

Performance of ML Receiver for Binary Signaling

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Real AWGN Channel

M-ary Signaling in AWGN Channel

- One of M continuous-time signals $s_1(t), \dots, s_M(t)$ is transmitted
- The received signal is the transmitted signal corrupted by real AWGN
- M hypotheses with prior probabilities $\pi_i, i = 1, \dots, M$

$$\begin{aligned} H_1 & : y(t) = s_1(t) + n(t) \\ H_2 & : y(t) = s_2(t) + n(t) \\ & \vdots \\ H_M & : y(t) = s_M(t) + n(t) \end{aligned}$$

- If the prior probabilities are equal, ML decision rule is optimal
- The ML decision rule is

$$\delta_{ML}(\mathbf{y}) = \operatorname{argmin}_{1 \leq i \leq M} \|\mathbf{y} - \mathbf{s}_i\|^2 = \operatorname{argmax}_{1 \leq i \leq M} \langle \mathbf{y}, \mathbf{s}_i \rangle - \frac{\|\mathbf{s}_i\|^2}{2}$$

- We want to study the performance of the ML decision rule

ML Decision Rule for Binary Signaling

- Consider the special case of binary signaling

$$H_0 : y(t) = s_0(t) + n(t)$$

$$H_1 : y(t) = s_1(t) + n(t)$$

- The ML decision rule decides H_0 is true if

$$\langle y, s_0 \rangle - \frac{\|s_0\|^2}{2} > \langle y, s_1 \rangle - \frac{\|s_1\|^2}{2}$$

- The ML decision rule decides H_1 is true if

$$\langle y, s_0 \rangle - \frac{\|s_0\|^2}{2} \leq \langle y, s_1 \rangle - \frac{\|s_1\|^2}{2}$$

- The ML decision rule

$$\langle y, s_0 - s_1 \rangle \underset{H_1}{\overset{H_0}{>}} \frac{\|s_0\|^2}{2} - \frac{\|s_1\|^2}{2}$$

- The distribution of $\langle y, s_0 - s_1 \rangle$ is required to evaluate decision rule performance

Performance of ML Decision Rule for Binary Signaling

- Let $Z = \langle y, \mathbf{s}_0 - \mathbf{s}_1 \rangle$
- Z is a Gaussian random variable

$$Z = \langle y, \mathbf{s}_0 - \mathbf{s}_1 \rangle = \langle \mathbf{s}_i, \mathbf{s}_0 - \mathbf{s}_1 \rangle + \langle n, \mathbf{s}_0 - \mathbf{s}_1 \rangle$$

- The mean and variance of Z under H_0 are

$$\begin{aligned} E[Z|H_0] &= \|\mathbf{s}_0\|^2 - \langle \mathbf{s}_0, \mathbf{s}_1 \rangle \\ \text{var}[Z|H_0] &= \sigma^2 \|\mathbf{s}_0 - \mathbf{s}_1\|^2 \end{aligned}$$

where σ^2 is the PSD of $n(t)$

- Probability of error under H_0 is

$$P_{e|0} = \Pr \left[Z \leq \frac{\|\mathbf{s}_0\|^2 - \|\mathbf{s}_1\|^2}{2} \middle| H_0 \right] = Q \left(\frac{\|\mathbf{s}_0 - \mathbf{s}_1\|}{2\sigma} \right)$$

Performance of ML Decision Rule for Binary Signaling

- The mean and variance of Z under H_1 are

$$\begin{aligned}E[Z|H_1] &= \langle \mathbf{s}_1, \mathbf{s}_0 \rangle - \|\mathbf{s}_1\|^2 \\ \text{var}[Z|H_1] &= \sigma^2 \|\mathbf{s}_0 - \mathbf{s}_1\|^2\end{aligned}$$

- Probability of error under H_1 is

$$P_{e|1} = \Pr \left[Z > \frac{\|\mathbf{s}_0\|^2 - \|\mathbf{s}_1\|^2}{2} \middle| H_1 \right] = Q \left(\frac{\|\mathbf{s}_0 - \mathbf{s}_1\|}{2\sigma} \right)$$

- The average probability of error is

$$P_e = \frac{P_{e|0} + P_{e|1}}{2} = Q \left(\frac{\|\mathbf{s}_0 - \mathbf{s}_1\|}{2\sigma} \right)$$

Different Types of Binary Signaling

- Let $E_b = \frac{1}{2} (\|s_0\|^2 + \|s_1\|^2)$
- For antipodal signaling, $s_1(t) = -s_0(t)$
 $E_b = \|s_0\|^2 = \|s_1\|^2$ and $\|s_0 - s_1\| = 2\|s_0\| = 2\|s_1\| = 2\sqrt{E_b}$

$$P_e = Q\left(\frac{\sqrt{E_b}}{\sigma}\right) = Q\left(\sqrt{\frac{2E_b}{N_0}}\right)$$

where $\sigma^2 = \frac{N_0}{2}$

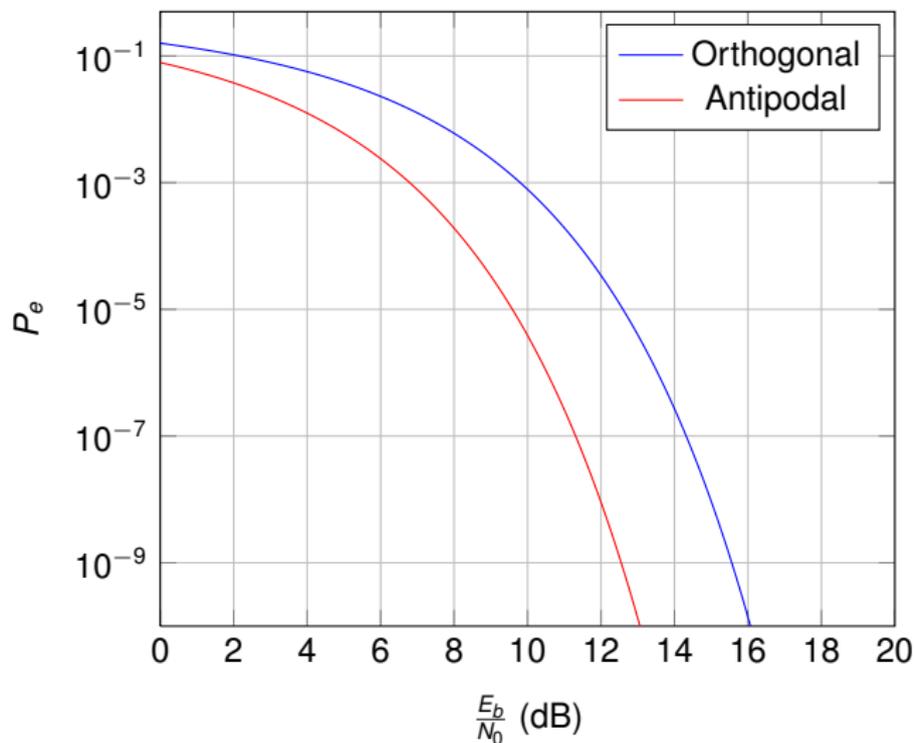
- For on-off keying, $s_1(t) = s(t)$ and $s_0(t) = 0$ and

$$P_e = Q\left(\sqrt{\frac{E_b}{N_0}}\right)$$

- For orthogonal signaling, $s_1(t)$ and $s_2(t)$ are orthogonal ($\langle s_0, s_1 \rangle = 0$)

$$P_e = Q\left(\sqrt{\frac{E_b}{N_0}}\right)$$

Performance Comparison of Antipodal and Orthogonal Signaling



Optimal Choice of Signal Pair

- For any $s_0(t)$ and $s_1(t)$, the probability of error of the ML decision rule is

$$P_e = Q\left(\frac{\|s_0 - s_1\|}{2\sigma}\right)$$

- How to choose $s_0(t)$ and $s_1(t)$ to minimize P_e ?
- If E_b is not fixed, the problem is ill-defined
- For a given E_b , we have

$$P_e = Q\left(\sqrt{\frac{\|s_0 - s_1\|^2}{2N_0}}\right) = Q\left(\sqrt{\frac{E_b(1 - \rho)}{N_0}}\right)$$

where

$$\rho = \frac{\langle s_0, s_1 \rangle}{E_b}, \quad -1 \leq \rho \leq 1$$

- $\rho = -1$ for antipodal signaling, $s_0(t) = -s_1(t)$
- **Any pair of antipodal signals is the optimal choice**

Complex AWGN Channel

ML Rule for Complex Baseband Binary Signaling

- Consider binary signaling in the complex AWGN channel

$$H_0 : y(t) = s_0(t) + n(t)$$

$$H_1 : y(t) = s_1(t) + n(t)$$

where

$y(t)$ Complex envelope of received signal

$s_i(t)$ Complex envelope of transmitted signal under H_i

$n(t)$ Complex white Gaussian noise with PSD $N_0 = 2\sigma^2$

- $n(t) = n_c(t) + jn_s(t)$ where $n_c(t)$ and $n_s(t)$ are independent WGN with PSD σ^2
- The ML decision rule is

$$\operatorname{Re}(\langle y, s_0 \rangle) - \frac{\|s_0\|^2}{2} \underset{H_1}{\overset{H_0}{>}} \operatorname{Re}(\langle y, s_1 \rangle) - \frac{\|s_1\|^2}{2}$$

$$\operatorname{Re}(\langle y, s_0 - s_1 \rangle) \underset{H_1}{\overset{H_0}{>}} \frac{\|s_0\|^2 - \|s_1\|^2}{2}$$

- The distribution of $\operatorname{Re}(\langle y, s_0 - s_1 \rangle)$ is required to evaluate decision rule performance

Performance of ML Rule for Complex Baseband Binary Signaling

- Let $Z = \text{Re}(\langle y, s_0 - s_1 \rangle)$
- Z is a Gaussian random variable

$$\begin{aligned} Z &= \text{Re}(\langle y, s_0 - s_1 \rangle) = \langle y_c, s_{0,c} - s_{1,c} \rangle + \langle y_s, s_{0,s} - s_{1,s} \rangle \\ &= \langle s_{i,c} + n_c, s_{0,c} - s_{1,c} \rangle + \langle s_{i,s} + n_s, s_{0,s} - s_{1,s} \rangle \\ &= \langle s_{i,c}, s_{0,c} - s_{1,c} \rangle + \langle n_c, s_{0,c} - s_{1,c} \rangle \\ &\quad + \langle s_{i,s}, s_{0,s} - s_{1,s} \rangle + \langle n_s, s_{0,s} - s_{1,s} \rangle \end{aligned}$$

- The mean and variance of Z under H_0 are

$$\begin{aligned} E[Z|H_0] &= \|s_{0,c}\|^2 + \|s_{0,s}\|^2 - \langle s_{0,c}, s_{1,c} \rangle - \langle s_{0,s}, s_{1,s} \rangle \\ &= \|s_0\|^2 - \text{Re}(\langle s_0, s_1 \rangle) \\ \text{var}[Z|H_0] &= \sigma^2 \|s_{0,c} - s_{1,c}\|^2 + \sigma^2 \|s_{0,s} - s_{1,s}\|^2 = \sigma^2 \|s_0 - s_1\|^2 \end{aligned}$$

- Probability of error under H_0 is

$$P_{e|0} = \Pr \left[Z \leq \frac{\|s_0\|^2 - \|s_1\|^2}{2} \middle| H_0 \right] = Q \left(\frac{\|s_0 - s_1\|}{2\sigma} \right)$$

Performance of ML Rule for Complex Baseband Binary Signaling

- The mean and variance of Z under H_1 are

$$\begin{aligned}E[Z|H_1] &= \langle \mathbf{s}_{1,c}, \mathbf{s}_{0,c} \rangle + \langle \mathbf{s}_{1,s}, \mathbf{s}_{0,s} \rangle - \|\mathbf{s}_{1,c}\|^2 - \|\mathbf{s}_{1,s}\|^2 \\ &= \operatorname{Re}(\langle \mathbf{s}_1, \mathbf{s}_0 \rangle) - \|\mathbf{s}_1\|^2 \\ \operatorname{var}[Z|H_1] &= \sigma^2 \|\mathbf{s}_{0,c} - \mathbf{s}_{1,c}\|^2 + \sigma^2 \|\mathbf{s}_{0,s} - \mathbf{s}_{1,s}\|^2 = \sigma^2 \|\mathbf{s}_0 - \mathbf{s}_1\|^2\end{aligned}$$

- Probability of error under H_1 is

$$P_{e|1} = \Pr \left[Z > \frac{\|\mathbf{s}_0\|^2 - \|\mathbf{s}_1\|^2}{2} \middle| H_1 \right] = Q \left(\frac{\|\mathbf{s}_0 - \mathbf{s}_1\|}{2\sigma} \right)$$

- The average probability of error is

$$P_e = \frac{P_{e|0} + P_{e|1}}{2} = Q \left(\frac{\|\mathbf{s}_0 - \mathbf{s}_1\|}{2\sigma} \right)$$

Thanks for your attention