hence, (c) is true.

Suppose $A = \begin{bmatrix} 0 & 1 \\ 0 & 0 \end{bmatrix}$; $B = \begin{bmatrix} 1 \\ 0 \end{bmatrix}$; $C(A, B) = \begin{bmatrix} 1 & 0 \\ 0 & 0 \end{bmatrix}$

so $(sI - A)^{-1} = \frac{1}{s^2} \begin{bmatrix} s & 1 \\ 0 & s \end{bmatrix}$ not invertible!

so (d) is not true.

Q.9 (a) Take the case when $a_i \neq 0 \forall i=0, 1, 2, \dots, n-1$.
 A has all its eigenvalues at 0. (check!).

~~Suppose~~ Suppose it is diagonalizable. Then $T^{-1}AT = O_{n \times n}$ (zero matrix)
 But this would lead to $A = T O_{n \times n} T^{-1} = 0$ (contradiction).

Hence (a) is not true.

(b) Check to see that $[B \ AB \ A^2B \ \dots \ A^{n-1}B]$

$$= \begin{bmatrix} 0 & 0 & 0 & \dots & 1 \\ 0 & 0 & 1 & \dots & 0 \\ 0 & 1 & -a_{n-1} & \dots & 0 \\ \vdots & \vdots & \vdots & \ddots & \vdots \\ 1 & -a_{n-1} & (-a_{n-2} + a_{n-1}a_{n-1}) & \dots & 0 \end{bmatrix}$$

which clearly has full rank (why?) Hint: consider rows and see that they are always linearly independent. Thus, (b) is true.

(c) straightforward calculation of $|sI - A|$ yields that (c) is true.

(d) $A + BF = A + \begin{bmatrix} 0 & 0 & \dots & 0 \\ f_0 & f_1 & \dots & f_{n-1} \end{bmatrix}$ where $F = [f_0 \ f_1 \ \dots \ f_{n-1}]$

$$\therefore A + BF = \begin{bmatrix} 0 & 1 & 0 & \dots & 0 \\ 0 & 0 & 1 & \dots & 0 \\ \vdots & \vdots & \vdots & \ddots & \vdots \\ 0 & 0 & 0 & \dots & 1 \\ f_0 + a_0 & f_1 + a_1 & \dots & f_{n-1} + a_{n-1} \end{bmatrix}$$

clearly, choosing f_i such that $f_i + a_i = -d_i$

$\Rightarrow f_i = -a_i - d_i$ yields

Closed loop char. eqn $s^n + d_{n-1}s^{n-1} + \dots + d_1s + d_0$

Thus, (d) is true.