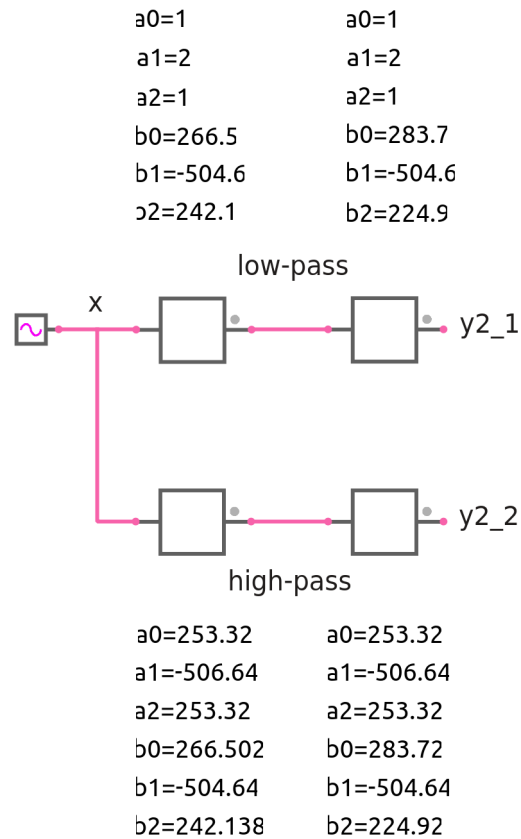


# butterworth\_4\_digital\_ac.sqproj



Shown in the figure are 4<sup>th</sup>-order low-pass and 4<sup>th</sup>-order high-pass digital Butterworth filters. Starting with the analog normalised filter function, the  $z$ -domain digital filter function can be obtained as follows.

- (a) Substitute  $s \leftarrow s/\omega_c$  where  $\omega_c$  is the desired cut-off frequency in rad/sec.
- (b) Use the bilinear transformation,

$$s \leftarrow \frac{2}{T_d} \left( \frac{1 - z^{-1}}{1 + z^{-1}} \right), \tag{1}$$

where  $T_d$  is the sampling interval.

- (c) Rewrite  $H(z)$  in standard form.

The filters shown in the figure are designed for a cut-off frequency of 200 Hz.

## Exercise Set

1. Work out the filter coefficients, and check the values against those shown in the figure.
2. Run the simulation. Plot the outputs  $y_{2\_1}$ ,  $y_{2\_2}$  versus frequency (log-log plot), and verify the low-pass and high-pass functionality.
3. From the plots, verify that they are 4<sup>th</sup>-order filters, and that the cut-off frequency is 200 Hz.

## References

1. A.V. Oppenheim, R.W. Schaffer, and J.R. Buck, *Discrete-time Signal Processing*, Pearson/Prentice-Hall, 1999.