

# Active Queue Management using Adaptive RED

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### Abstract

Random Early Detection (RED) [1] is an active queue management scheme which has been deployed extensively to reduce packet loss during congestion. Although RED can improve loss rates, its performance depends severely on the tuning of its operating parameters. The idea of adaptively varying RED parameters to suit the network conditions has been investigated in [2], where the maximum packet dropping probability  $max_p$  has been varied. This paper focuses on adaptively varying the queue weight  $w_q$  in conjunction with  $max_p$  to improve the performance. We propose two algorithms viz.,  $w_q-thresh$  and  $w_q-ewma$  to adaptively vary  $w_q$ . The performance is measured in terms of the packet loss percentage, link utilization and stability of the instantaneous queue length. We demonstrate that varying  $w_q$  and  $max_p$  together results in an overall improvement in loss percentage and queue stability, while maintaining the same link utilization. We also show that  $max_p$  has a greater influence on loss percentage and queue stability as compared to  $w_q$ , and that varying  $w_q$  has a positive influence on link utilization.

### Index Terms

Random Early Detection (RED), active queue management, next generation Internet.

## I. INTRODUCTION

The problem of congestion control in TCP/IP networks has been studied extensively in the literature [3]. TCP provides an inherent mechanism for end-to-end congestion control. The essence of this mechanism is that a TCP source adjusts its window size based on an implicit feedback of a packet drop. Traditionally, a packet gets dropped whenever it encounters a full buffer (known as the Drop-Tail gateway). This however has been found to be inadequate owing to the following two reasons. First, gateways are designed with large buffers to accommodate transient congestion. However, queues that are occupied most of the time would be undesirable as this would increase the average delay in the network. Secondly, in spite of all the enhancements TCP has undergone, Drop-Tail gateways suffer from high packet loss rates. The reasons attributed to this high loss rate include a lack of early congestion notification to sources. This problem has been addressed by deploying active queue management strategies like RED in the network.

The basic philosophy behind RED is to *prevent* congestion rather than to *cure* it. In RED scheme, packets are dropped even before the buffer is full, in order to notify sources if congestion is building up. The sources can then reduce their window sizes (or rates), thereby preventing

further packet loss. The scheme is described in detail in the next section. However, RED has several shortcomings, including a high degree of sensitivity towards its operating parameters, unfairness to flows with different round-trip times, and the problem of global synchronization.

Several studies have been performed to address the above shortcomings [2], [4], [5], [6], [7], [8]. The idea of adaptively varying RED parameters has been proposed in [2]. In [2], one of the RED parameters  $max_p$  is adaptively varied. The objective is to reduce the oscillations in the queue length. We have demonstrated through simulations that varying  $max_p$  also has a positive effect on the packet loss percentage. However, as illustrated in the simulation results in this paper, varying  $max_p$  has an adverse effect on the link utilization. Floyd et al. in [8] discuss algorithmic modifications to the self-configuring RED algorithm [2] for tuning  $max_p$  adaptively. Their objective is to control the average queue length around a pre-decided target. However, it may be noted that controlling the average queue size has a limited impact on regulating the packet loss rate.

Previous papers have considered adaptive RED schemes in order to tune  $max_p$ . This paper addresses the issue of adaptively varying  $w_q$ . We demonstrate that adaptively varying  $w_q$  has a positive effect on link utilization. We show that varying  $w_q$ , by the techniques illustrated in the paper, along with varying  $max_p$ , in a manner similar to that of [2], brings about an improvement in terms of packet loss rates and queue stability without adversely affecting the link utilization. We, therefore, suggest that both  $max_p$  and  $w_q$  be varied adaptively.

The rest of the paper is organized as follows. Section II explains the problem of parameter sensitivity and discusses an algorithm to modify  $max_p$  adaptively. In Section III, we propose some algorithms for adaptively varying  $w_q$ . Section IV studies the relative performance of these algorithms. Finally, Section V concludes the paper.

## II. BACKGROUND

### A. RED scheme

The RED scheme was initially described and analyzed in [1]. The RED gateways detect incipient congestion by computing the average queue size. RED computes the average queue length  $q_{avg}$  using an exponentially weighted moving average:

$$q_{avg} = (1 - w_q)q_{avg} + w_q q_{instantaneous} \quad (1)$$

The packets are dropped based on the above  $q_{avg}$ . The averaging process smoothens out temporary traffic fluctuations and allows small bursts to pass through unharmed, dropping packets only during sustained overloads. RED maintains two queue thresholds:  $min_{th}$  and  $max_{th}$ . If  $q_{avg}$  exceeds  $max_{th}$ , all incoming packets are dropped, whereas if  $q_{avg}$  is less than  $min_{th}$  no packet is dropped. If  $q_{avg}$  lies between the two thresholds, packets are dropped with a probability  $p$  which increases linearly from 0 (at  $min_{th}$ ) to  $max_p$  (at  $max_{th}$ ). By dropping packets before the buffer is completely full, the RED gateway attempts to warn the TCP sources of incipient congestion.

### B. Performance dependence on parameters

The various control parameters of RED are listed below (Table I). The performance of a

TABLE I  
RED PARAMETERS

Parameter	Function
$w_q$	Weight for calculating average queue
$max_p$	Maximum dropping probability
$min_{th}$	Lower threshold below which no packet is dropped
$max_{th}$	Upper threshold above which all incoming packets are dropped

gateway employing RED depends significantly upon its parameters (see [2], [7]). In [9], certain guidelines to decide the values of these parameters have been given. However, experiments have shown that it is difficult to find appropriate values of parameters that will enable RED gateways to perform equally well under different congestion scenarios. In cases where the parameters are not suitable for the given network traffic load, the performance of the RED gateway can approach that of the traditional Drop-Tail gateway. One approach to solve this problem is to update the RED parameters dynamically in order that they are suitable for the given network conditions.

### C. Self-Configuring RED

An algorithm to modify the parameter  $max_p$  based on the average queue length is described in [2]. The basic idea is to modulate the aggressiveness of RED scheme by examining the variations in average queue length. If the average queue length oscillates around  $min_{th}$ , then the algorithm reduces the value of  $max_p$  by a factor  $\alpha$  (i.e.  $max_p = max_p/\alpha$ ), in order to make RED less aggressive. Similarly, if the average oscillates around  $max_{th}$ , then  $max_p$  is increased by a factor  $\beta$  (i.e.  $max_p = max_p * \beta$ ). This makes RED more aggressive. The outline of the algorithm is given in Figure 1. In the rest of the paper, we will call this the  $max_p$  algorithm. The algorithm performs well by reducing the oscillations in the instantaneous queue length under different traffic conditions.

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On the  $n$ th  $q_{avg}$  Update

- Calculate average queue size as
 
$$q_{avg_n} \leftarrow (1 - w_q)q_{avg_{n-1}} + w_q \cdot q_{instantaneous}$$
  - If ( $min_{th} < q_{avg_n} < max_{th}$ )
    - status = Between
  - If ( $q_{avg_n} < min_{th}$  && status!=Below)
    - status = Below
    - $max_p = max_p/\alpha$
  - If ( $q_{avg_n} > max_{th}$  && status!=Above)
    - status = Above
    - $max_p = max_p * \beta$
  - Rest of the RED algorithm remains the same.
- 

Fig. 1. Self-Configuring RED algorithm ( $max_p$ )

## III. ADAPTIVE RED

The Self-Configuring RED algorithm improves the performance in terms of the instantaneous queue stability by reducing oscillations. However, (as shown in the simulations below) it results

in a lower link utilization<sup>1</sup> under conditions of congestion. Our simulation results show that adapting the parameter  $w_q$  has a positive effect on link utilization under conditions of heavy load. This motivates one to look at algorithms which vary  $w_q$  adaptively in conjunction with  $max_p$ , in order to get better performance in terms of both link utilization and stability. As shown by the simulations, varying both  $w_q$  and  $max_p$  results in an improvement in queue stability and loss percentage without bringing down the link utilization. Also, the performance is considerably better in terms of loss percentage and stability as compared to the default<sup>2</sup> scheme or varying only  $w_q$ . We would, however, like to point out that varying  $w_q$  alone does not bring any significant improvement in terms of loss percentage or stability.

We propose to vary the parameter  $w_q$  adaptively based on the variations of the average queue length. If the change in average queue length is significant, then at the next  $q_{avg}$  update, greater weight should be given to the instantaneous queue length and hence  $w_q$  should be increased. Similarly, if the change is negligible,  $w_q$  should be reduced and greater weight should be given to the previous value of the average queue size. In other words,  $w_q$  controls how fast the network conditions are learnt. In this paper, we suggest two algorithms which can be used to vary  $w_q$ . The first algorithm ( $w_q - thresh$ , Figure 2) switches  $w_q$  between two levels and the second algorithm ( $w_q - ewma$ , Figure 5) varies  $w_q$  through an exponentially weighted moving average. Both of these are explained in the following subsections.

#### A. $w_q - thresh$ algorithm

The  $w_q - thresh$  algorithm changes the aggressiveness of RED scheme by changing the value of  $w_q$  based on the changes in the average queue length. The idea is to have two values for  $w_q$ , one ( $w_1$ ) corresponding to network conditions where the queue length is varying rapidly and the other ( $w_2$ ) corresponding to conditions of stable queue length. Depending on whether the variation in  $q_{avg}$ , viz.,  $|\Delta avg|$  exceeds a threshold  $\rho$  or not, the value of  $w_q$  is set to  $w_1$  or  $w_2$  respectively.  $w_1$  is chosen to be greater than  $w_2$  because more weight should be given to the instantaneous queue length when the queue size is varying rapidly. Also,  $w_1$  and  $w_2$  are varied close to 0.0020 which is the default value of  $w_q$  in the non-adaptive RED scheme (as suggested in [1]).

<sup>1</sup>The total number of packets transmitted *successfully* on a particular link (for a given time interval) is taken as a measure of the link utilization for that link.

<sup>2</sup>In the paper, the *default* scheme refers to the original RED scheme [1].

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On the  $n$ th  $q_{avg}$  Update

- Calculate average queue size as
 
$$q_{avg_n} \leftarrow (1 - w_q)q_{avg_{n-1}} + w_q \cdot q_{instantaneous}$$
  - If  $|\Delta avg| > \rho$ 

$$w_q = w_1$$
 else
 
$$w_q = w_2$$
 where  $\Delta avg = q_{avg_n} - q_{avg_{n-1}}$  and  $w_1 > w_2$   
 $\rho$  is some threshold value
  - Rest of the RED algorithm remains the same.
- 

Fig. 2. Adaptive RED algorithm ( $w_q$ : Thresholding)

The performance of the  $w_q - thresh$  algorithm has been studied for various values of  $w_1$ ,  $w_2$  and  $\rho$ . One significant observation that we would like to mention is that the performance of the algorithm is not affected significantly for  $\rho$  lying in the range  $[0.5, 2]$  (see Figure 3). For  $\rho > 2$ , the algorithm tends to be the same as the default scheme with  $w_1$  as the queue weight, since  $|\Delta avg|$  does not exceed  $\rho$ . For lower values of the parameter  $\rho$  the performance varies a lot for small variations in  $\rho$  (see Figure 4). In the simulations carried out in the paper, we have chosen a value of  $\rho = 1$  and it has been found to work well under various network scenarios considered in the simulations.

The performance varies marginally with respect to the parameter pair  $\{w_1, w_2\}$ . The simulations were carried out with  $\{w_1, w_2\}$  being equal to  $\{0.0022, 0.0018\}$ ,  $\{0.0021, 0.0017\}$ ,  $\{0.0024, 0.0020\}$  and  $\{0.0020, 0.0018\}$ . However, the pair  $\{0.0022, 0.0018\}$  gives the best performance in most of the scenarios simulated in this paper compared to the other values. The results in the paper correspond to  $\{w_1 = 0.0022, w_2 = 0.0018\}$  and  $\rho = 1$ .

### B. $w_q - ewma$ algorithm

The  $w_q - ewma$  algorithm regulates the aggressiveness of RED scheme, by allowing the queue weight  $w_q$  to take a *continuous* set of values unlike the  $w_q - thresh$  algorithm in which  $w_q$  takes only two discrete values. The scheme works by observing the change in  $q_{avg}$  and modifying  $w_q$

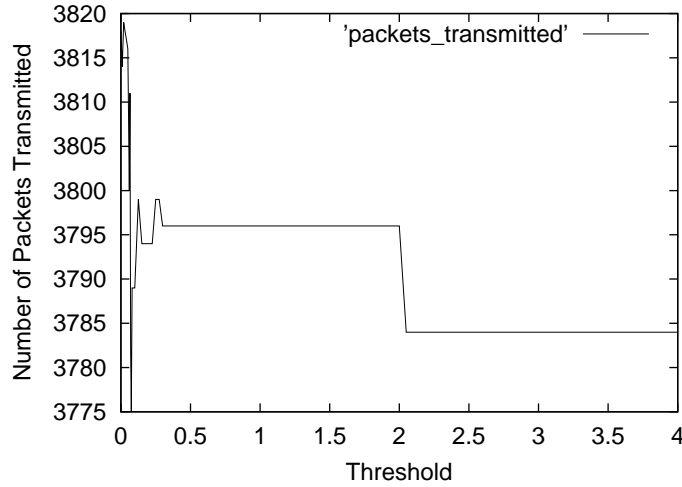


Fig. 3. Packets transmitted as a function of threshold  $\rho$ , ( $w_1 = 0.0022$ ,  $w_2 = 0.0018$ ) for a particular network scenario.

according to the equation

$$w_q \leftarrow k_1 w_q + k_2 |\Delta avg| \quad (2)$$

The constant  $k_1 (< 1)$  is responsible for decreasing  $w_q$  whenever  $|\Delta avg|$  is negligible. The constant  $k_2$  changes  $w_q$  in proportion to  $|\Delta avg|$  so that when the queue length is varying rapidly,  $w_q$  increases at a faster rate. The  $w_q - ewma$  algorithm has been simulated for various values of the parameters  $k_1$  and  $k_2$ . The algorithm gives a consistently good performance when  $k_1$  is close to unity and  $k_2$  is close to zero. Otherwise, the performance varies considerably and at times can become worse than the non-adaptive algorithm. Also, the parameters cannot be arbitrarily varied independent of each other without compromising on performance. From the simulations we determine that if  $k_2$  is set close to  $(1 - k_1)/10$  then the algorithm gives good performance for  $k_1$  in  $[0.999, 1.000]$ . The rationale behind setting  $k_2$  in terms of  $k_1$  in such a fashion is the following.

The adaptation equation for changing  $w_q$  is given by Equation (2). As long as the change in the average queue length is observed to be negligible, ( $|\Delta avg| \approx 0$ ),  $w_q$  keeps decreasing by a factor  $k_1$ . Whenever  $|\Delta avg|$  is observed to be changing rapidly,  $w_q$  needs to be restored to a higher value. Therefore,  $k_2$  needs to not only offset the decrease caused by  $k_1$  (which is  $(1 - k_1) * w_q$ ) but also provide the necessary increase. Hence,  $k_2$  should be set to  $(1 - k_1) * \frac{w_q}{|\Delta avg|} * \kappa$ , where



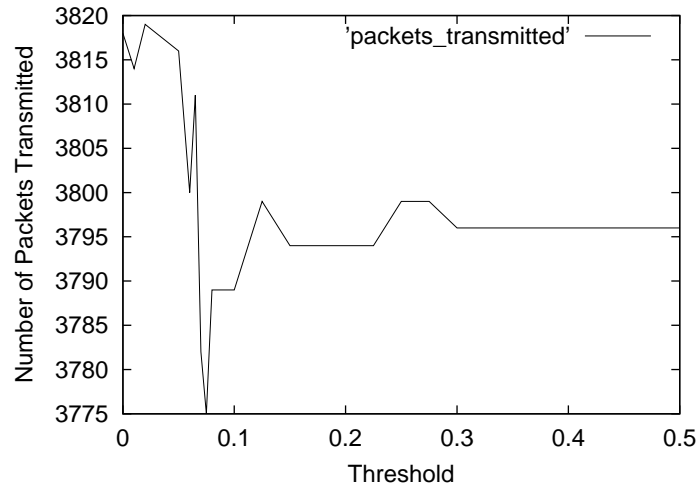


Fig. 4. Packets transmitted as a function of threshold  $\rho$ , (Magnified view:  $\rho \in [0,0.5]$ ,  $w_1 = 0.0022$ ,  $w_2 = 0.0018$ ) for a particular network scenario.

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On the  $n$ th  $q_{avg}$  Update

- Calculate average queue size as

$$q_{avg_n} \leftarrow (1 - w_q)q_{avg_{n-1}} + w_q \cdot q_{instantaneous}$$

- Update queue weight  $w_q$  as

$$w_q \leftarrow k_1 w_q + k_2 |\Delta avg|$$

$$\text{where } \Delta avg = q_{avg_n} - q_{avg_{n-1}}$$

- Rest of the RED algorithm remains the same.
- 

Fig. 5. Adaptive RED algorithm ( $w_q$ : Weighted Average)

$\kappa$  is a constant which controls the amount of increase in  $w_q$ . In addition, from simulations we find that the variations in the average queue length is about an order of magnitude higher than  $w_q$ . Therefore,  $k_2$  can be set as  $(1 - k_1) * \kappa/10$ . We have taken  $\kappa$  to be 1.

In the simulations, when only  $w_q - ewma$  is employed, we use the value  $k_1 = 0.9996$  and hence  $k_2 = 0.00004$ , whereas when both the  $w_q - ewma$  and the  $max_p$  algorithms are employed, then  $k_1 = 0.9992$  and  $k_2 = 0.00010$  are used. Here  $k_2$  is set to 0.00010 instead of 0.00008, as dictated by the above reasoning. This is because the adaptation algorithm for  $max_p$  uses a value of  $\alpha$  which is greater than  $\beta$  so that  $max_p$  decreases faster than it increases (see Section IV). So

a higher value of  $k_2$  enables  $w_q$  to increase faster when congestion occurs and compensate for the slower response of  $max_p$ .

#### IV. PERFORMANCE EVALUATION

##### A. Experimental network

The simulations have been performed using the **ns v2.1b7** network simulator ([10]). The network topology shown in Figure 6 is used for simulating the various scenarios. It may be noted that the simulation topology used is similar to the topology used in other papers, for consistent comparison. The issue of multiple congested gateways has not been considered here. The value of  $N$  is varied for different scenarios. The default RED parameters are kept as  $w_q = 0.0020$ ,  $max_p = 0.1$ ,  $max_{th} = 15$  and  $min_{th} = 5$ . The buffer size for the RED router is kept as 50 packets and the simulations are performed with equal sized packets. The results are obtained for the RED router and the bottleneck link shown in the figure.

We call a *harsh* scenario as one where the loss percentage (defined as number of packets lost / number of packets which entered the router) exceeds 20%. If the loss rate is around 1%, then the scenario is referred to as *mild*. In between (loss percentage  $\approx$  5-15%), the simulation scenario is called *moderate*.

In all of the simulations, the values of  $\alpha$  and  $\beta$  for the  $max_p$  algorithm are taken as 2 and 1.5 respectively. The reasoning behind choosing these values is that  $max_p$  should be decreased more drastically compared to when it is increased. The packet loss rate is directly influenced by  $max_p$ . A large increase in  $max_p$  can lead to high loss rates and hence it should be increased cautiously. In [2],  $\alpha$  and  $\beta$  are taken as 3 and 2 respectively. However, the values  $\alpha = 2$  and  $\beta = 1.5$  give a relatively better performance under harsh and moderate scenarios and these have been used in the simulations.

##### B. Harsh scenario

For the harsh scenario the total number of nodes has been taken as 80. The bottleneck bandwidth is 1Mbps while the other link bandwidths are 3Mbps. The various sources are switched on at random times between  $t = 0$ sec and  $t = 7$ sec. The sources stop transmitting at time  $t = 30$ sec.

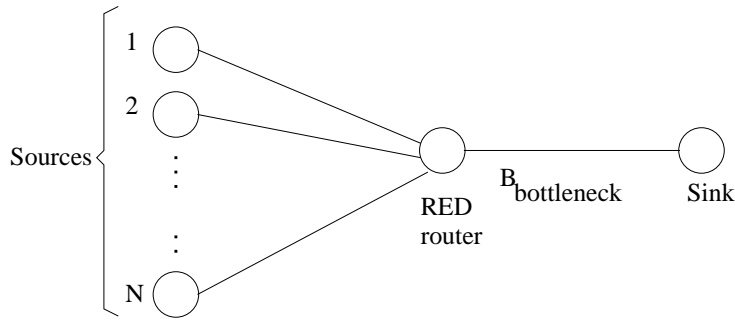


Fig. 6. Network Topology

TABLE II

PERFORMANCE COMPARISON (HARSH SCENARIO):  $w_q$ -*thresh*,  $w_q$ -*ewma* AND  $max_p$  ALGORITHMS

Algorithm	Drop%	Packets	Stable
Default	30.39	3741.9	No
Only $w_q$ - <i>thresh</i>	30.18	3750.1	No
Only $w_q$ - <i>ewma</i>	30.23	3755.0	No
Only $max_p$	26.61	3724.9	Yes
$w_q$ - <i>thresh</i> + $max_p$	26.19	3736.3	Yes
$w_q$ - <i>ewma</i> + $max_p$	26.65	3730.0	Yes

From the simulation results (refer Table<sup>3</sup> II) it can be inferred that:

- Both the  $w_q$ -*thresh*+ $max_p$  and  $w_q$ -*ewma*+ $max_p$  algorithms are much better than the default scheme in terms of stability (see Figures 7, 8 and 9).
- Using only the  $max_p$  algorithm results in a drop in the number of packets transmitted successfully. Varying  $w_q$  in conjunction with  $max_p$  helps in achieving the benefits of varying  $max_p$  (lower loss percentage and more stability) and at the same time counters the adverse effect of  $max_p$  on link utilization. The overall improvement in performance is prominent in the moderate scenario.
- Varying only  $w_q$  results in an improvement in the number of packets transmitted. Even though the improvement seems marginal, in such a scenario where the link utilization is as such close to 97 – 98%, an improvement of only about half a percent is substantial. In

<sup>3</sup>By *packets*, we mean the number of *successfully* transmitted packets.

certain sample paths, the improvement was close to 2%. The importance of  $w_q$  in affecting the link utilization is further seen in the moderate scenario.

- Both the algorithms result in a substantial decrease ( $\approx 4\%$ ) in the loss percentage compared to the default RED scheme.
- Also, the stability of the instantaneous queue length is better in the  $w_q\text{-ewma}+max_p$  algorithm than in the  $w_q\text{-thresh}+max_p$ . This can be attributed to the fact that  $w_q$  is intimately tied to the estimation of the average queue length and hence the regulation of the instantaneous queue length. So varying  $w_q$  continuously has a better stabilizing effect than switching it between two different values.

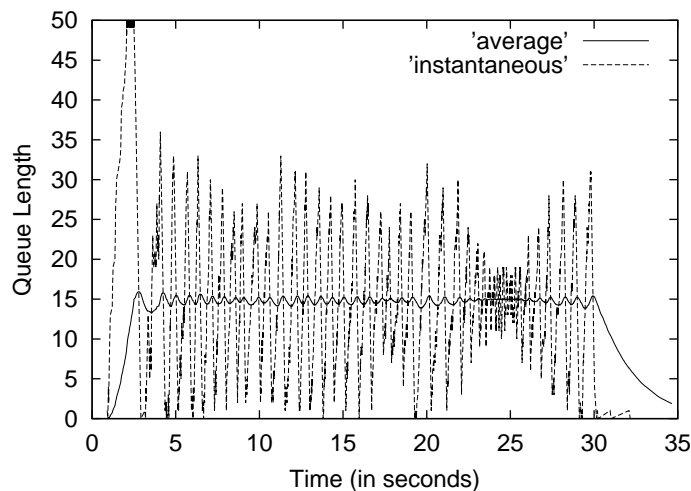


Fig. 7. Average and instantaneous queues with default RED (Harsh scenario)

### C. Moderate scenario

Here the total number of nodes has been taken as 25. The sources start transmitting at random times between  $t = 0\text{sec}$  to  $t = 5\text{sec}$ . Their stop times are also random. The sources transmit till about  $t = 20\text{sec}$ . The following inferences can be drawn from the results (refer Table III):

- As far as the stability of the instantaneous queue is concerned, the problem is less severe in this scenario (Figure 10) compared to the harsh scenario. Still, the adaptive algorithms varying both  $max_p$  and  $w_q$  perform better (Figures 11 and 12) compared to the non-adaptive RED scheme.

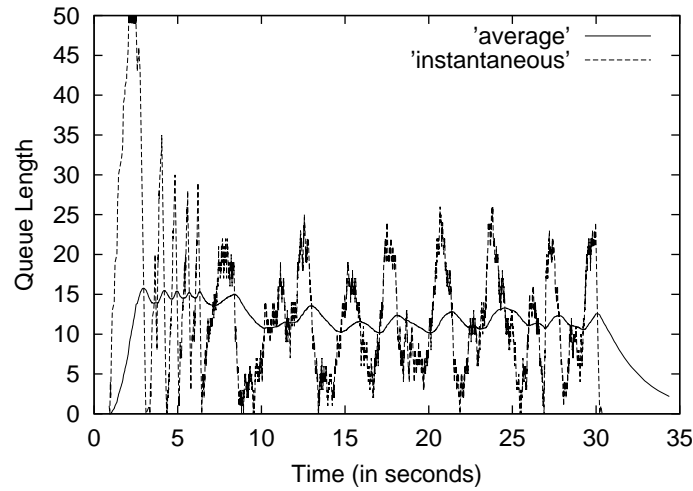


Fig. 8. Average and instantaneous queues with  $max_p+w_q$ -thresh algorithm (Harsh scenario)

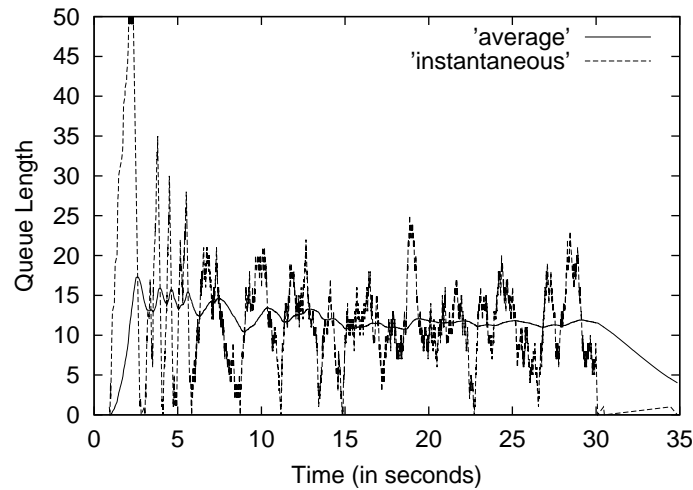


Fig. 9. Average and instantaneous queues with  $max_p+w_q$ -ewma algorithm (Harsh scenario)

- The performance of the adaptive algorithms (varying both  $max_p$  and  $w_q$ ) is better, compared to the default RED scheme, in terms of loss percentage and number of packets transmitted.
- Varying only  $max_p$  results in a drop in the number of packets transmitted. Varying  $w_q$  along with  $max_p$  results in a better link utilization compared to when only  $max_p$  is varied.
- Varying only  $w_q$  is not sufficient to bring down the loss percentage or make the queue stable.

TABLE III

PERFORMANCE COMPARISON (MODERATE SCENARIO):  $w_q$ -*thresh*,  $w_q$ -*ewma* AND  $max_p$  ALGORITHMS

Algorithm	Drop%	Packets	Stable
Default	12.69	2369.3	No
Only $w_q$ - <i>thresh</i>	12.44	2364.0	No
Only $w_q$ - <i>ewma</i>	12.66	2362.9	No
Only $max_p$	11.84	2345.7	Yes
$w_q$ - <i>thresh</i> + $max_p$	11.03	2372.1	Yes
$w_q$ - <i>ewma</i> + $max_p$	11.94	2373.0	Yes

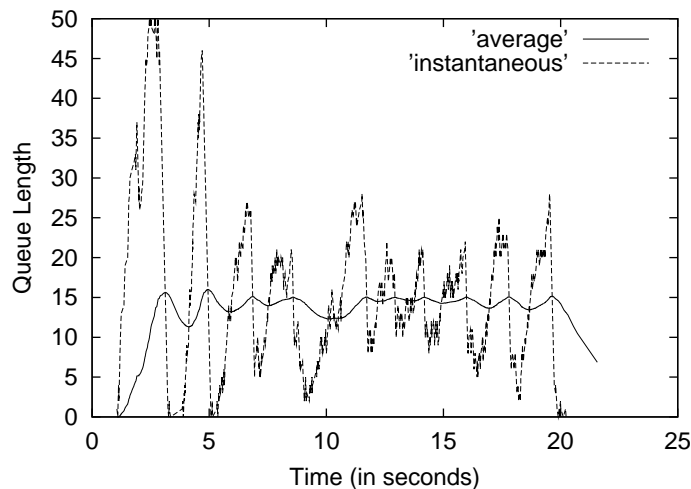


Fig. 10. Average and instantaneous queues with default RED (Moderate scenario)

*D. Mild scenario*

In a mild scenario, where the loss percentages are very low, the problem of stability does not arise. Also, using any of the adaptive algorithms does not help much in reducing the loss percentages further. However, there is an increase in the number of packets transmitted.

The results (refer Table IV) shown are for  $N = 5$  and all link bandwidths being equal to 10Mbps. As can be seen from the results, varying only  $max_p$  brings about a good improvement in the number of packets transmitted and further varying  $w_q$  (using the  $w_q$ -*thresh* algorithm) improves the performance only marginally. Thus, if a tradeoff has to be made between com-

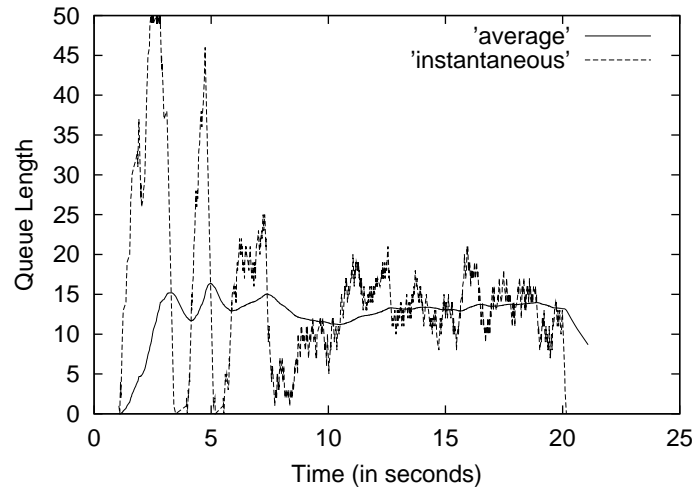


Fig. 11. Average and instantaneous queues with  $max_p+w_q-thresh$  algorithm (Moderate scenario)

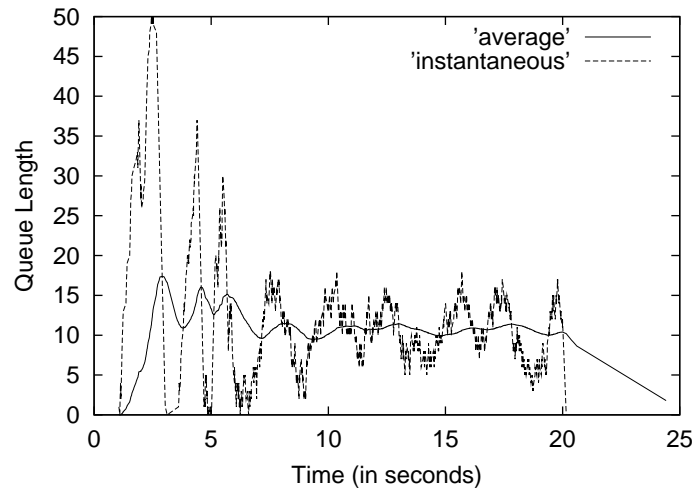


Fig. 12. Average and instantaneous queues with  $max_p+w_q-ewma$  algorithm (Moderate scenario)

plexity and performance, the results suggest that only  $max_p$  should be varied in such a scenario. However, varying both  $w_q$  ( $w_q-thresh$  algorithm) and  $max_p$  still gives a better performance compared to the other schemes. The  $w_q-ewma$  algorithm gives poorer performance in terms of the packets transmitted but there is marginal improvement in the loss percentage. This can be explained as follows. The manner in which  $w_q$  is varied controls how fast the network conditions are learnt. Since in a mild scenario, the network changes are smaller, the  $w_q-thresh$  algorithm

is faster to respond than the  $w_q - ewma$  algorithm, and hence performs better. This suggests that in scenarios with little or no congestion,  $w_q$  should be varied according to the  $w_q - thresh$  algorithm. In case computation complexity is of great concern, then only  $max_p$  should be varied in such scenarios.

It was also observed that in mild scenarios, varying  $max_p$  in larger steps (e.g.  $\{\alpha = 3, \beta = 2\}$ ) gives better results than varying it with  $\{\alpha = 2, \beta = 1.5\}$ . However,  $\alpha$  and  $\beta$  should not be too large because then the algorithm becomes unstable.

TABLE IV

PERFORMANCE COMPARISON (MILD SCENARIO):  $w_q - thresh$ ,  $w_q - ewma$  AND  $max_p$  ALGORITHMS

Algorithm	Drop%	Packets
Default	0.80	24715.6
Only $w_q - thresh$	0.82	24713.2
Only $w_q - ewma$	0.77	24387.7
Only $max_p$	0.73	24774.5
$w_q - thresh + max_p$	0.73	24789.7
$w_q - ewma + max_p$	0.61	24531.2

### E. Summary of results

Based on the above observations, we can make the following conclusions on the effect of  $max_p$  and  $w_q$  on the performance of RED:

- 1)  $max_p$  has a stronger influence on the loss percentage and stability of RED as compared to  $w_q$ . The strong influence of  $max_p$  on the packet loss rate is evident, since it is directly related to how harshly the RED scheme drops packets in order to discourage sources from sending too much data. The influence on stability is however indirect. Only varying  $w_q$  is not sufficient to avoid persistent oscillations of the instantaneous queue, whereas changing  $max_p$  helps in stabilizing the queue size.
- 2)  $w_q$  has a greater positive influence in terms of link utilization as compared to  $max_p$ . Moreover, the effect is prominent under conditions of heavy and moderate network traffic. The



drop in link utilization due to varying  $max_p$  can be countered by varying  $w_q$  in conjunction with  $max_p$ .

- 3) In mild scenarios, varying  $max_p$  alone can ensure a good performance in terms of loss percentage and link utilization.

## V. CONCLUSIONS

In this paper, we have looked at the performance of RED scheme in relation to its operating parameters. We have identified the impact of varying  $max_p$  on link utilization and loss percentage. Previous papers on adaptive RED have focussed exclusively on tuning  $max_p$ , while ignoring the effects of  $w_q$ . We have studied the effect of varying  $w_q$  in conjunction with  $max_p$  and demonstrated how this can serve to counter the decrease in link utilization caused by varying  $max_p$  alone. We have suggested algorithms to adaptively vary  $w_q$ . We note that varying  $max_p$  has a greater influence on packet loss rate and queue length stability, while varying  $w_q$  controls the link utilization. Finally, it has been suggested that both  $max_p$  and  $w_q$  should be varied, in *harsh* and *moderate* congestion scenarios, to achieve an overall improvement in loss percentage and stability without adversely affecting the link utilization as compared to the default RED scheme.

In the end, we would like to reiterate the fact that RED is quite sensitive to its operating parameters. The issue of the performance of RED (adaptive or otherwise) in multiple congested networks is quite crucial and has not been investigated. We have explored active queue management strategies based on traffic prediction, and we feel that these algorithms are likely to fare better in multiple congested links and would be less sensitive to parameters. These issues are however beyond the scope of the current paper, and will be addressed elsewhere [11].

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