

17 February:

$$s^4 + s^2 + 1 \checkmark$$

$$s^4: 1 \quad 1 \quad 1 \checkmark \rightarrow$$

$$s^3: 4 \quad 2 \quad 2 \quad 1$$

$$s^2: \frac{1}{2} \quad 1$$

$$s: * -3$$

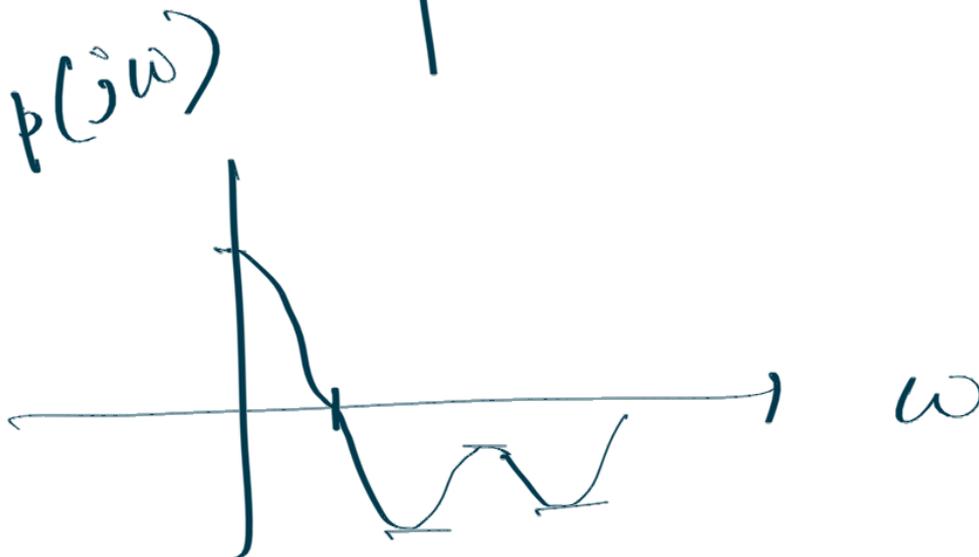
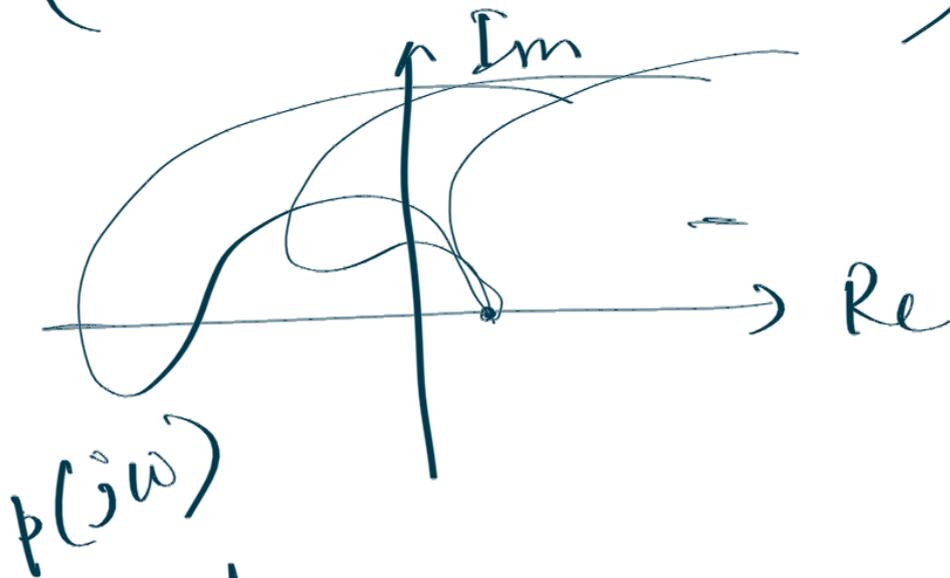
$$1: 1 \checkmark$$

$p(s)$ even polynomial

$$\deg p = 2m =$$

γ roots on the \mathbb{C}^+

$$(s^4 + s^2 + 1 + 4s^3 + 2s)$$

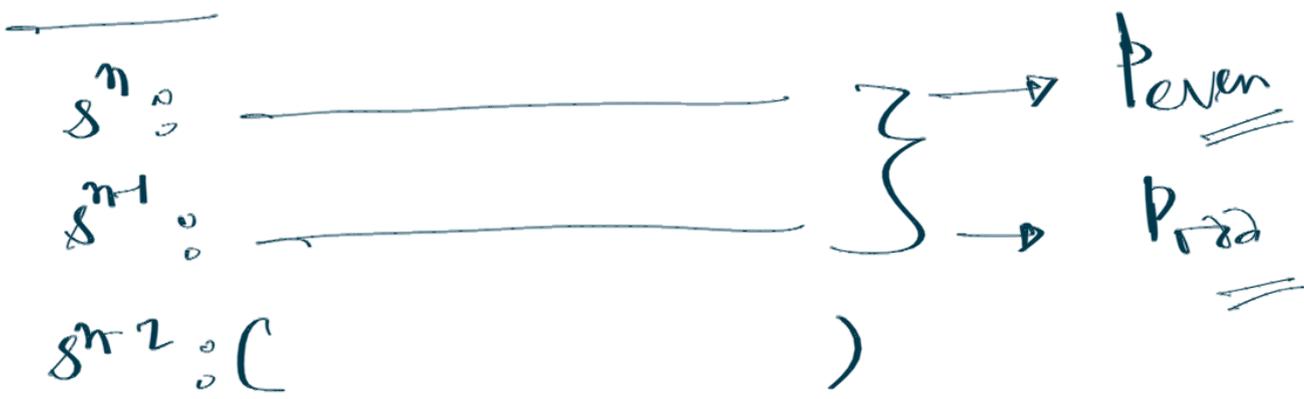


$$(2m - 2\gamma)$$

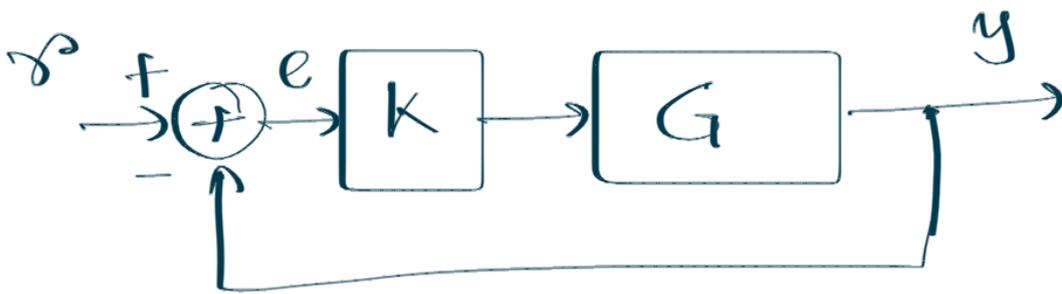
$$(2m - \gamma) \frac{\pi}{2} - \gamma \frac{\pi}{2}$$

$$= m\pi - \gamma\pi$$

$$= 2(m - \sigma) \frac{\sqrt{\lambda}}{2}$$



[-] Negative feedback:



CLTF = $\left(\frac{KG}{1+KG} \right) \approx 1$ as $K \gg 0$

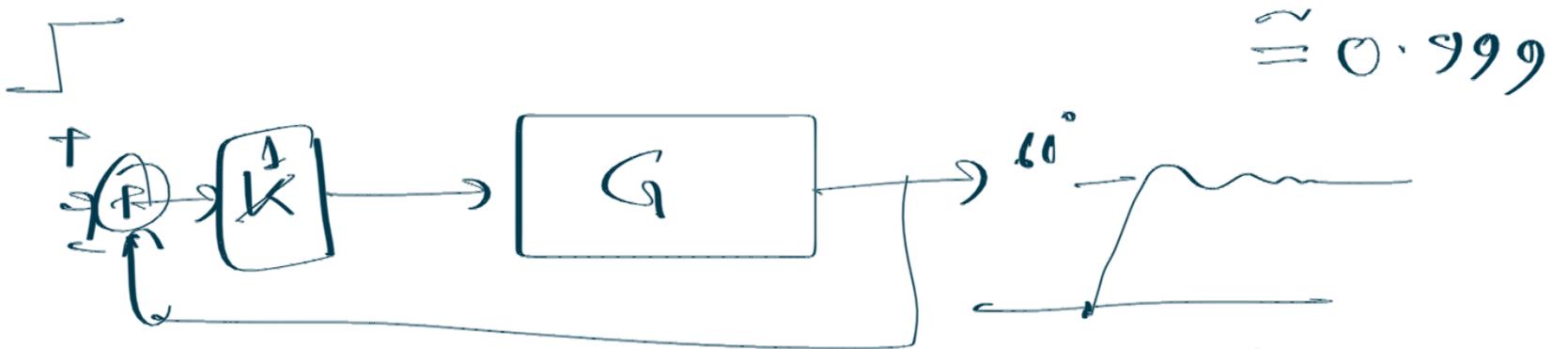
$\left[\frac{G + \Delta G}{G} \right] = 1 + \left(\frac{\Delta G}{G} \right)$ OLTF.

$G = 1, \Delta G = 0.1$

OLTF 1.1.

CLTF = $\frac{K}{1+K} \checkmark = \frac{1000}{1001} \approx 0.999$

CLTF = $\frac{K \times 1.1}{1 + K \times 1.1} = \frac{1100}{1 + 1100} = \frac{1100}{1101}$



Steady-state error, error, $e := x - y$

\swarrow ref. input \rightarrow output

$$e_{ss} = \lim_{t \rightarrow \infty} e(t) = \underline{\underline{e(\infty)}}$$

Error transfer f_e

$$E(s) = R(s) - Y(s)$$

$$= R(s) - G(s)E(s)$$

$$\Rightarrow (1 + G(s))E(s) = R(s)$$

$$\Rightarrow E(s) = \left(\frac{1}{1 + G(s)} \right) \cdot R(s)$$

↑ error transfer f_e

$$f(t) \xrightarrow{\mathcal{L}} F(s)$$

$$\lim_{t \rightarrow \infty} f(t) = \lim_{s \rightarrow 0} s F(s)$$

Find value theorem

$$F(s) = \frac{1}{s(s-1)}$$

$$f(t) = A \cdot 1(t) + B e^{t-1}(t)$$

$$\lim_{s \rightarrow 0} s F(s) = 1$$

$$R(s) = \frac{1}{s}$$

$$e(\infty) = \lim_{s \rightarrow 0} s \left(\frac{1}{s} \cdot \frac{1}{1 + G(s)} \right)$$

$$= \frac{1}{1 + G(s)} \quad (\text{assuming closed-loop stability})$$