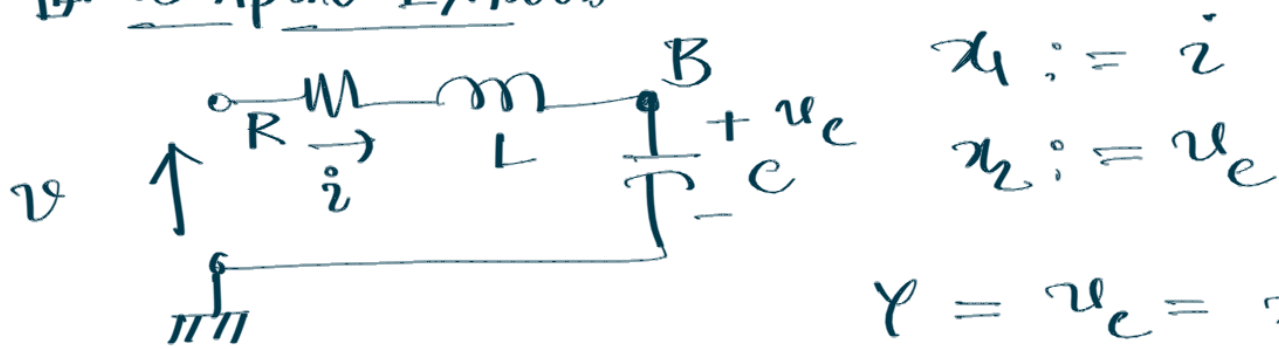


Q13 April Extra:



$$\dot{x}_2 = \dot{v}_c = \frac{1}{C} i = \frac{1}{C} x_1 \quad (\text{KCL @ node B})$$

$$\dot{x}_1 = \frac{di}{dt} = \frac{1}{L} [-v_c - iR] + \frac{v}{L}$$

$$= -\frac{1}{L} x_2 - \frac{R}{L} x_1 + \frac{v}{L}$$

$$\begin{bmatrix} \dot{x}_1 \\ \dot{x}_2 \end{bmatrix} = \begin{bmatrix} -\frac{R}{L} & -\frac{1}{L} \\ \frac{1}{C} & 0 \end{bmatrix} \begin{bmatrix} x_1 \\ x_2 \end{bmatrix} + \begin{bmatrix} \frac{1}{L} \\ 0 \end{bmatrix} v$$

$$y = \begin{bmatrix} 0 & 1 \end{bmatrix} \begin{bmatrix} x_1 \\ x_2 \end{bmatrix}$$

SS model for the speaker system.

- Solutions: (ZIS)

$$\dot{x} = Ax; \quad x(0) = \underbrace{x_0}_{\text{Initial cond.}} \in \mathbb{R}^n$$

$$x(t) = e^{At} x_0$$

$$e^{At} := I + At + \frac{A^2 t^2}{2!} + \frac{A^3 t^3}{3!} + \dots$$

$$e^{At} x_0 = x_0 + t \underline{A} x_0 + \frac{t^2}{2!} A^2 x_0 + \frac{t^3}{3!} A^3 x_0 + \dots$$

$$\frac{d}{dt} (e^{At} x_0) = 0 + \underline{A} x_0 + t A^2 x_0 + \frac{t^2}{2!} A^3 x_0 + \dots$$

$$= A \left[x_0 + tAx_0 + \frac{t^2}{2} A^2 x_0 + \dots \right]$$

$$= A \left(e^{At} x_0 \right)$$

$$e^{At}$$

A diagonalizable $\Leftrightarrow \exists$ n LI eigenvectors of A in \mathbb{R}^n ,
(over \mathbb{R})

"eigenvector" $\lambda \in \mathbb{R}, v \in \mathbb{R}^n, v \neq 0$.

$$Av = \lambda v$$

$\{v_1, \dots, v_n\}$ LI set of eigenvectors

$$T := [v_1 \ v_2 \ \dots \ v_n] \in \mathbb{R}^{n \times n}$$

T invertible.

$$AT = A[v_1 \ v_2 \ \dots \ v_n] = [Av_1 \ \dots \ Av_n]$$

$$= [\lambda_1 v_1 \ \dots \ \lambda_n v_n]$$

$$= [v_1 \ \dots \ v_n] \begin{bmatrix} \lambda_1 & 0 & \dots & 0 \\ 0 & \lambda_2 & \dots & 0 \\ \vdots & \vdots & \ddots & \vdots \\ 0 & 0 & \dots & \lambda_n \end{bmatrix}$$

$$\Lambda$$

$$\Rightarrow AT = T\Lambda$$

$$\Rightarrow T^{-1}AT = \Lambda$$

$$e^{At} = I + At + \frac{A^2 t^2}{2!} + \frac{A^3 t^3}{3!} + \dots$$

$$\Rightarrow T^{-1} e^{At} T = \underbrace{T^{-1} I T}_{\text{w}} + T^{-1} A t T + T^{-1} A^2 \frac{t^2}{2!} T + T^{-1} A^3 \frac{t^3}{3!} T + \dots$$

$$= I + \Lambda t + \Lambda^2 \frac{t^2}{2!} + \Lambda^3 \frac{t^3}{3!} + \dots$$

$$T^{-1} A^2 T = T^{-1} A T T^{-1} A T = \Lambda^2$$

$$= \begin{bmatrix} e^{\lambda_1 t} & & & 0 \\ & e^{\lambda_2 t} & & \\ & & \dots & \\ 0 & & & e^{\lambda_n t} \end{bmatrix} = e^{\Lambda t}$$

exists
[scalar exponentials exist]

$$\Rightarrow T^{-1} e^{At} T = e^{\Lambda t}$$

$$\Rightarrow e^{At} = T e^{\Lambda t} T^{-1}$$

Warning: Not every matrix is diagonalizable.

$$x(t) = e^{At} x_0$$

$$x(t+T) = e^{A(t+T)} x_0$$

$$= e^{At} (e^{AT} x_0)$$

$$= e^{At} x(T)$$

$$x(t) = e^{At} x(0)$$

$$\rightarrow x(0) = e^{-At} x(t)$$

Input

$$\dot{x} = Ax + Bu$$

$$x(t) = \underbrace{e^{At}}_0 x(0) + \int_0^t \underbrace{e^{A(t-\tau)}}_0 B u(\tau) d\tau$$

$$x(T+t) = e^{A(T+t)} x(0) + \int_0^{T+t} e^{A(T+t-\tau)} B u(\tau) d\tau$$

$$= e^{At} e^{AT} x(0) + \int_0^T e^{A(T+t-\tau)} B u(\tau) d\tau$$

$$+ \int_T^{T+t} e^{A(T+t-\tau)} B u(\tau) d\tau$$

$$= e^{At} e^{AT} x(0) + e^{At} \int_0^T e^{A(T-\tau)} B u(\tau) d\tau$$

$$+ \int_T^{T+t} e^{A(T+t-\tau)} B u(\tau) d\tau$$

$$= e^{At} \left[e^{AT} x(0) + \int_0^T e^{A(T-\tau)} B u(\tau) d\tau \right]$$

$$+ \int_T^{T+t} e^{A(T+t-\tau)} B u(\tau) d\tau$$

$$= e^{At} x(\tau) + \int_{\tau}^{\tau+t} e^{A(\tau+t-\tau)} B u(\tau) d\tau$$