

Figure 1: `cmptrtr_hyst_1.gce`: input-output relationship.

## `cmptrtr_hyst_1.gce`

### Attributes

```
mainvars: x1 x2 y
rparams: g_high=1.0 eps1=1.0e-6 delta_tmin=1.0e-6
+ delta_tnrml=1.0e-3 h=0.1
```

### Description

`cmptrtr_hyst_1.gce` is a comparator with hysteresis. It compares general variables `x1` and `x2`. The input-output relation is as shown in Fig. 1.

The parameters `delta_tmin`, `delta_tnrml`, and `eps1` are used for controlling the simulator time steps. Additional time points are forced, depending on the values of `delta_tmin` and `delta_tnrml`, when  $(x1 - x2) \pm h/2 \leq \text{eps1}$ . This feature allows accurate simulation without having to make the average time step very small. Generally, `delta_tnrml` should be made equal to the typical simulator time step (`delt_const`) while `delta_tmin` should be made much smaller (say, by a factor of 100).

AC behaviour is not implemented.

Fig. 2 shows typical waveforms obtained with `cmptrtr_hyst_1.gce`. The corresponding circuit file (available as `cmptrtr_hyst_1.gce.in` in the examples directory) is reproduced below.

```

title: testing of cmptrtr_hyst_1

begin_circuit
  gelement type=triangle_2 y=x1 i0=0 tperiod=8m t0=0
+   g_high=1 g_low=-1 epsl=1u
  gelement type=triangle_2 y=x2 i0=1 tperiod=8m t0=0
+   g_high=1 g_low=-1 epsl=1u
  gelement type=cmptrtr_hyst_1 x1=x1 x2=x2 y=y g_high=1.2 epsl=1.0e-15
+   delta_tmin=0.2u delta_tnrml=0.80m h=0.5

  outvar:
+   x1=var_of_x1
+   x2=var_of_x2
+   y=var_of_y
end_circuit

begin_solve
  solve_type=startup
  initial_sol initialize
  method: t_startup=0
end_solve

begin_solve
  solve_type=trns
  initial_sol previous
  begin_output
    filename=cmptrtr_hyst_1_gce.dat limit_lines=10000
    variables: x1 x2 y
  end_output
  method: itmax_trns=10000
+   back_euler=yes
+   t_start=0 t_end=20m delt_const=0.80m delt_min=0.10u
+   n_wrtiterno=1000
end_solve

end_cf

```

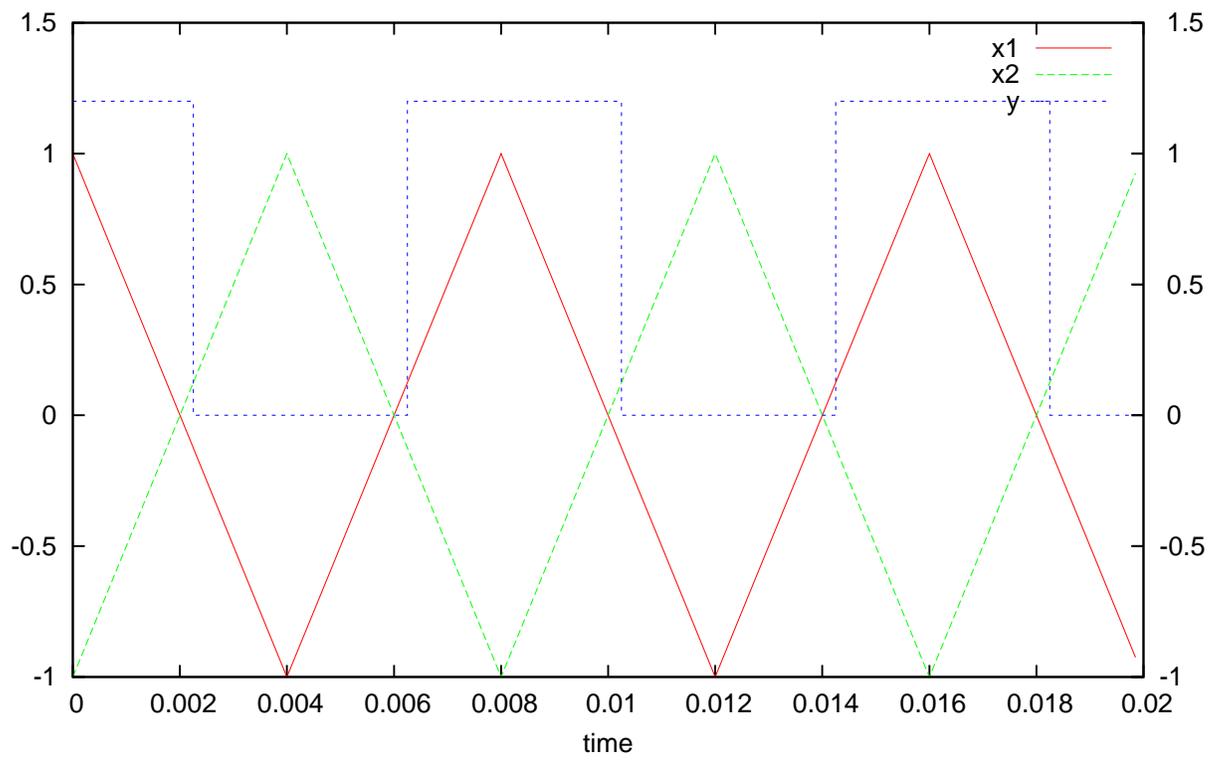


Figure 2: Waveforms obtained with `cmptr_hyst_1.gce` (see the circuit file for details).