

Op-Amp Circuits: Part 4



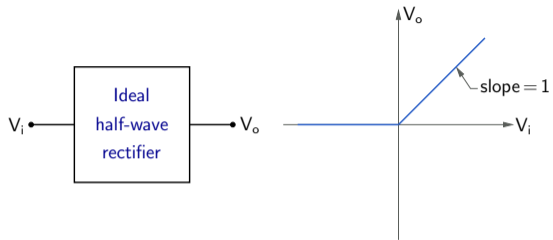
M. B. Patil

mbpatil@ee.iitb.ac.in

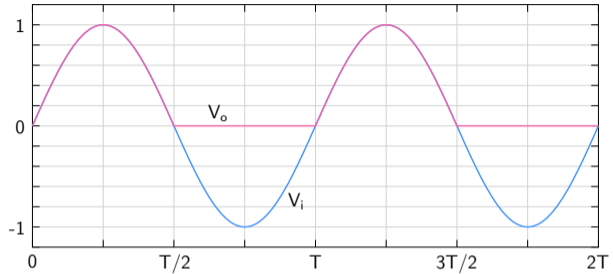
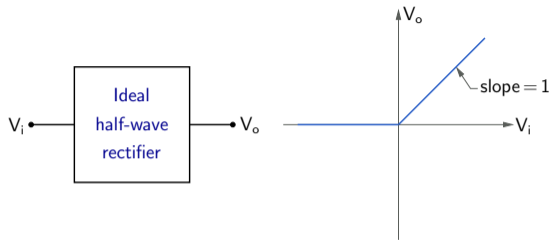
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Department of Electrical Engineering
Indian Institute of Technology Bombay

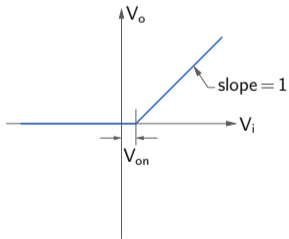
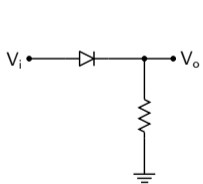
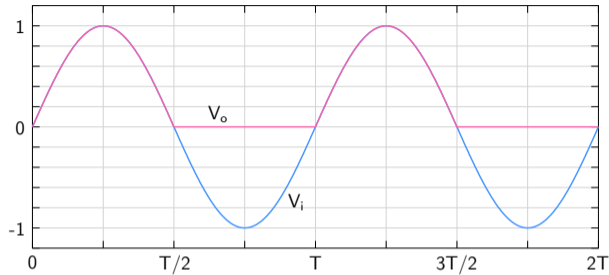
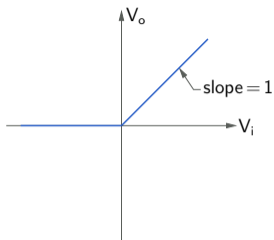
Half-wave rectifier



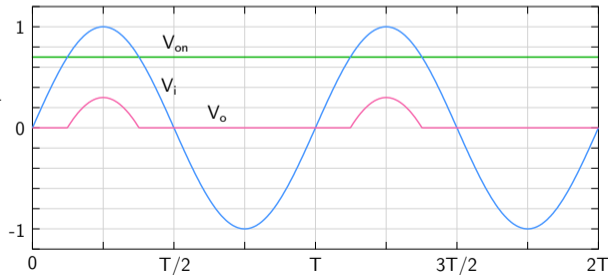
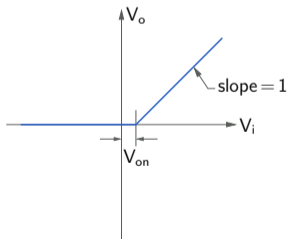
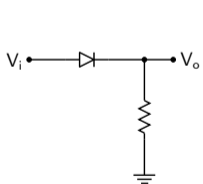
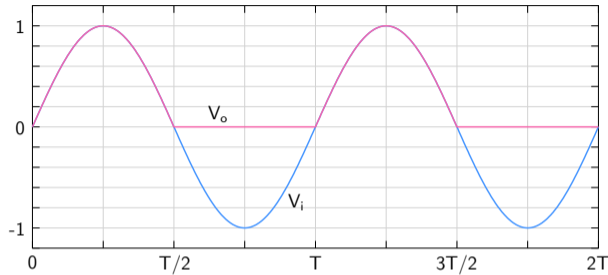
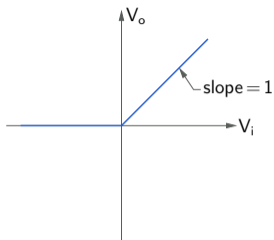
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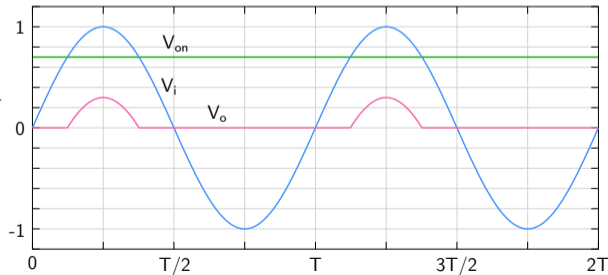
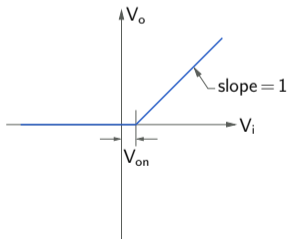
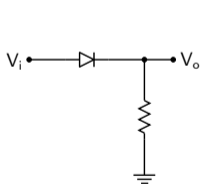
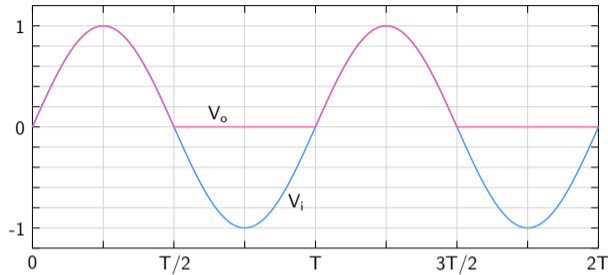
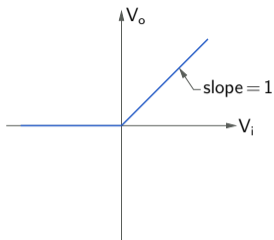
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Half-wave rectifier

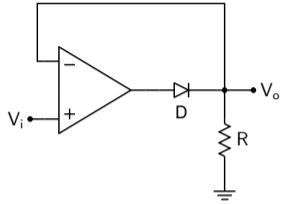


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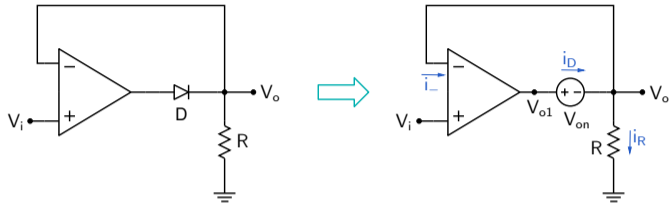


→ need an improved circuit

Half-wave precision rectifier



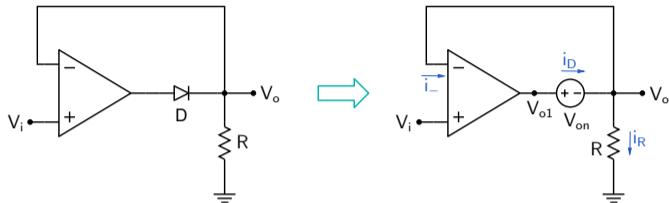
Half-wave precision rectifier



Consider two cases:

- (i) D is conducting: The feedback loop is closed, and the circuit looks like (except for the diode drop) the buffer we have seen earlier.

Half-wave precision rectifier



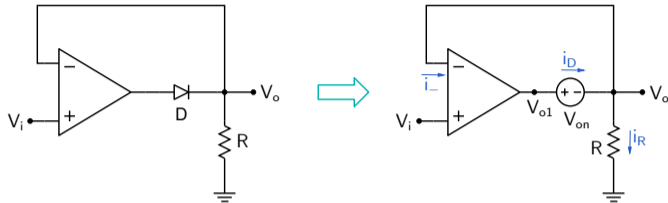
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Since the input current $i_- \approx 0$, $i_R = i_D$.

$$V_+ - V_- = \frac{V_{o1}}{A_V} = \frac{V_o + 0.7V}{A_V} \approx 0V \rightarrow V_o = V_- \approx V_+ = V_i.$$

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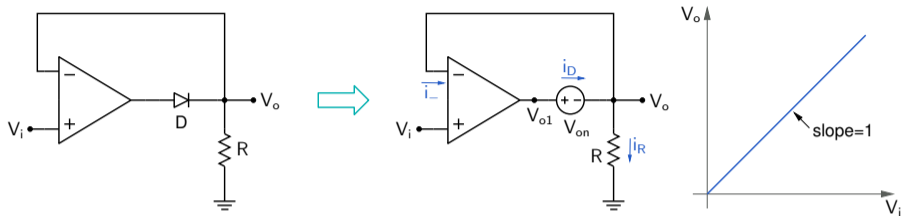
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This situation arises only if $i_D > 0$ (since the diode can only conduct in the forward direction), i.e., $i_R > 0 \rightarrow V_o = i_R R > 0$, and therefore $V_i = V_o > 0 \text{ V}$.

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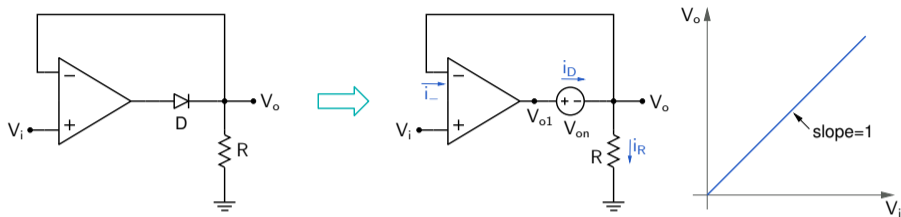
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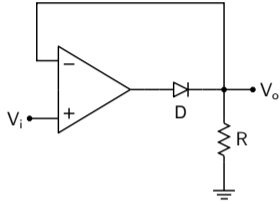
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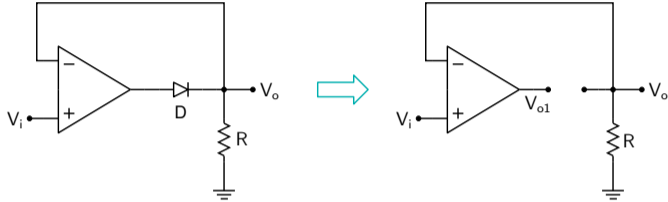
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Note: V_{on} does not appear in the graph.

Half-wave precision rectifier

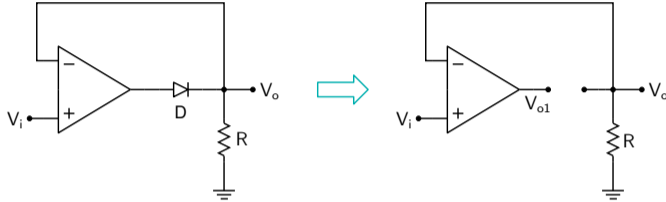


Half-wave precision rectifier



(ii) D is not conducting $\rightarrow V_o = 0 V$.

Half-wave precision rectifier

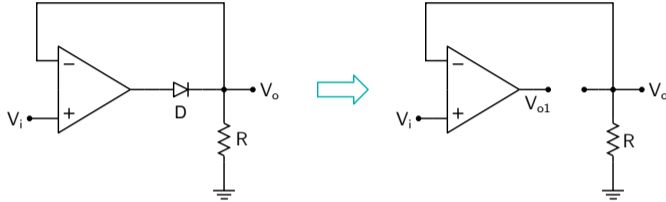


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What about V_{o1} ?

Since the op-amp is now in the open-loop configuration, a very small V_i is enough to drive it to saturation.

Half-wave precision rectifier



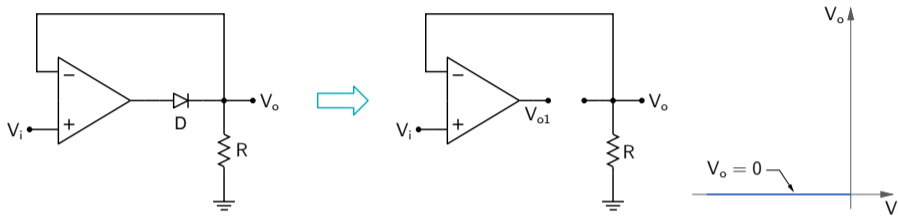
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Half-wave precision rectifier



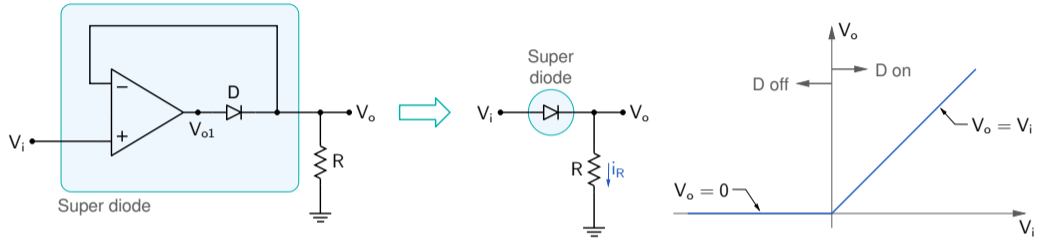
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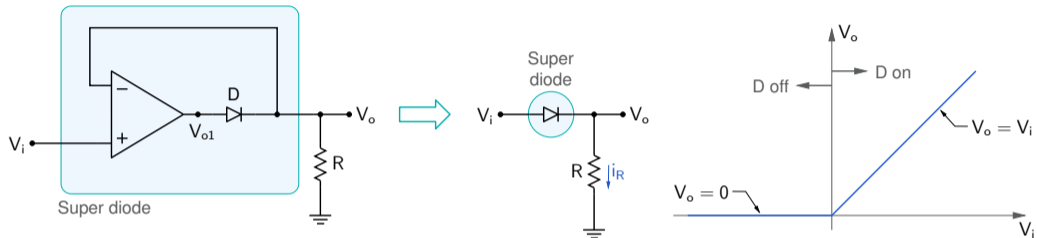
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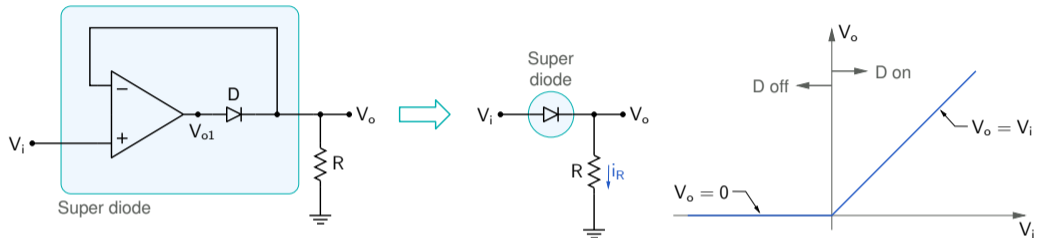


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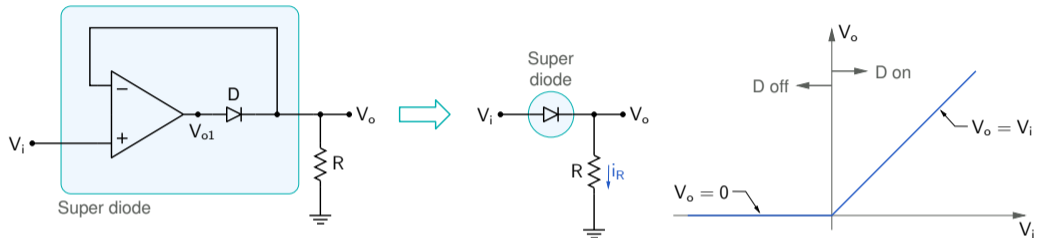
* The circuit is called "super diode" (an ideal diode with $V_{on} = 0\text{V}$).

Half-wave precision rectifier



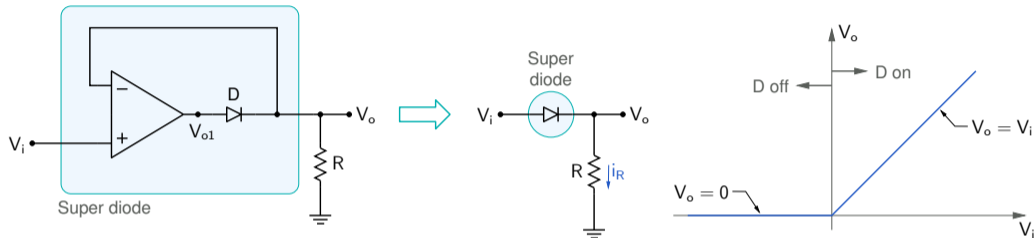
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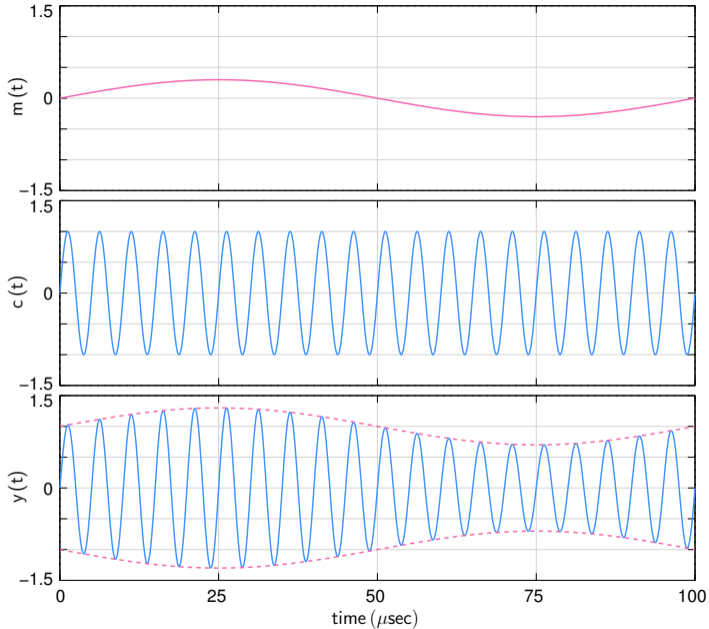
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- * Where does i_R come from?

$A = 1$
 $M = 0.3$
 $f_c = 200 \text{ kHz}$
 $f_m = 10 \text{ kHz}$

Application: AM demodulation

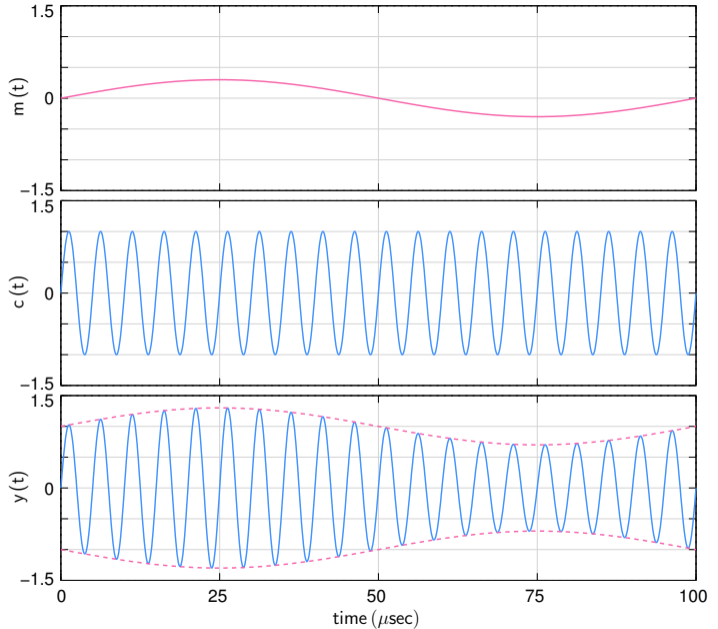


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Application: AM demodulation

Carrier wave:

$$c(t) = A \sin(2\pi f_c t)$$



$$\begin{aligned} A &= 1 \\ M &= 0.3 \\ f_c &= 200 \text{ kHz} \\ f_m &= 10 \text{ kHz} \end{aligned}$$

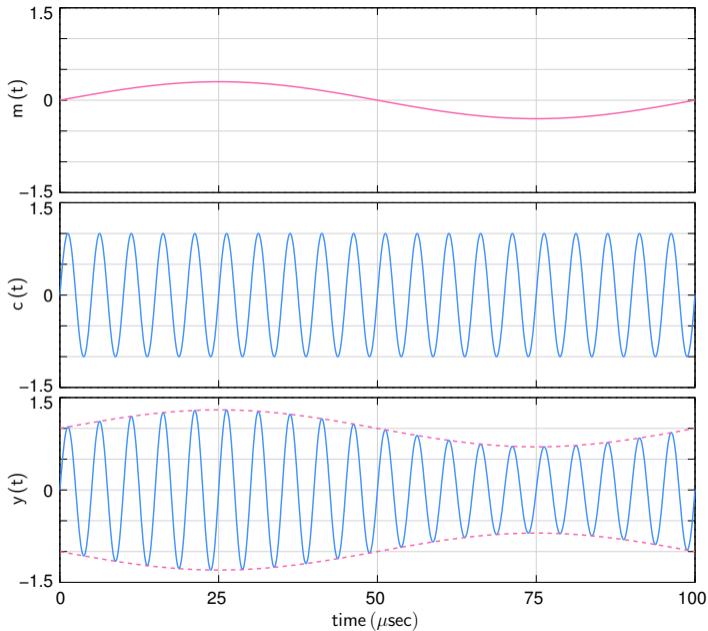
Application: AM demodulation

Carrier wave:

$$c(t) = A \sin(2\pi f_c t)$$

Signal (e.g., audio):

$$m(t) = M \sin(2\pi f_m t + \phi)$$



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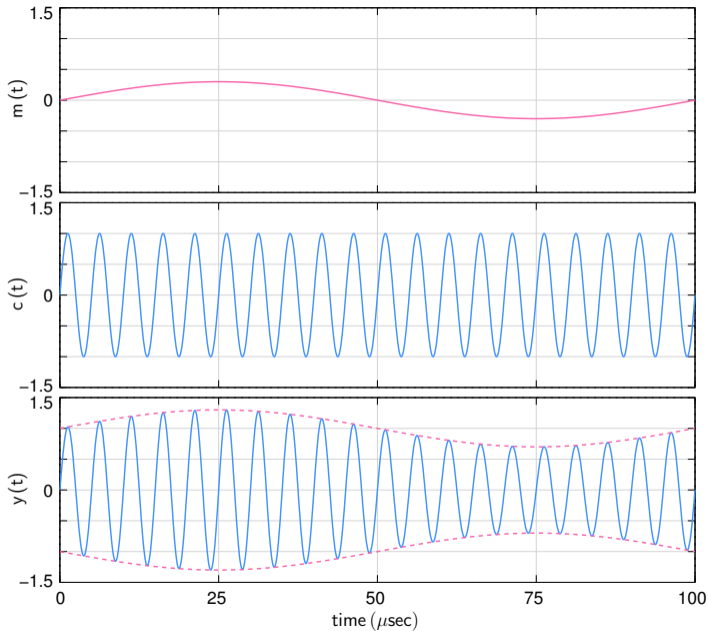
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AM wave:

$$y(t) = [1 + m(t)] c(t)$$

(Assume $M < 1$)



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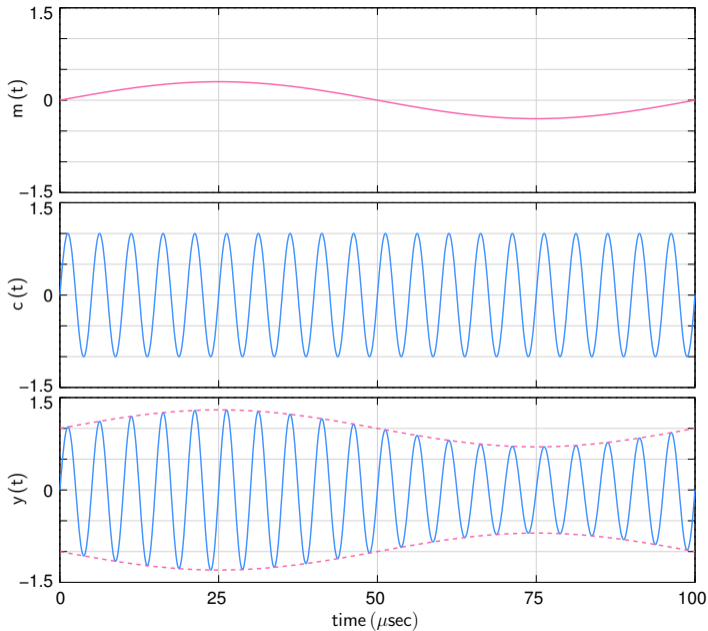
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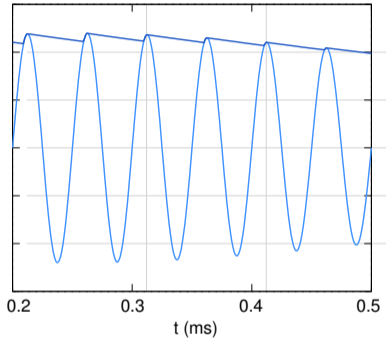
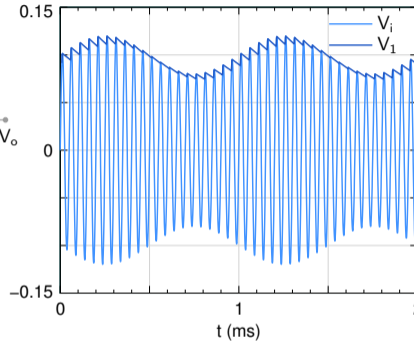
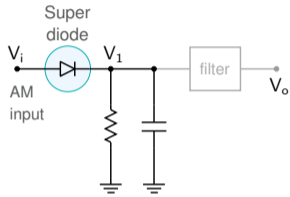
e.g., Vividh Bharati:

$$f_c = 1188 \text{ kHz},$$

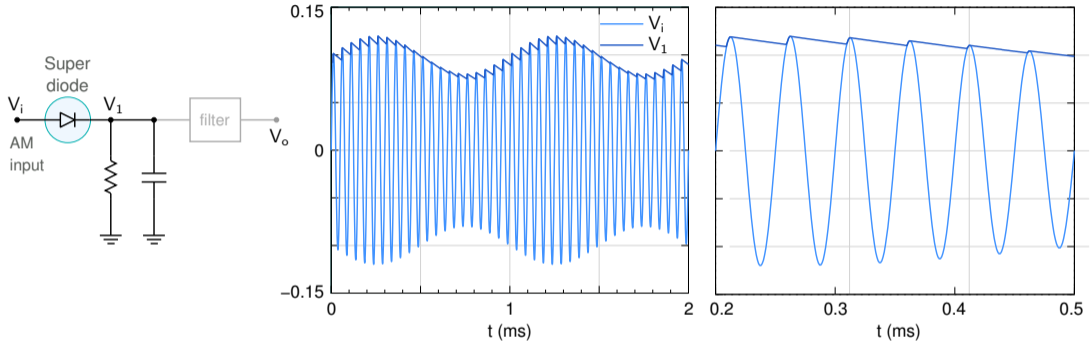
$$f_m \simeq 10 \text{ kHz (audio).}$$



AM demodulation using a peak detector

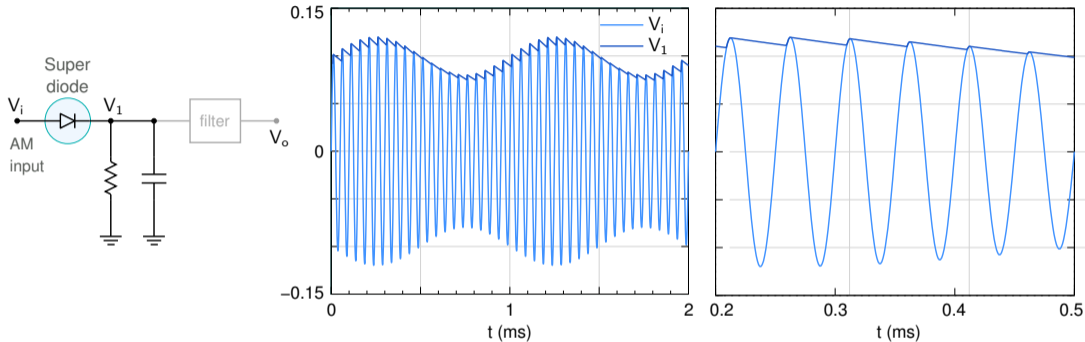


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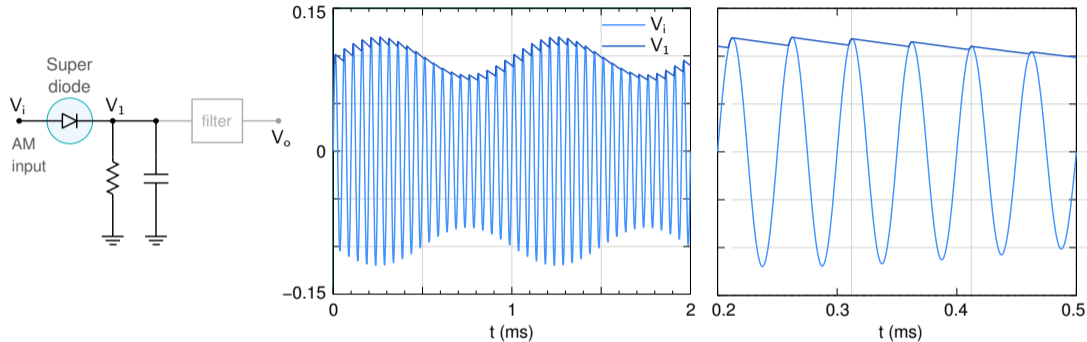
* charging through super diode, discharging through resistor

AM demodulation using a peak detector



- * charging through super diode, discharging through resistor
- * The time constant (RC) needs to be carefully selected.

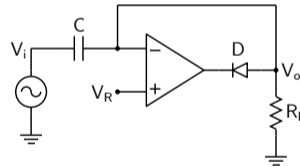
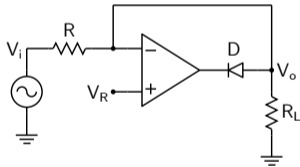
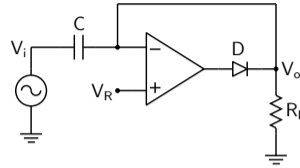
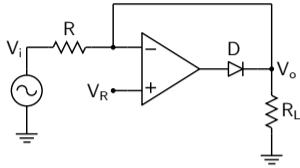
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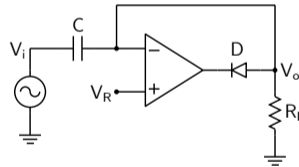
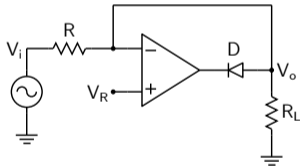
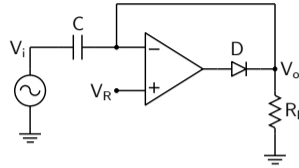
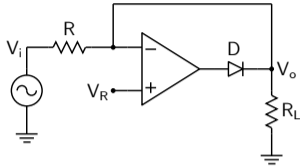
SEQUEL file: [super_diode.sqproj](#)

Clipping and clamping

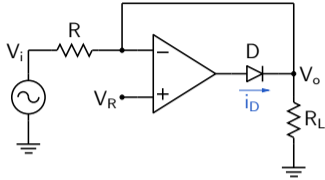


* What is the function provided by each circuit?

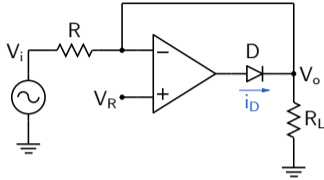
Clipping and clamping



- * What is the function provided by each circuit?
- * Verify with simulation (and in the lab).

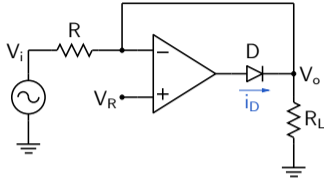


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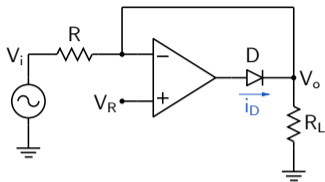
$$\text{KCL: } i_D = \frac{V_R}{R_L} + \frac{V_R - V_i}{R}.$$



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$$\text{Since } i_D > 0, \quad V_R \left(\frac{1}{R_L} + \frac{1}{R} \right) > \frac{V_i}{R} \rightarrow V_i < V_R \left(\frac{R + R_L}{R_L} \right) \equiv V_{i1}.$$

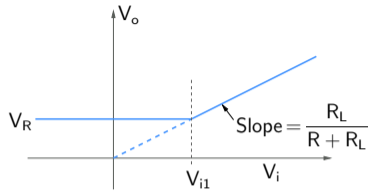
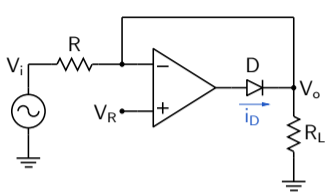


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For $V_i > V_{i1}$, D does not conduct $\rightarrow V_o = \frac{R_L}{R + R_L} V_i$.

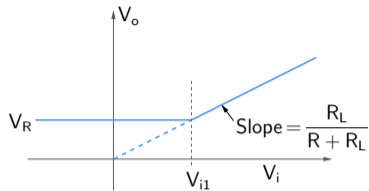
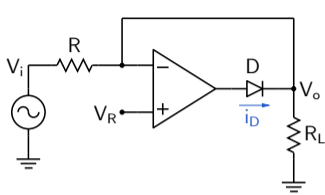


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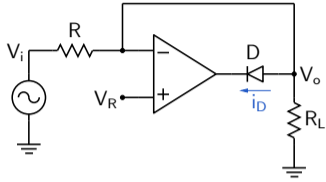
When D conducts, feedback path is closed $\rightarrow V_- \approx V_+ = V_R \rightarrow V_o = V_R$.

$$\text{KCL: } i_D = \frac{V_R}{R_L} + \frac{V_R - V_i}{R}.$$

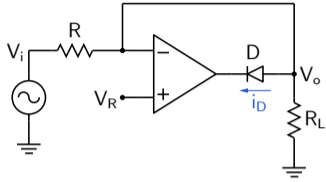
$$\text{Since } i_D > 0, V_R \left(\frac{1}{R_L} + \frac{1}{R} \right) > \frac{V_i}{R} \rightarrow V_i < V_R \left(\frac{R + R_L}{R_L} \right) \equiv V_{i1}.$$

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If $R_L \gg R$, $V_{i1} = R$, and slope = 1 for $V_i > V_{i1}$.

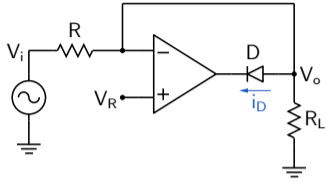


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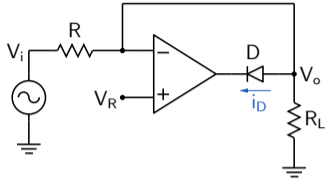
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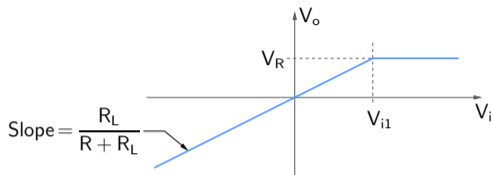
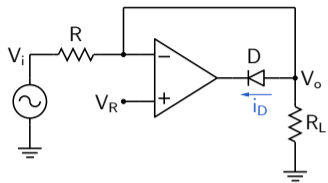


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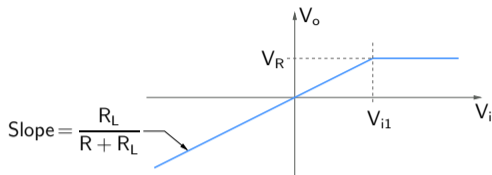
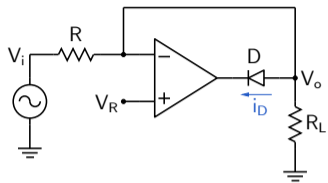


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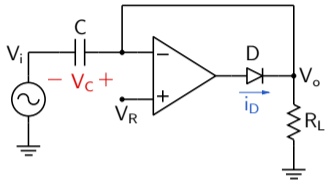
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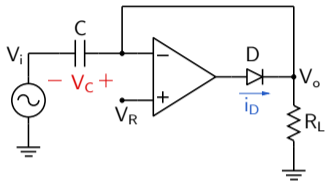
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Time constant for the discharging process is $R_L C$.

Assume $R_L C \gg T \rightarrow V_C$ can only increase (in one cycle).

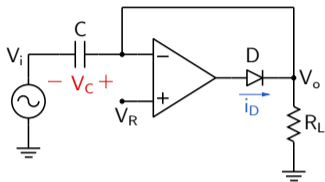


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$\rightarrow V_C^{\max} = V_R - (-V_m) = V_R + V_m$.



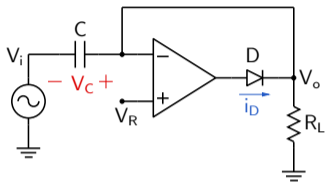
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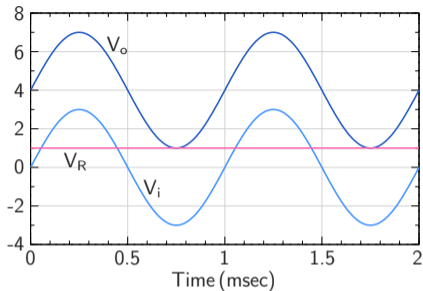
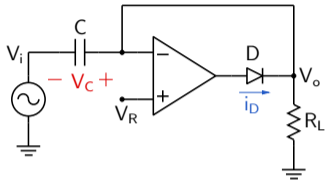
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Note: V_{on} of the diode does not appear in the expression for $V_o(t)$.



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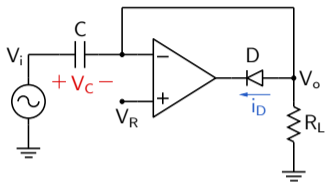
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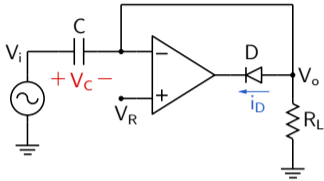
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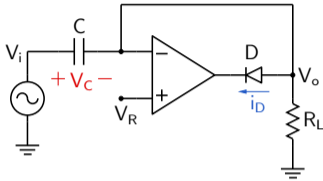


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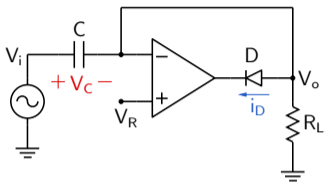
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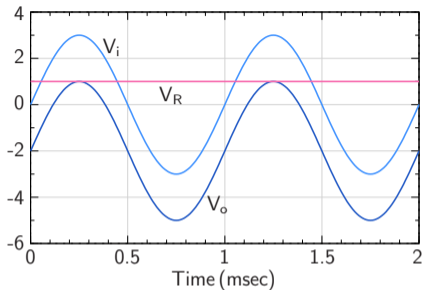
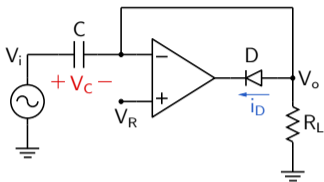
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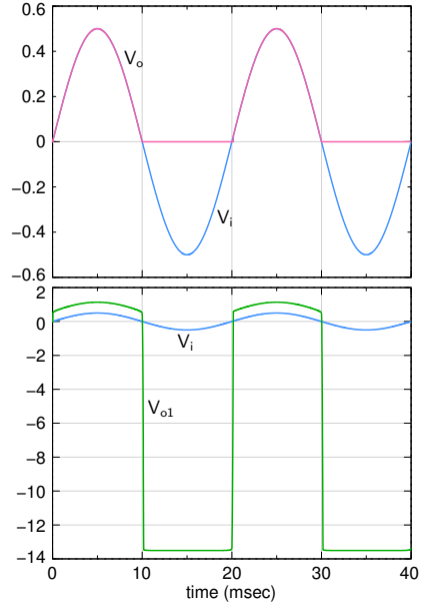
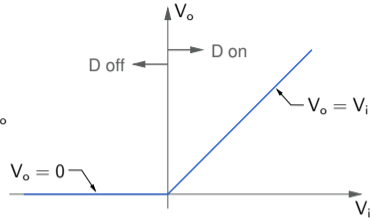
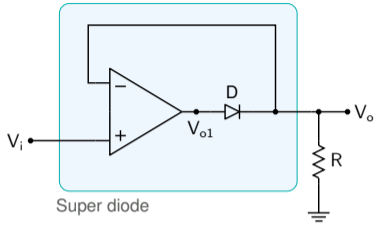
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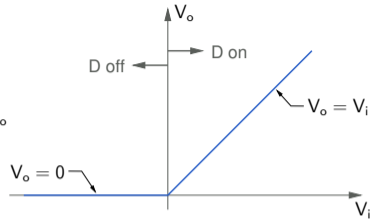
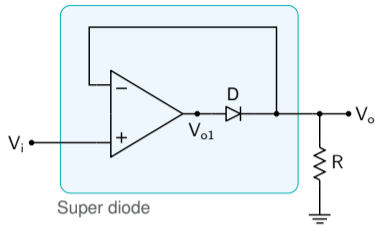
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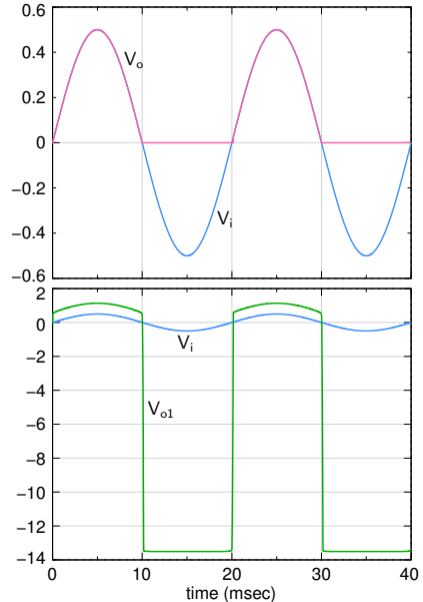
Half-wave precision rectifier



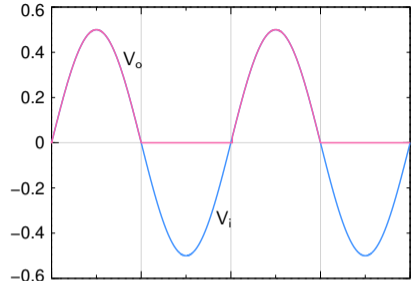
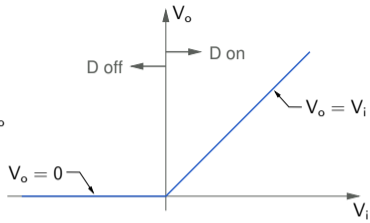
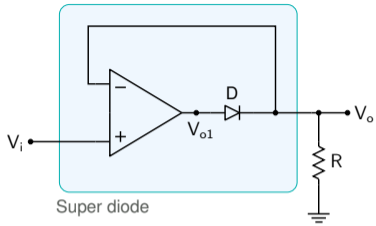
Half-wave precision rectifier



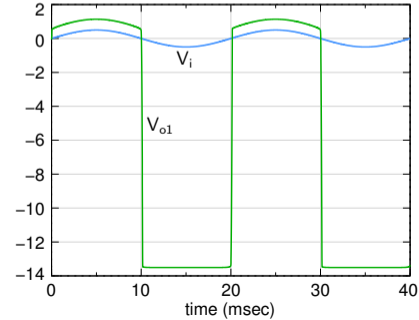
- * When $V_i > 0$, the op-amp operates in the linear region, and $V_{o1} = V_o + V_{on}$.



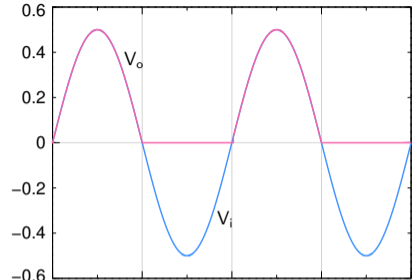
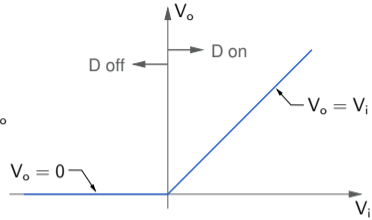
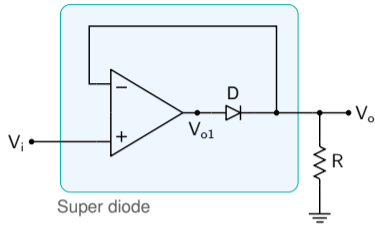
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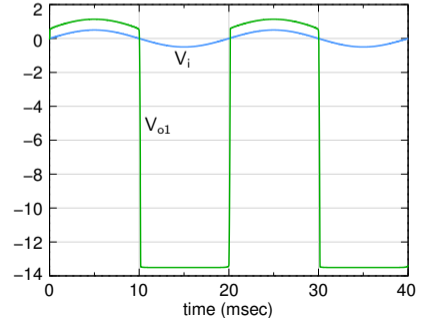
- * When $V_i > 0$, the op-amp operates in the linear region, and $V_{o1} = V_o + V_{on}$.
- * When $V_i < 0$, the op-amp operates in the open-loop configuration, leading to saturation, and $V_{o1} = -V_{sat}$.



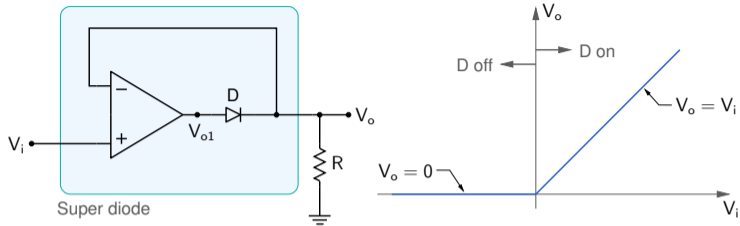
Half-wave precision rectifier



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- * The $V_i < 0$ to $V_i > 0$ transition requires the op-amp to come out of saturation. This is a relatively slow process and is limited by the op-amp slew rate.

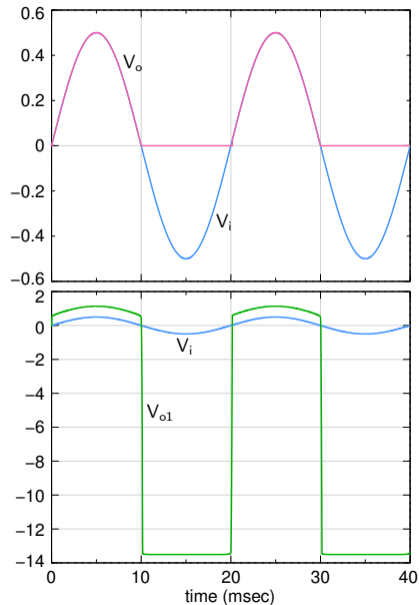


Half-wave precision rectifier

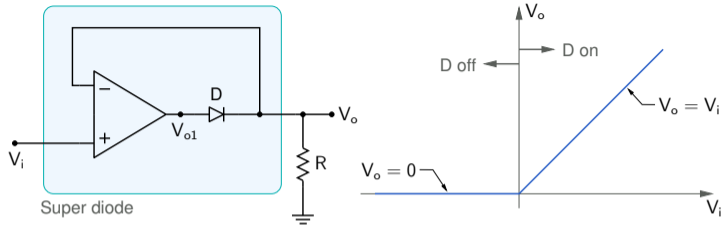


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SEQUEL file: ee101_super_diode.1.sqproj

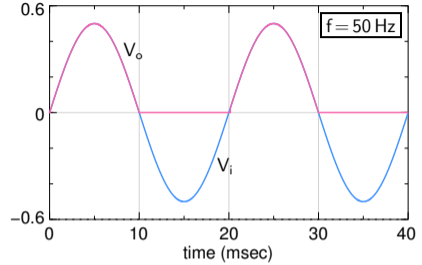
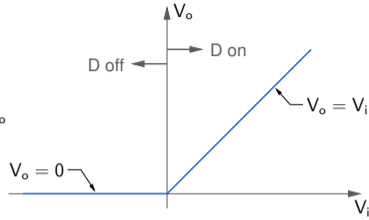
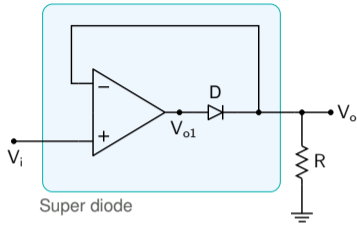


Half-wave precision rectifier



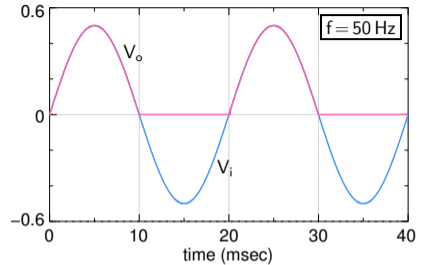
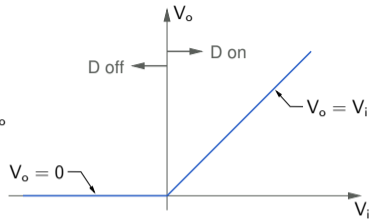
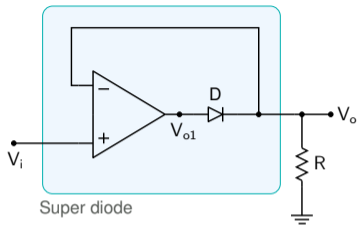
- * The time taken by the op-amp to come out of saturation can be neglected at low signal frequencies.

Half-wave precision rectifier



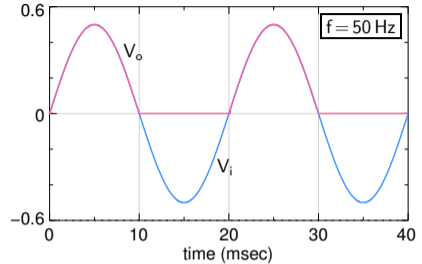
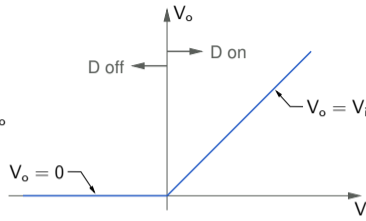
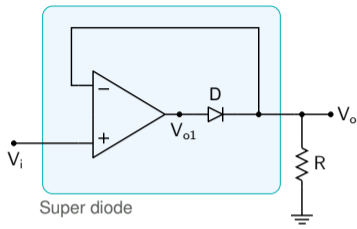
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Half-wave precision rectifier

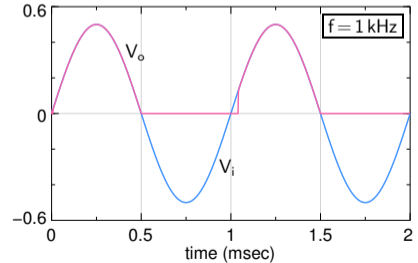


- * The time taken by the op-amp to come out of saturation can be neglected at low signal frequencies.
- * At high signal frequencies, it leads to distortion in the output waveform.

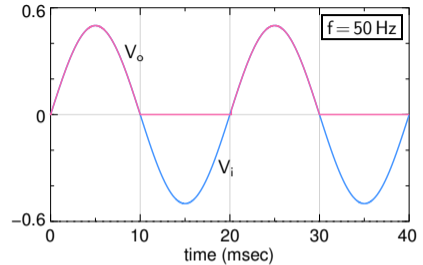
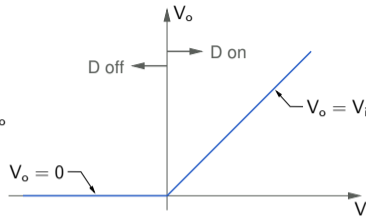
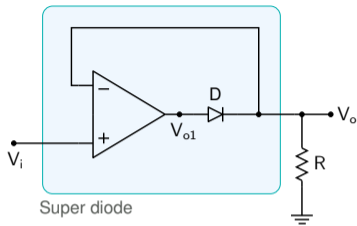
Half-wave precision rectifier



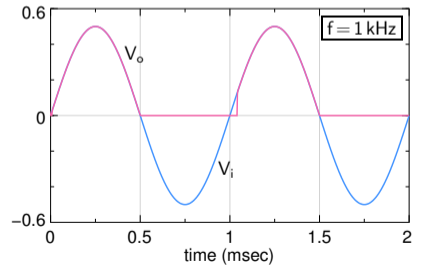
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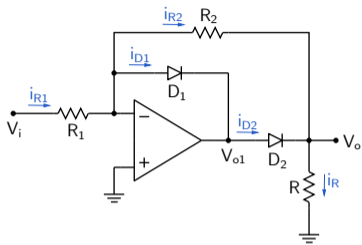
Half-wave precision rectifier



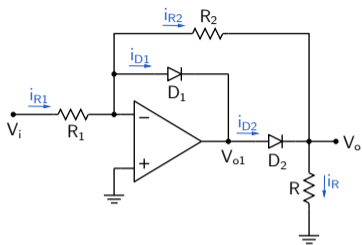
- * The time taken by the op-amp to come out of saturation can be neglected at low signal frequencies.
- * At high signal frequencies, it leads to distortion in the output waveform.
- * Hook up the circuit in the lab, and check it out!



Improved half-wave precision rectifier

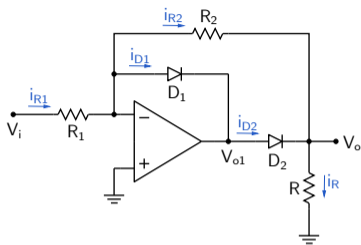


Improved half-wave precision rectifier



(i) D_1 conducts: $V_- = V_+ = 0\text{ V}$, $V_{o1} = -V_{D1} \approx -0.7\text{ V}$.

Improved half-wave precision rectifier

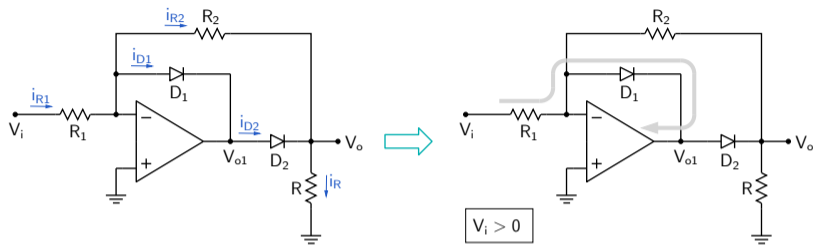


(i) D_1 conducts: $V_- = V_+ = 0\text{ V}$, $V_{o1} = -V_{D1} \approx -0.7\text{ V}$.

D_2 cannot conduct (show that, if it did, KCL is not satisfied at V_o).

$\rightarrow i_{R2} = 0$, $V_o = V_- = 0\text{ V}$.

Improved half-wave precision rectifier

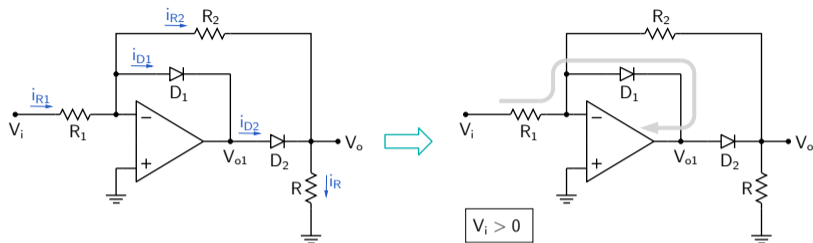


(i) D_1 conducts: $V_- = V_+ = 0$ V, $V_{o1} = -V_{D1} \approx -0.7$ V.

D_2 cannot conduct (show that, if it did, KCL is not satisfied at V_o).

$\rightarrow i_{R2} = 0$, $V_o = V_- = 0$ V.

Improved half-wave precision rectifier



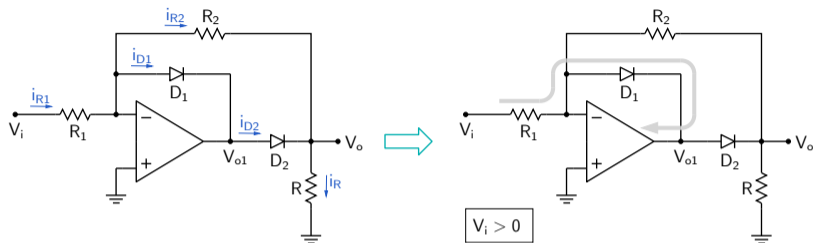
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$i_{R1} = i_{D1}$ which can only be positive $\Rightarrow V_i > 0 \text{ V}$.

Improved half-wave precision rectifier



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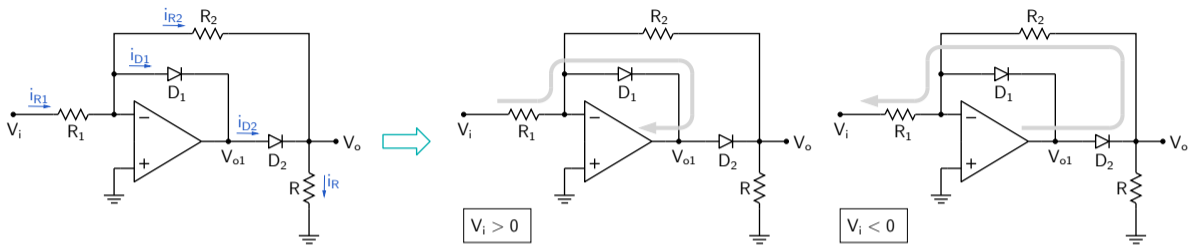
D_2 cannot conduct (show that, if it did, KCL is not satisfied at V_o).

$\rightarrow i_{R2} = 0$, $V_o = V_- = 0 \text{ V}$.

$i_{R1} = i_{D1}$ which can only be positive $\Rightarrow V_i > 0 \text{ V}$.

(ii) D_1 is off; this will happen when $V_i < 0 \text{ V}$.

Improved half-wave precision rectifier



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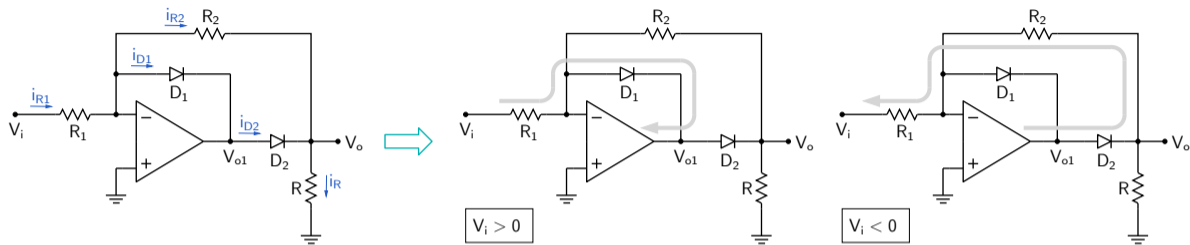
$\rightarrow i_{R2} = 0$, $V_o = V_- = 0$ V.

$i_{R1} = i_{D1}$ which can only be positive $\Rightarrow V_i > 0$ V.

(ii) D_1 is off; this will happen when $V_i < 0$ V.

In this case, D_2 conducts and closes the feedback loop through R_2 .

Improved half-wave precision rectifier



(i) D_1 conducts: $V_- = V_+ = 0\text{ V}$, $V_{o1} = -V_{D1} \approx -0.7\text{ V}$.

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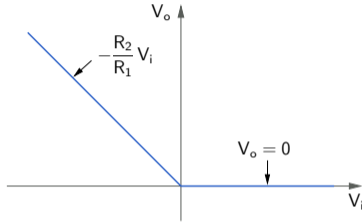
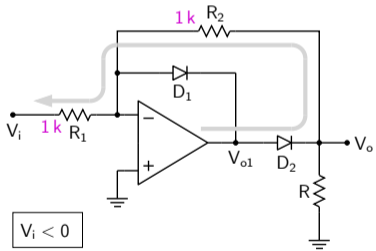
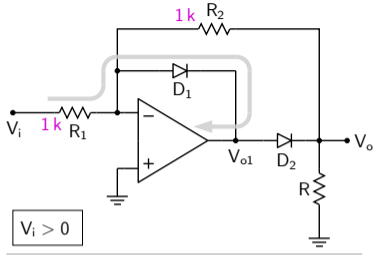
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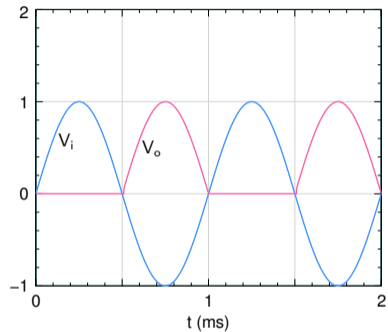
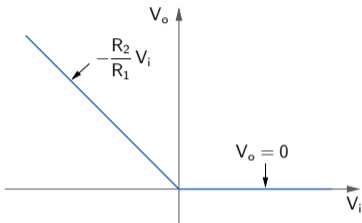
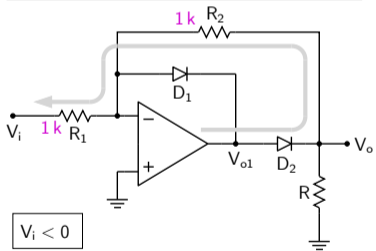
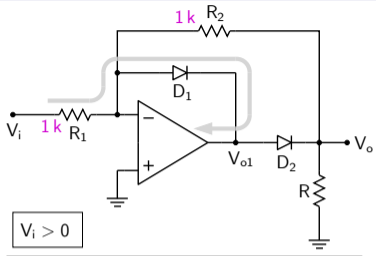
In this case, D_2 conducts and closes the feedback loop through R_2 .

$$V_o = V_- + i_{R2}R_2 = 0 + \left(\frac{0 - V_i}{R_1}\right) R_2 = -\frac{R_2}{R_1} V_i.$$

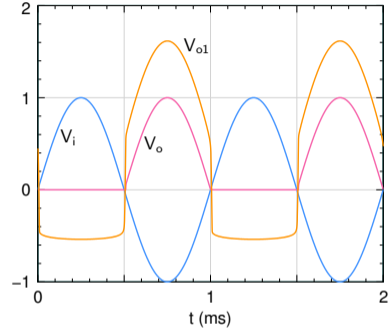
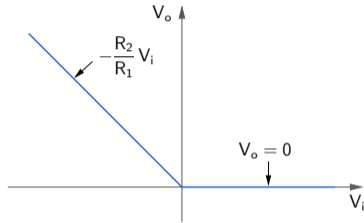
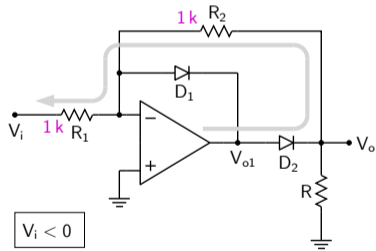
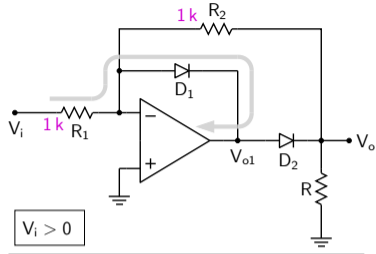
Improved half-wave precision rectifier



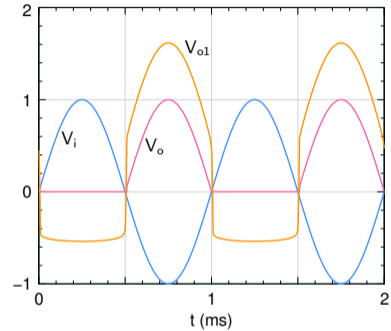
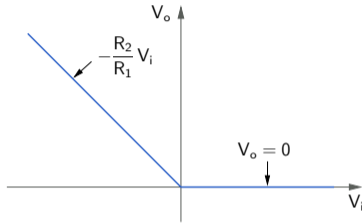
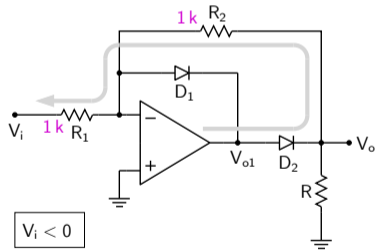
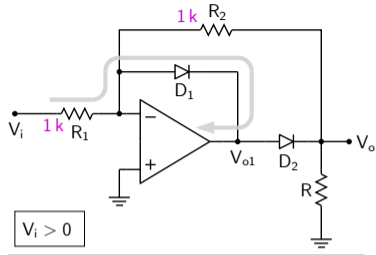
Improved half-wave precision rectifier



Improved half-wave precision rectifier

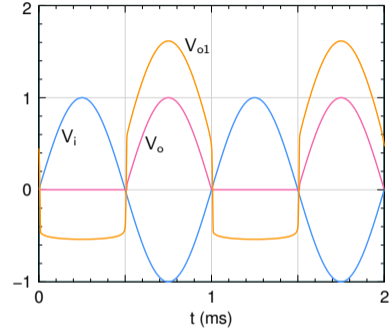
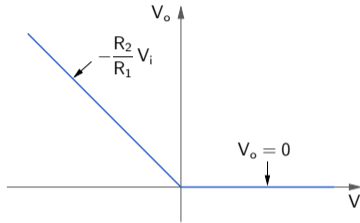
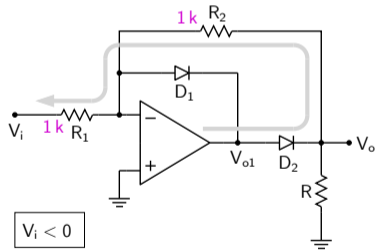
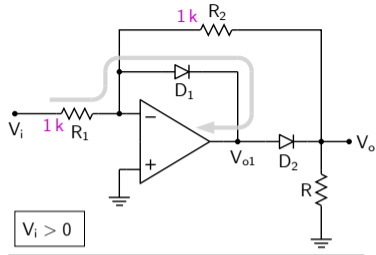


Improved half-wave precision rectifier



* Note that the op-amp does not enter saturation since a feedback path is available for $V_i > 0$ V and $V_i < 0$ V.

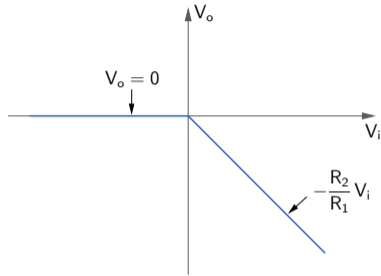
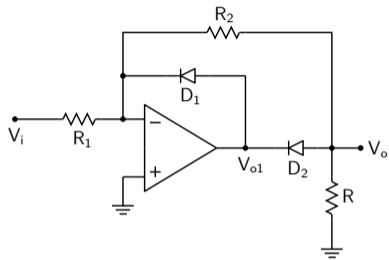
Improved half-wave precision rectifier



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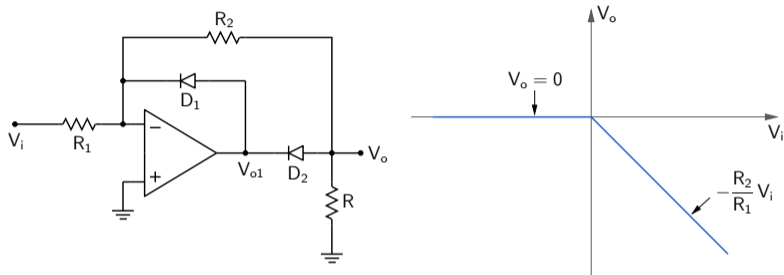
SEQUEL file: precision_half_wave.sqproj

Improved half-wave precision rectifier



The diodes are now reversed.

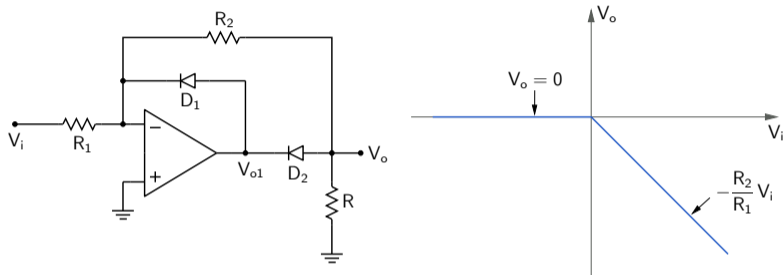
Improved half-wave precision rectifier



The diodes are now reversed.

By considering two cases: (i) D_1 on, (ii) D_1 off, the V_o versus V_i relationship shown in the figure is obtained (show this).

Improved half-wave precision rectifier

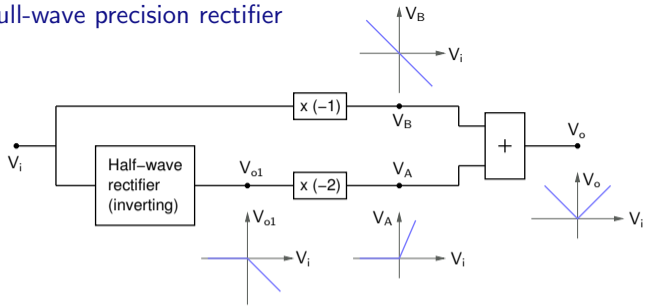


The diodes are now reversed.

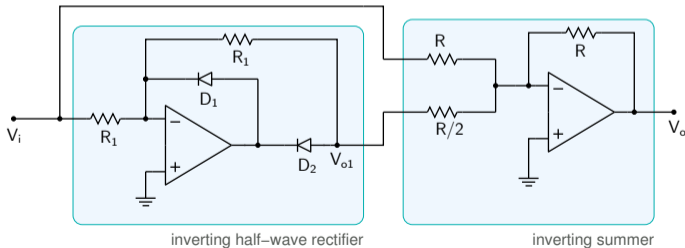
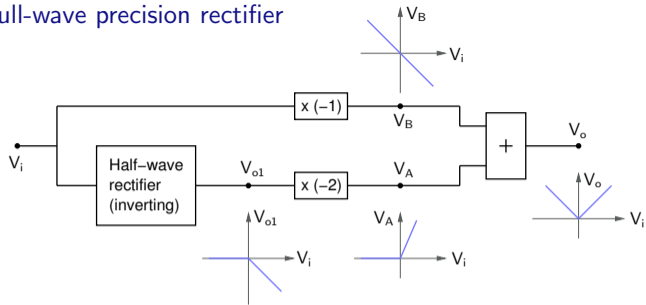
By considering two cases: (i) D_1 on, (ii) D_1 off, the V_o versus V_i relationship shown in the figure is obtained (show this).

SEQUEL file: precision_half_wave_2.sqproj

Full-wave precision rectifier

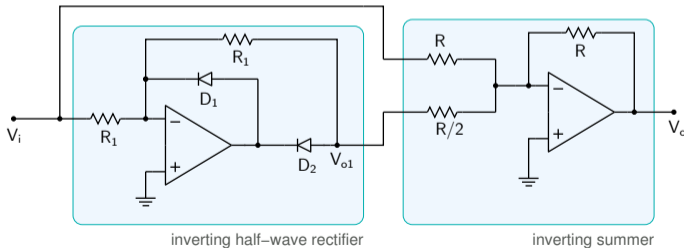
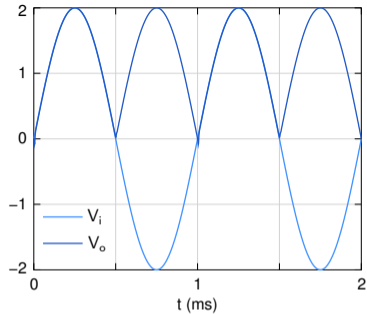
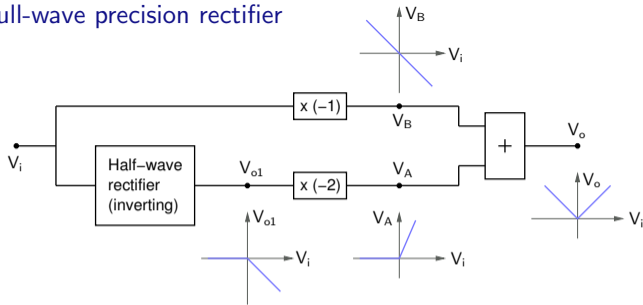


Full-wave precision rectifier



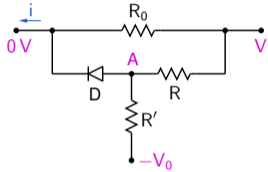
(SEQUEL file: precision_full_wave.sqproj)

Full-wave precision rectifier

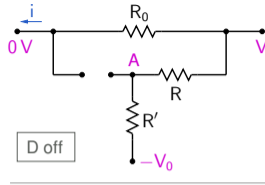
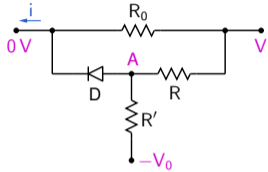


(SEQUEL file: precision_full_wave.sqproj)

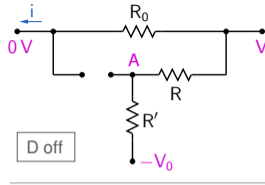
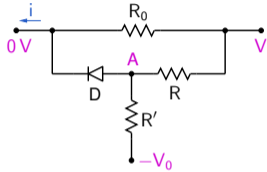
Wave shaping with diodes



Wave shaping with diodes

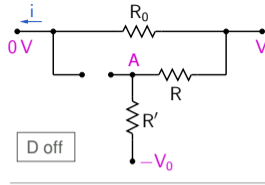
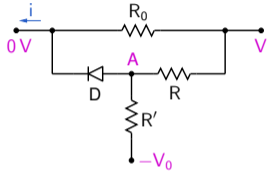


Wave shaping with diodes



When D is off, $i = \frac{V}{R_0}$, and V_A is (by superposition), $V_A = V \frac{R'}{R + R'} - V_0 \frac{R}{R + R'}$.

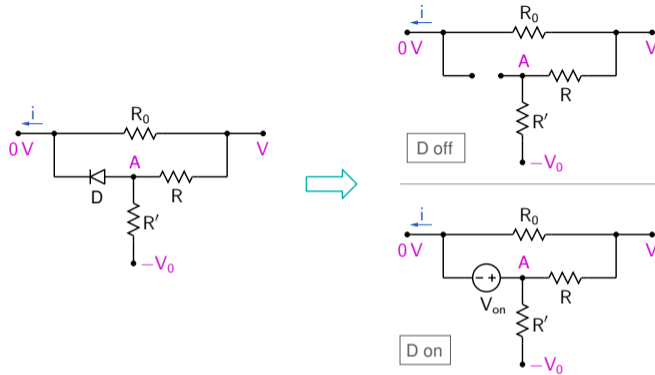
Wave shaping with diodes



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For D to turn on, $V_A = V_{\text{on}} \approx 0.7 \text{ V} \rightarrow V \equiv V_{\text{break}} = \frac{R}{R'} (V_0 + V_{\text{on}}) + V_{\text{on}}$.

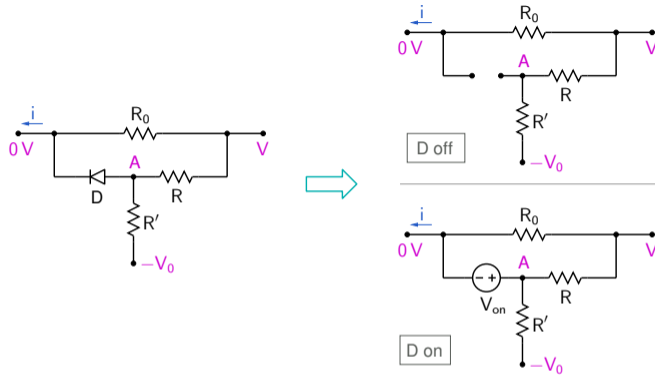
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Wave shaping with diodes

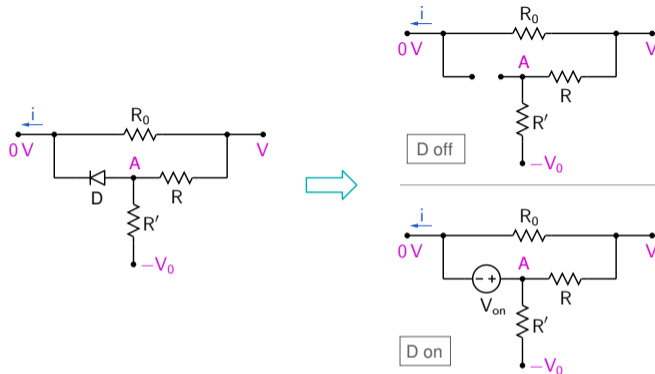


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When D is on, $i = \frac{V}{R_0} + \frac{V - V_{on}}{R} + \frac{-V_0 - V_{on}}{R'} = V \left[\frac{1}{R_0} + \frac{1}{R} \right] + (\text{constant})$

Wave shaping with diodes



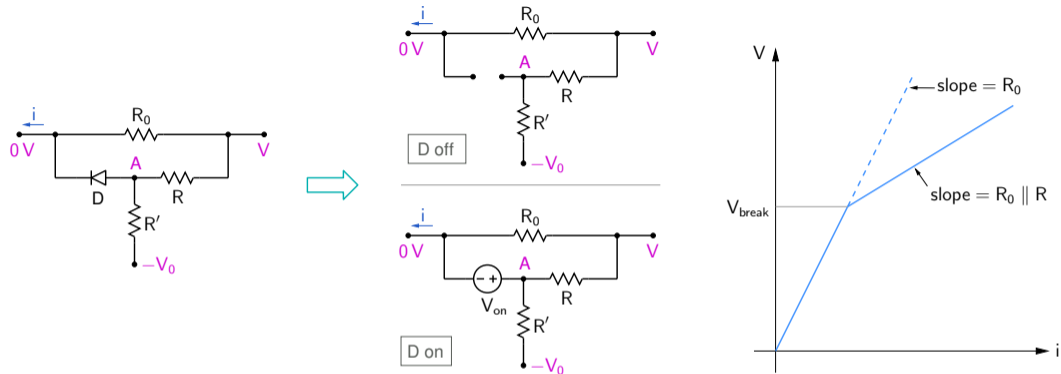
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i.e., $V = (R_0 \parallel R) i + (\text{constant})$.

Wave shaping with diodes



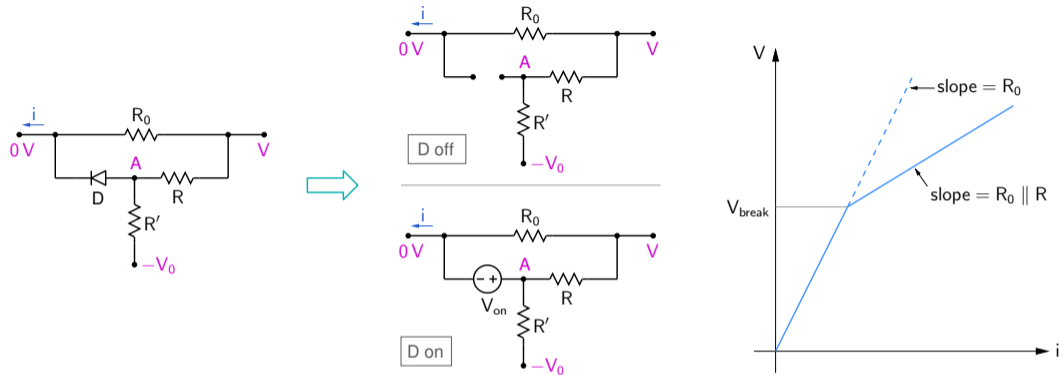
When D is off, $i = \frac{V}{R_0}$, and V_A is (by superposition), $V_A = V \frac{R'}{R + R'} - V_0 \frac{R}{R + R'}$.

For D to turn on, $V_A = V_{on} \approx 0.7 V \rightarrow V \equiv V_{break} = \frac{R}{R'} (V_0 + V_{on}) + V_{on}$.

When D is on, $i = \frac{V}{R_0} + \frac{V - V_{on}}{R} + \frac{-V_0 - V_{on}}{R'} = V \left[\frac{1}{R_0} + \frac{1}{R} \right] + (\text{constant})$

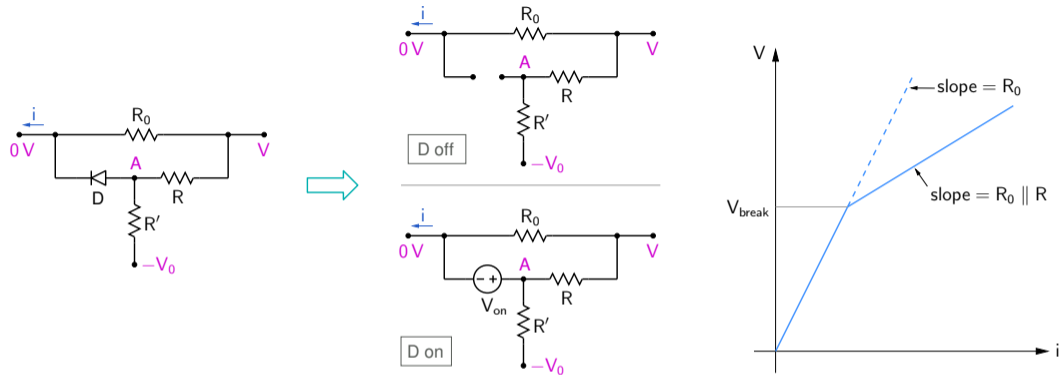
i.e., $V = (R_0 \parallel R) i + (\text{constant})$.

Wave shaping with diodes



(a) $V_{break} = \frac{R}{R'} (V_0 + V_{on}) + V_{on}$. (b) When D is on, $V = (R_0 \parallel R) i + (\text{constant})$.

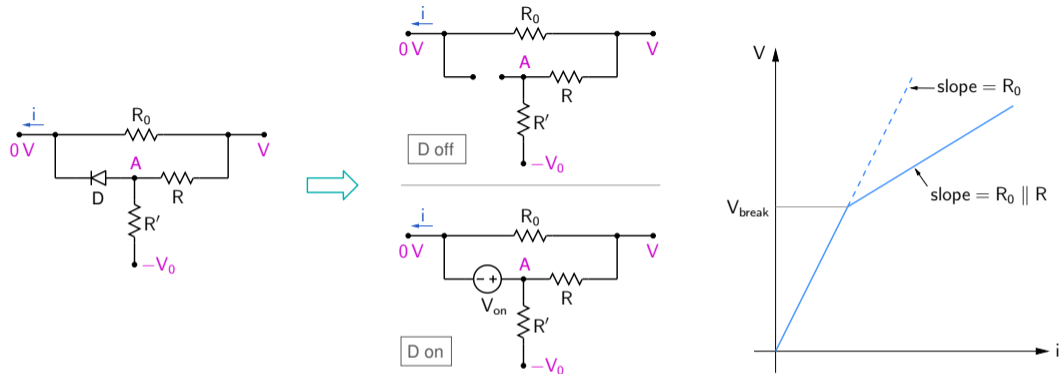
Wave shaping with diodes



(a) $V_{break} = \frac{R}{R'} (V_0 + V_{on}) + V_{on}$. (b) When D is on, $V = (R_0 \parallel R) i + (\text{constant})$.

* V_{break} depends on the ratio R/R' .

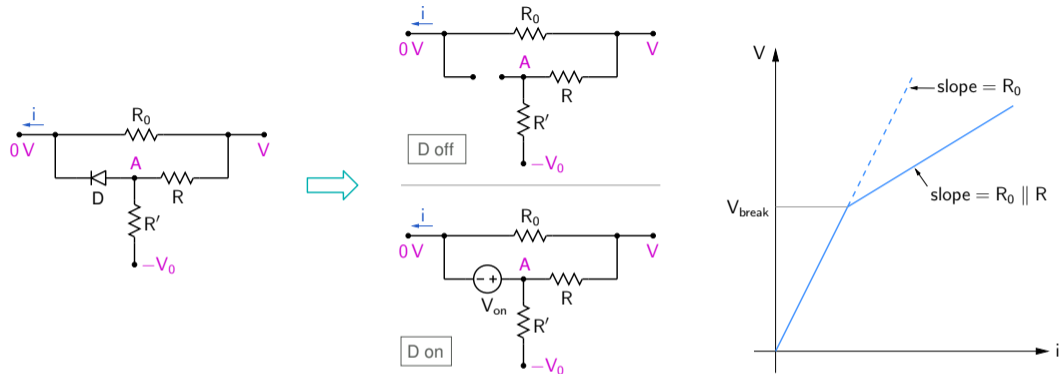
Wave shaping with diodes



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* V_{break} depends on the ratio R/R' .

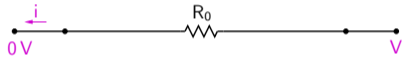
* The slope $R_0 \parallel R$ depends on the resistance values.



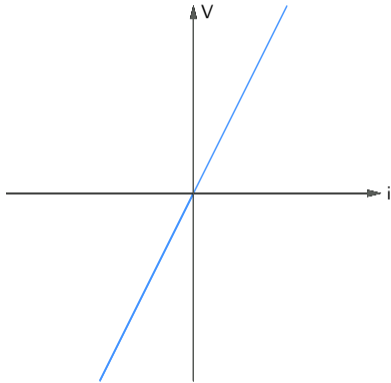
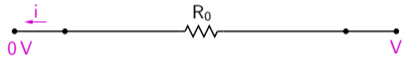
(a) $V_{break} = \frac{R}{R'} (V_0 + V_{on}) + V_{on}$. (b) When D is on, $V = (R_0 \parallel R) i + (\text{constant})$.

- * V_{break} depends on the ratio R/R' .
- * The slope $R_0 \parallel R$ depends on the resistance values.
- * Given the break point and the two slopes, the resistance values can be easily determined.

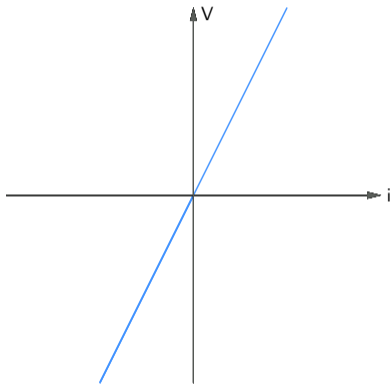
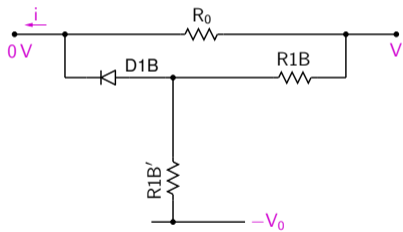
Wave shaping with diodes



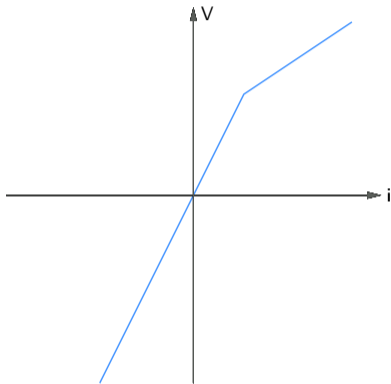
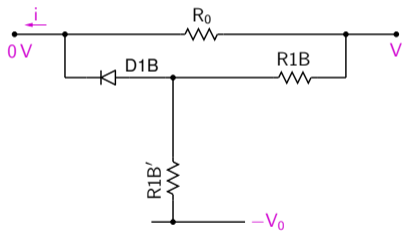
Wave shaping with diodes



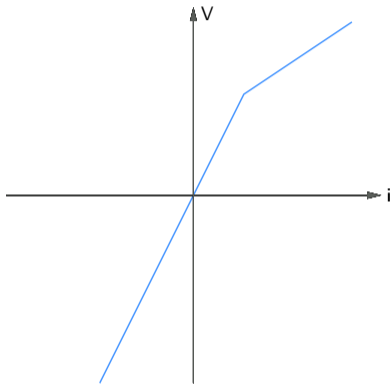
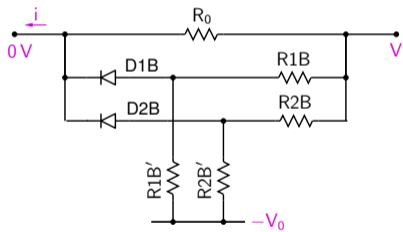
Wave shaping with diodes



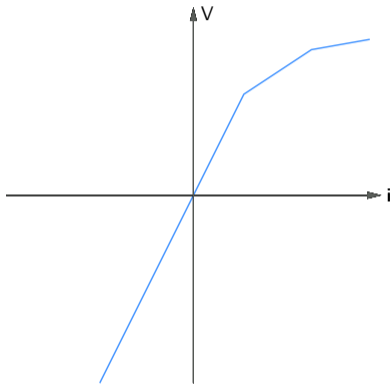
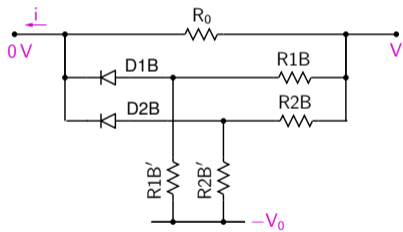
Wave shaping with diodes



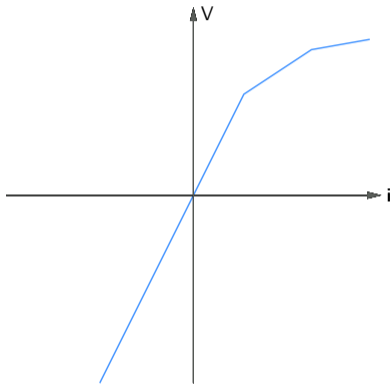
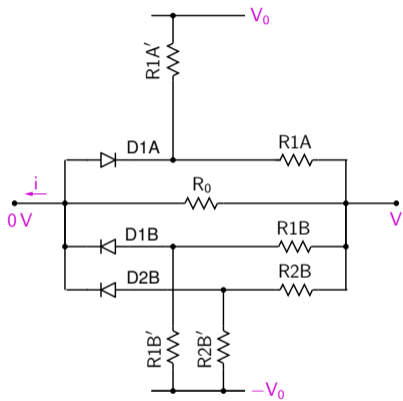
Wave shaping with diodes



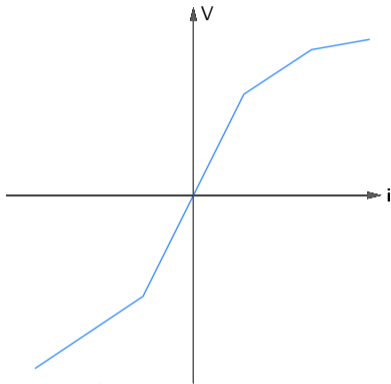
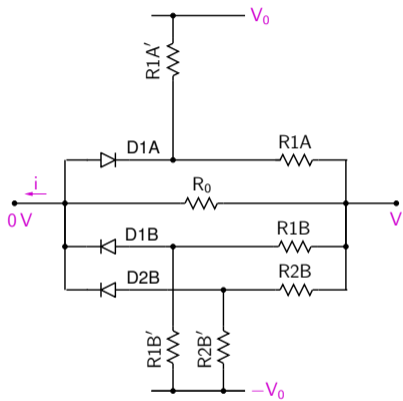
Wave shaping with diodes



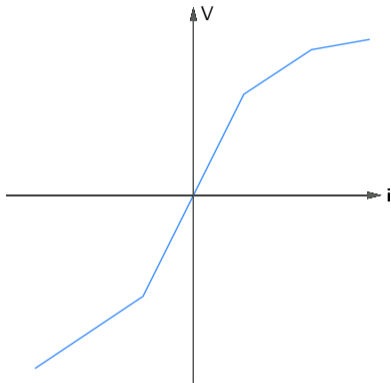
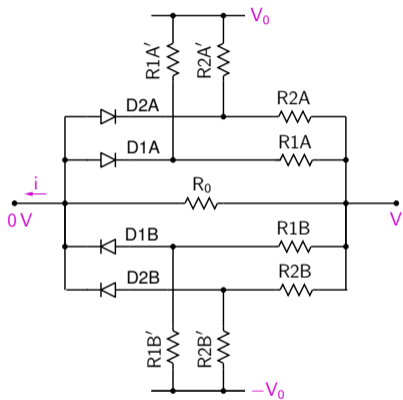
Wave shaping with diodes



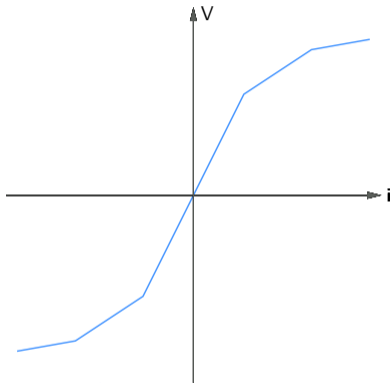
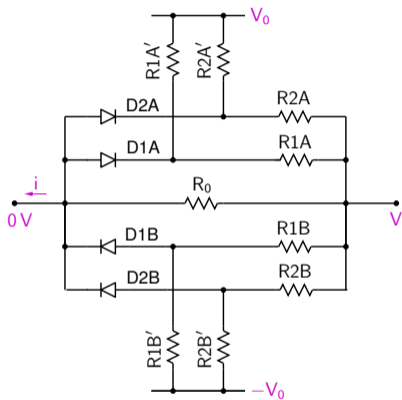
Wave shaping with diodes



Wave shaping with diodes

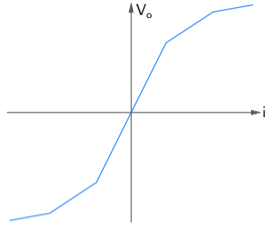
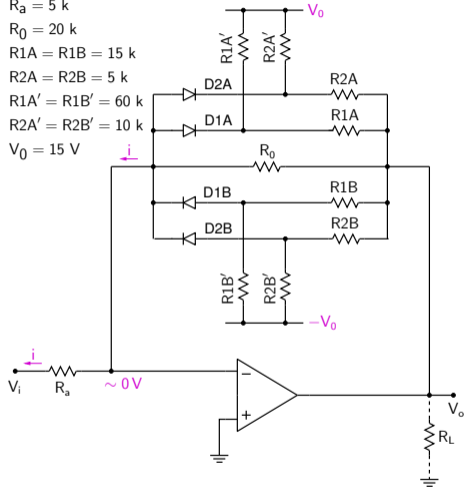


Wave shaping with diodes

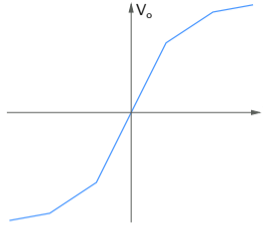
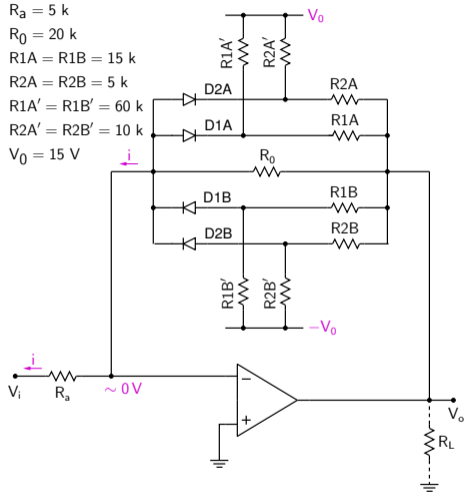


Wave shaping with diodes

$R_a = 5 \text{ k}$
 $R_0 = 20 \text{ k}$
 $R_{1A} = R_{1B} = 15 \text{ k}$
 $R_{2A} = R_{2B} = 5 \text{ k}$
 $R_{1A'} = R_{1B'} = 60 \text{ k}$
 $R_{2A'} = R_{2B'} = 10 \text{ k}$
 $V_0 = 15 \text{ V}$



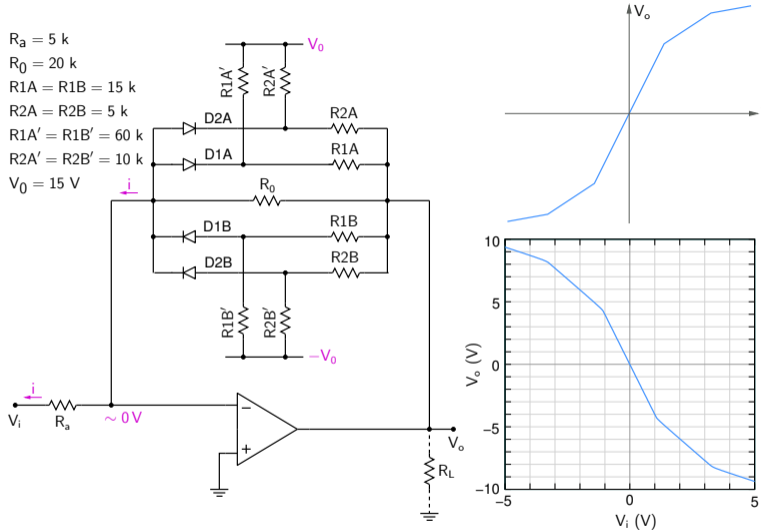
Wave shaping with diodes



Since $V_i = -R_a i$, the V_o versus V_i plot is similar to the V versus i plot, except for the $(-R_a)$ factor.

Wave shaping with diodes

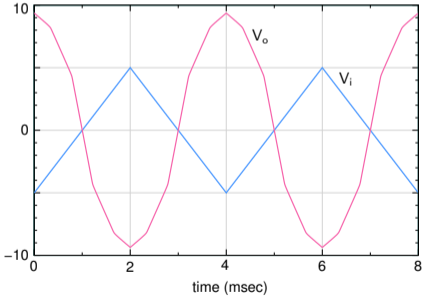
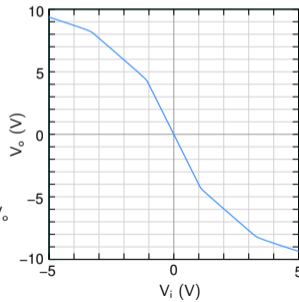
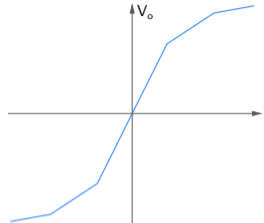
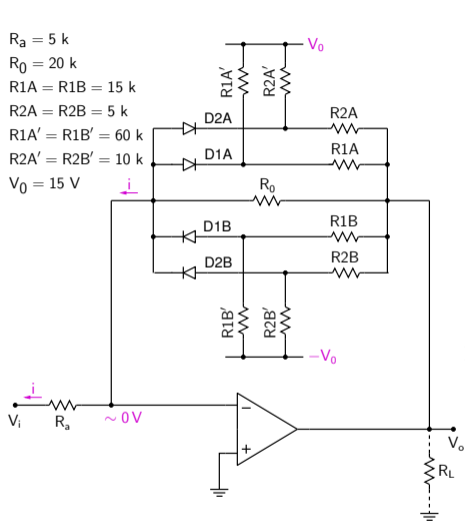
- $R_a = 5 \text{ k}$
- $R_0 = 20 \text{ k}$
- $R_{1A} = R_{1B} = 15 \text{ k}$
- $R_{2A} = R_{2B} = 5 \text{ k}$
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- $R_{2A'} = R_{2B'} = 10 \text{ k}$
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Wave shaping with diodes

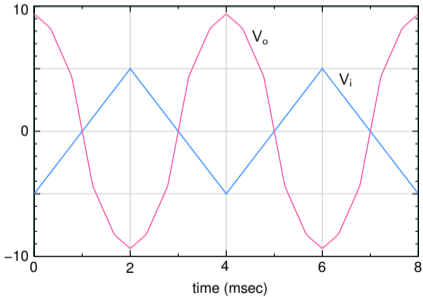
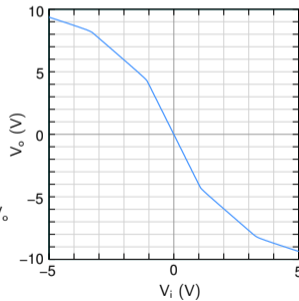
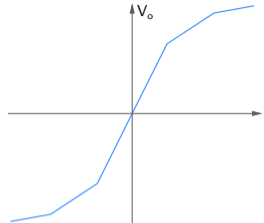
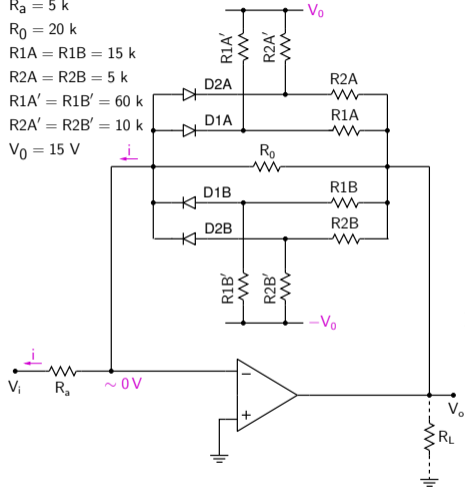
$R_a = 5 \text{ k}$
 $R_0 = 20 \text{ k}$
 $R_{1A} = R_{1B} = 15 \text{ k}$
 $R_{2A} = R_{2B} = 5 \text{ k}$
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Wave shaping with diodes

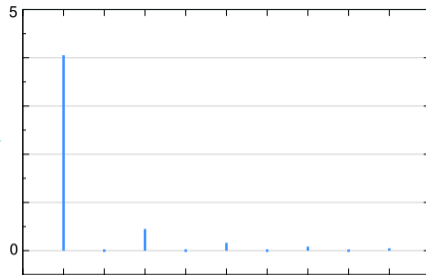
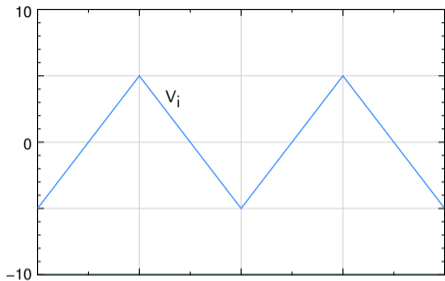
$R_a = 5 \text{ k}$
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Since $V_i = -R_a i$, the V_o versus V_i plot is similar to the V versus i plot, except for the $(-R_a)$ factor.

SEQUEL file: ee101_wave_shaper.sqproj

Wave shaping with diodes: spectrum



Wave shaping with diodes: spectrum

