

17 March

$$1 + k G(s) = 1 + k \frac{p(s)}{q(s)}$$

$$\deg p = m < \deg q = n$$

$k = K \in \mathbb{R}_+$ fixed

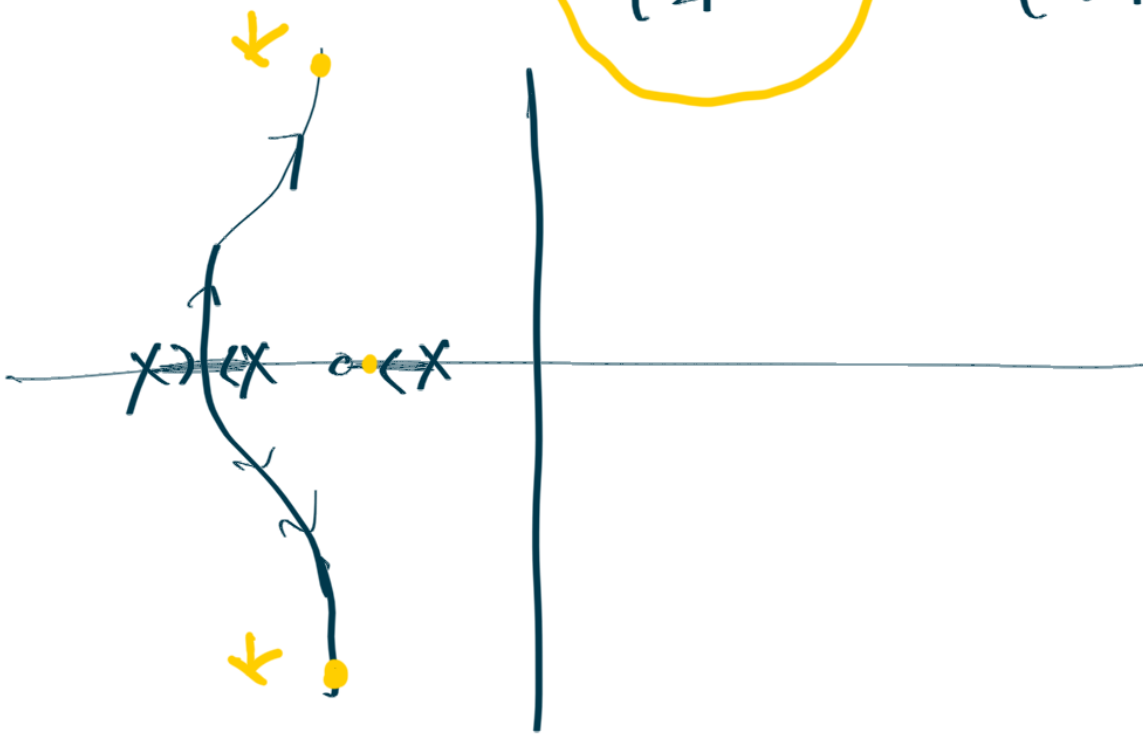
$$1 + (K + \Delta K) \frac{p(s)}{q(s)} = \frac{q(s) + K p(s) + \Delta K p(s)}{q(s)}$$

$$\text{zeros} = \text{zeros} \left(1 + \frac{\Delta K p(s)}{q(s) + K p(s)} \right)$$

$$q(s) + K p(s) = (s - \hat{p}_1)(s - \hat{p}_2) \dots (s - \hat{p}_n)$$

→ Centroid location

$$(n-m)\alpha = \sum_{i=1}^n \hat{p}_i - \sum_{i=1}^m z_i$$



$$1 + k \frac{p(s)}{q(s)} = \frac{[q(s) + k p(s)]}{q(s)}$$

$$= \frac{[(s^n + a_{n-1} s^{n-1} + \dots + a_0) + k (s^m + b_{m-1} s^{m-1} + \dots + b_0)]}{q(s)}$$

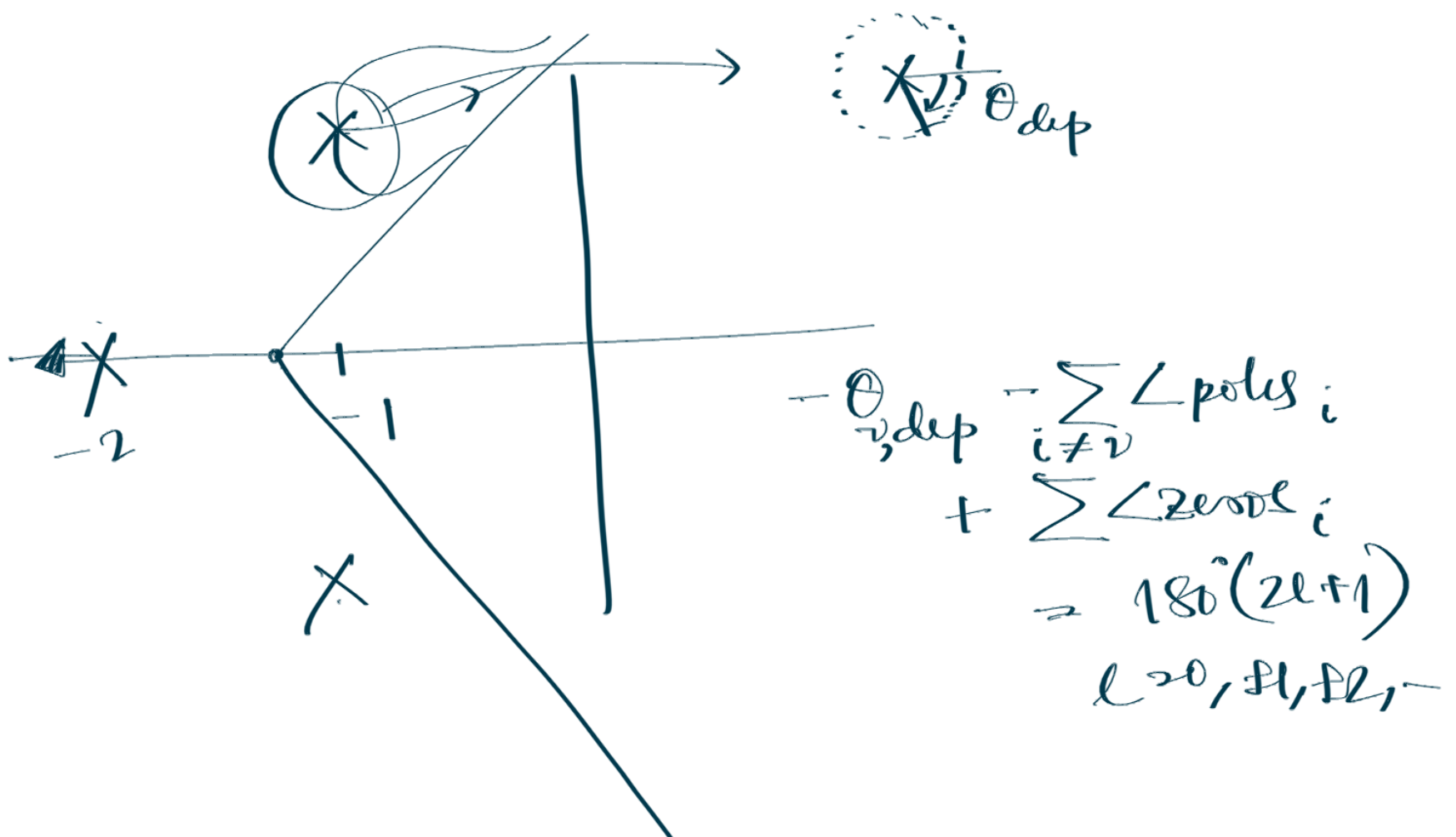
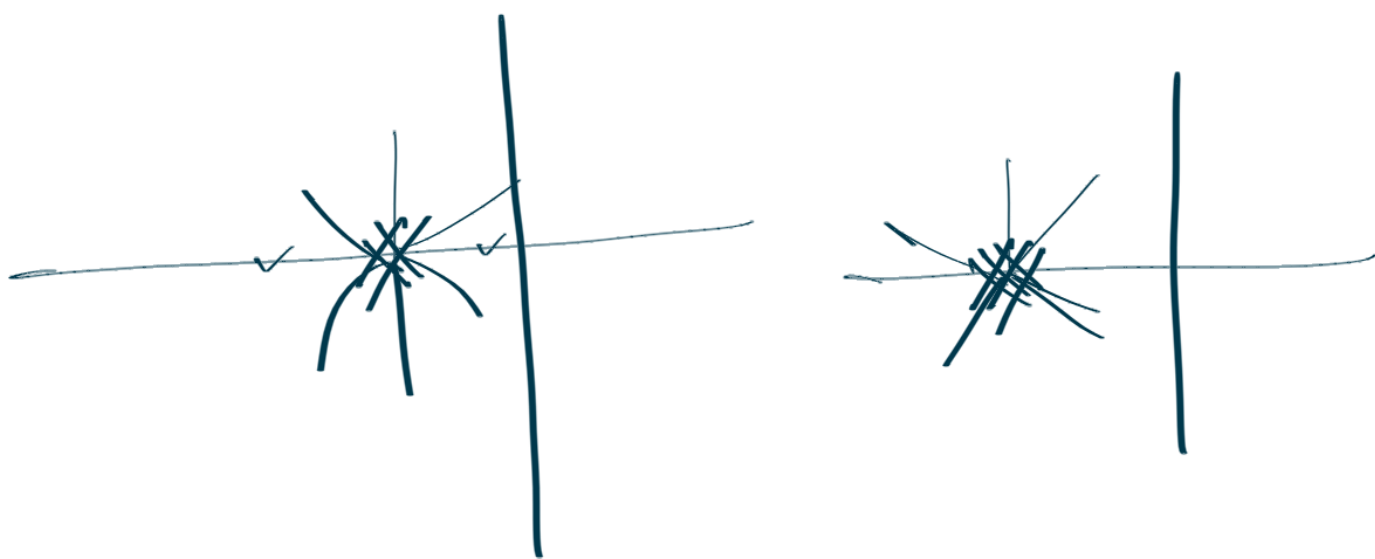
If $(n-m) \geq 2$ then

coeff. of s^{n-1} in the char. poly is unchanged by k .

$\Rightarrow \sum_{i=1}^n \hat{p}_i$ is invariant under the variation of k .

$$\Rightarrow \sum_{i=1}^n \hat{p}_i = \sum_{i=1}^n p_i$$

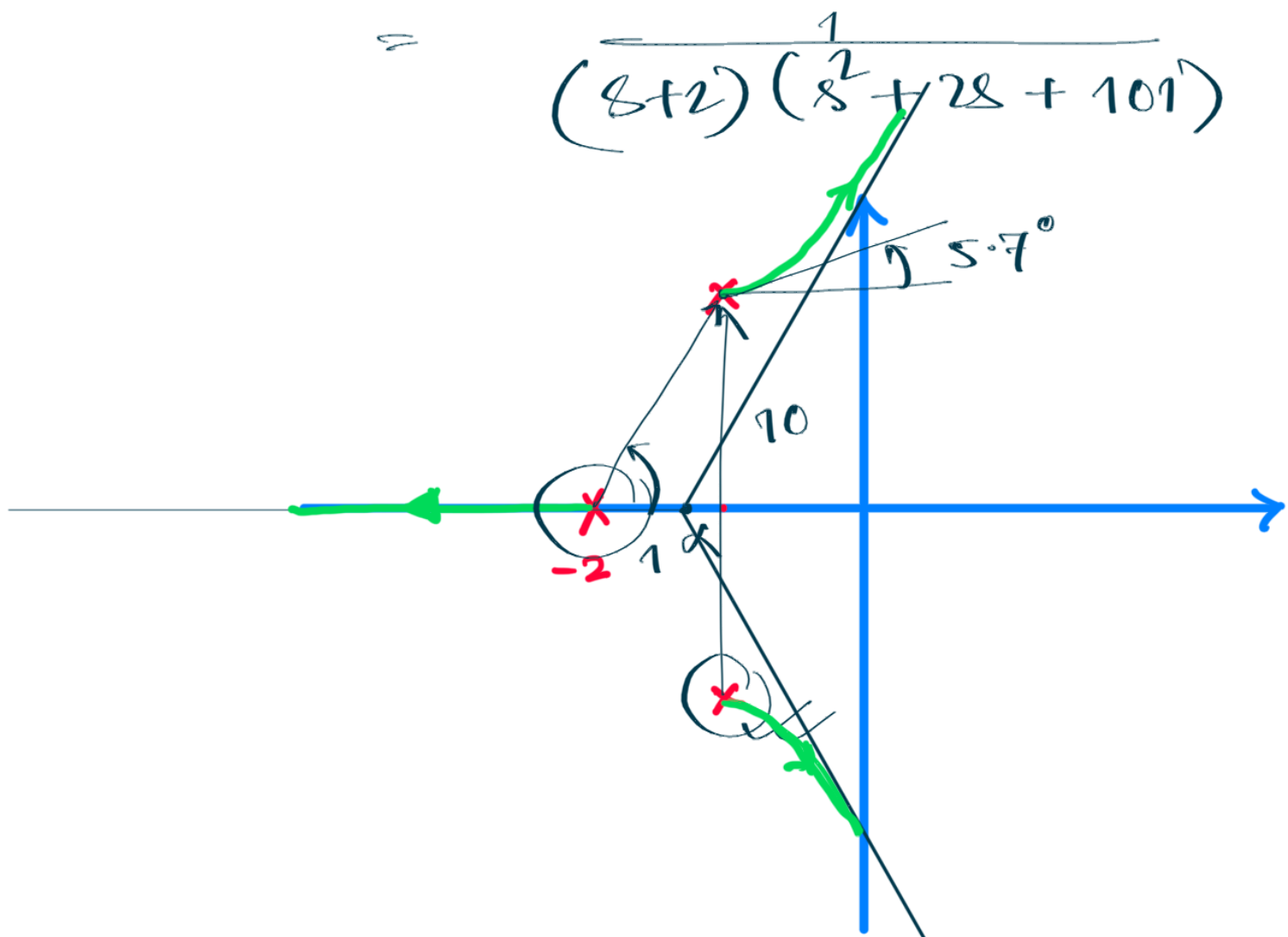
Rule #5: (Angles of arrival & departure)



Example:

$$G(s) = \frac{1}{(s+2)(s+1+j10)(s+1-j10)}$$

$$= \frac{1}{(s+2)((s+1)^2 + 100)}$$



Centroid locⁿ: $\sigma = \frac{1}{3} \begin{pmatrix} -2 & -1 - j10 \\ & -1 + j10 \end{pmatrix}$

$= -\frac{4}{3}$

Angle of departure:

$$(-\theta - 90^\circ - \tan^{-1} 10) = 180^\circ(2l+1)$$

$$= 180^\circ$$

$$\Rightarrow \theta = -90^\circ - \tan^{-1} 10 + 180^\circ$$

$$= 5.7^\circ$$