

Tutorial Sheet EE640 Multivariable Control, 7th Oct 2024
 Attempt/Read all questions before tutorial.

Q-1: Use $(I-P)^{-1} = I + P + P^2 + P^3 + \dots$ (as found power series
 (i.e. without bother about convergence))
 to get $\frac{CB}{s} + \frac{CAB}{s^2} + \frac{CA^2B}{s^3} + \dots = C(sI-A)^{-1}B$ ($sI-A = s(I-\frac{A}{s})$)

Q-2: Just like for a biproper transfor, d can be got
 as just ratio of leading terms, check that Markov parameters h_i
 of $G(s) = \frac{6s^2 + 3s + 2}{s^2 - 9s - 1}$ $\rightarrow h_0 = 6$, $h_1 = \lim_{s \rightarrow \infty} s(G(s) - 6)$
 $h_2 = \lim_{s \rightarrow \infty} s(s(G(s) - 6) - h_1)$
 (This is same as long division). \therefore

Q-3: Check that the Markov parameters do not change with
 $A \rightarrow T^{-1}AT$, $B \rightarrow T^{-1}B$, $C \rightarrow CT$, $D \rightarrow D$.

Q-4: Show that $(sI-A)^{-1}$ is strictly proper and where all
 the rel-deg 1 entries & rel-deg ≥ 2 entries (in $(sI-A)^{-1}$)?

Q-5: Consider controller canonical form for A & $b = e_n$.
 Obtain (by adjugate/co-factor method) just $(sI-A)^{-1}b$ as $\begin{bmatrix} ? \\ \vdots \end{bmatrix}$
 Compare relative degrees of $u \rightarrow x_1 \rightarrow x_2 \rightarrow x_3$ w.r.t. the

block diagram of controller canonical form $(\xrightarrow{u} \oplus \xrightarrow{\cdot} [s] \xrightarrow{\cdot} [s] \xrightarrow{\cdot} j \cdot j')$

Q-6: Suppose relative deg of a
 strictly proper $G(s) = 7$, then
 deduce $\forall h_i = 0$ for $i = 0, 1, \dots$? • What about converse?
 (Markov parameters).

Q-7: Prove $\Lambda_{un}(A, B) = \Lambda_0(A + BF)$ (where F is varied on $\mathbb{R}^{m \times n}$).
 Also obtain how many initial derivatives = 0 for step response.
 $B \in \mathbb{R}^{n \times m}$. $F \uparrow \sigma = \text{spectrum} \equiv \text{set of eigenvalues.}$

What if an eigenvalue λ is repeated & "both" controllable &
 uncontrollable?
 (#7: For simplicity, assume distinct eigenvalues of A &

Q-8: Let $A = \begin{bmatrix} 1 & -1 \\ 1 & 1 \end{bmatrix}$, $C = \begin{bmatrix} 2 & 3 \end{bmatrix}$. $x(0)$ = unknown.
 Check observability of matrix & its inverse Θ^{-1} .
 ~ use Θ^{-1} to get $x(0)$ from $\begin{bmatrix} y(0) \\ y(0) \end{bmatrix}$

Q-9: Assume (only in this exercise) that B is not full column rank. Show that $B \in \mathbb{R}^{n \times m}$, & suppose B has rank only σ & $\sigma < m$. Then $\lambda_m = 0, \lambda_{m-1} = 0, \dots, \lambda_{m-\sigma+1} = 0$ (λ_i = controllability indices). \uparrow kappa.

~~B~~ - Thus prove that $\lambda_i \geq 1 \Leftrightarrow B$ is full column rank. (for all i)

Q-10: Let B be f.c.r. and (A, B) controllable.

For each condition below, construct (if possible/exists)

A, B satisfying that condition

(a) all $\lambda_i = 2, m = 3, n = ?$

(b) $\lambda_1 = 2, \lambda_2 = 1, A$ is cyclic.

(c) $(\lambda_1, \lambda_2, \lambda_3) = (3, 2, 1), A$ is not cyclic.

(d) ———, A is of size 5

(e) ———, A is of size 7

(f) $(\lambda_1, \lambda_2, \lambda_3) = (1, 1, 1), A$ is of size ?

Q-11: Consider the Lyapunov operator $L_A: P \rightarrow A^T P + PA$

$L_A: \mathbb{R}^{n \times n} \rightarrow \mathbb{R}^{n \times n}$ with $P, A \in \mathbb{R}^{n \times n}$.

Assume A has all real & distinct eigenvalues and for each eigenvalue λ_i , let v_i^L, v_i^R denote left & right eigenvectors.

(a) Verify that ~~v_i^L~~ ~~v_i^R~~ is an eigenvector of A .

$p_{ij} := v_i^L (v_j^L)^T$ ~~$v_i^L (v_j^R)^T$~~ is an eigenvector

is an eigenvector.

(b) what is corresponding eigenvalue?

(c) Is # of eigenvalues = dimension of $\mathbb{R}^{n \times n}$?

(d) Find an $A \rightarrow$ singular

such that L_A is a singular operator,

→ non-singular

→ Hermitian & find matrix P in its nullspace

(e) Assume $P = v_i^L (v_j^L)^T + v_j^L (v_i^L)^T$ to get P symmetric.

& check $A^T P + PA$ also is symmetric.

(f) What is the dimension of symmetric $n \times n$ matrices? Do eigenvalue count add up?

(If you prefer, for simplicity, assume A is symmetric for all Q-11 a-f (thus not worrying about left/right eigenvectors.)